

Buck inductor design

---Prepared by Bean

1. Calculate inductance:

1). Determine Duty cycle

$$D := \frac{V_o}{V_{in}}$$

2). Calculate inductance

Analysing the circuit, we can get the followed equations easily.

a). Continued mode

$$L := (V_{in} - V_o) \cdot \frac{D}{2Kf \cdot f \cdot I_o} \quad \text{or} \quad L := V_o \cdot \frac{(1 - D)}{2Kf \cdot f \cdot I_o}$$

Where: V_{in} is input voltage (V) V_o is output voltage (V)
 f is operation frequency (Hz) I_o is output current (A)
 K_f is the ripple factor (0.1~0.2 for typical application)

b). Discontinued mode

$$L := (V_{in} - V_o) \cdot \frac{D}{f \cdot I_{pk}} \quad \text{or} \quad L := V_o \cdot \frac{(1 - D)}{f \cdot I_{pk}}$$

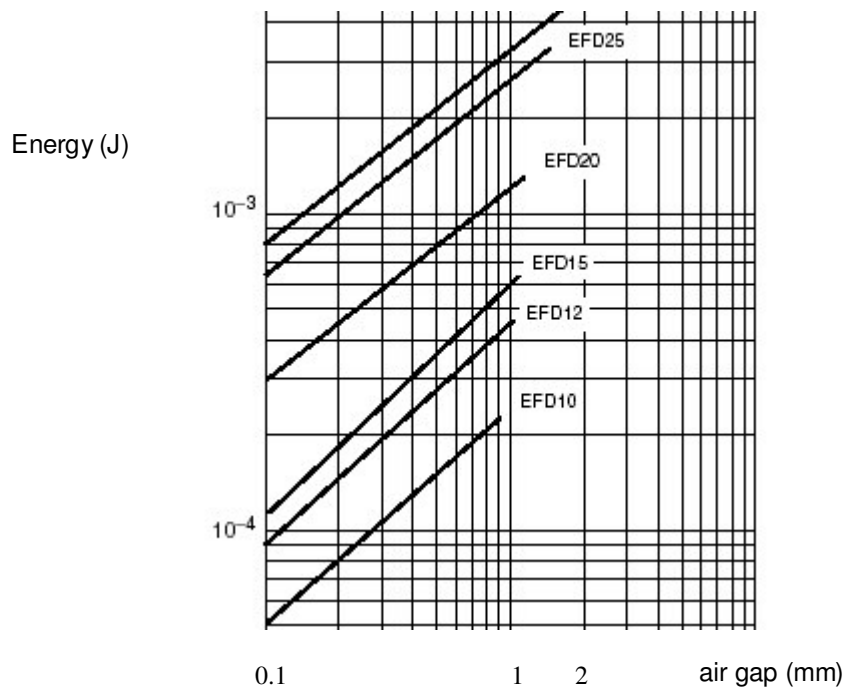
Note: The diode need to be considered on some cases especially for low output voltage application.

2. Choose core (Ferrite core design)

1). Calculate the energy storage

$$W := L \cdot I^2$$

2). Choose the core and determine the gap based on energy vs air-gap curve



3. Calculate the number of turns:

From step 2, the core and gap length were determined. Now we can use related factors of core to calculate turns number.

$$N := [L \cdot (R_c + R_g)]^{0.5}$$

Where: L ---inductance in Henry
R_c---Magnetic resistance of core
R_g---Magnetic resistance of air gap

$$R_c := \frac{l_e}{\mu \cdot A_e} \quad R_g := \frac{l_g}{\mu_0 \cdot A_e}$$

Where: l_e---effective length of core in meter
A_e---cross area of core in square meter
l_g---gap length in meter
μ---permeability of core
μ₀---permeability of air

4. Determine wire size

a). Chinese method

$$\phi := 1.13 \cdot \sqrt{\frac{I}{J}}$$

Where: φ---diameter of wire in mm
J---current density (7~16 for typical application)

b). American method

$$CM := J \cdot I$$

Where: CM---Area in circular mils
J---current density (100~250 for typical application)

Then go to wire table to find right wire.

5. Verify the design

Normally, the inductor has two limitations: one is the temperature rise, the other one is saturation of core. So need to verify if these two factors can meet requirement.

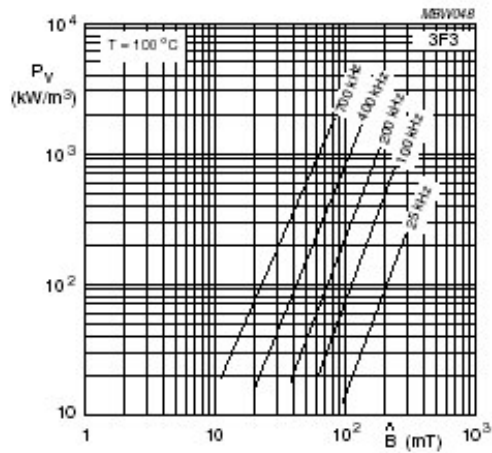
1). Verify if the core saturation

$$\Delta B := \Delta I \cdot \frac{L \cdot 10^{-2}}{N \cdot A_e}$$

Where: ΔB is the flux swing in Tesla
ΔI is the peak to peak current
L is inductance in μH
N is number of turns
A_e is core cross area in cm²

The flux swing divided by 2, then go to the core loss curve and find the core loss.
If the core loss higher than 100mW/cm³, the core is saturation.

*This rule come from Lloyd's technical paper. Actually, if you choose the core and gap based on this method, the core don't want to saturate.



2). Temperature rise

a). copper loss

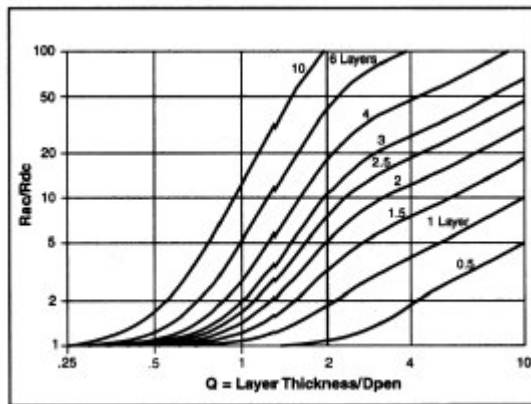
$$P_{\text{copper}} := I_{\text{dc}}^2 \cdot R_{\text{dc}} + I_{\text{ac}}^2 \cdot R_{\text{ac}}$$

Where: I_{dc} is DC current

R_{dc} is direct current resistance

I_{ac} is effective value of AC current

R_{ac} is AC resistance can got from Dewll's curve



b). core loss Pcore

The core loss can be gotten based on section 5.1. Normally, the core loss isn't a significant effect for ferrite design in continued mode.

c) Temperature

$$\Delta\tau := \sqrt[0.833]{\frac{P_t}{A_s}}$$

Where: P_t is the total loss in mW

A_s is the surface area in cm^2

Note: This method just for reference, the best way is to build a sample to test.

Up to now, a method to design a ferrite inductor was given. Actually, most buck inductors are designed with a powder material and toroid core. Now show a step by step design with powder core.

Ferrite: 1. large fringing
2. high ac loss
3. EMI problem

Powder: 1. high core loss
2. high saturation flux density
3. soft bias performance

Buck: Input voltage: 5V
Output voltage: 1.25V
Output current: 6.5A
Frequency: 1MHz

$$V_{in} := 5 \quad V_o := 1.25 \quad I_o := 6.5 \quad f := 1000000$$

1. Calculate duty cycle and inductance (Normally, the buck inductor is designed to continued mode

$$D := \frac{V_o}{V_{in}} \quad D = 0.25 \quad K_f := 0.1$$

$$L_{min} := (V_{in} - V_o) \cdot \frac{D \cdot 10^6}{2 \cdot K_f \cdot f \cdot I_o} \quad L_{min} = 0.721 \quad \text{or}$$

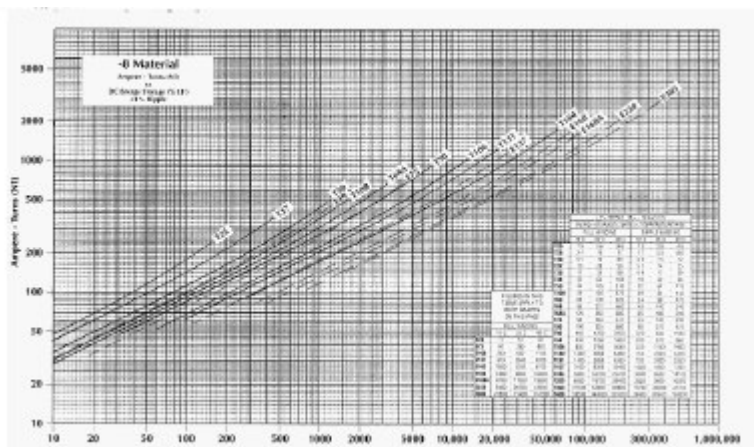
$$L_{min} := (V_o + 0.085 \cdot I_o) \cdot \frac{(1 - D) \cdot 10^6}{2 \cdot K_f \cdot f \cdot I_o} \quad L_{min} = 1.04$$

*This use a IC with a switcher instead of Diode. The resistance of swither is 85mOHM

2. Choose the core and material: chosse -8 material for frequency requirement.

$$W := 0.5 L_{min} \cdot I_o^2 \quad W = 21.968$$

Go to core selection cure and chart:



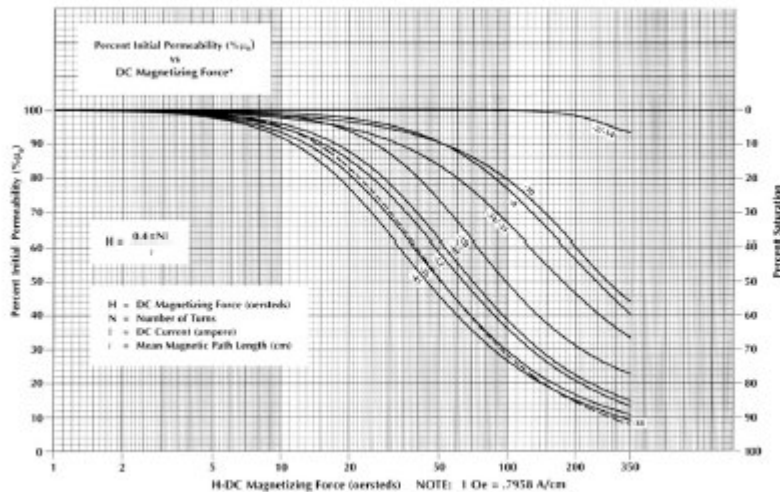
Found that T30 will yield such energy with single winding. The ampere turns will be about 67. So the pri-turns will be 10.

$$A_e := 0.06 \quad l_e := 1.84 \quad N_p := 10 \quad AL := 14 \quad V_e := .11$$

3. Adjust turns

$$\text{Magnetizing force: } H := 0.4 \cdot \pi \cdot Np \cdot \frac{I_o}{l_e} \quad H = 44.392$$

Then go to $\mu\%$ vs H cure and find the $\mu\%$ is 93.5%.



$$N := \left(L_{min} \cdot \frac{10^3}{A \cdot L \cdot 0.935} \right)^{0.5} \quad N = 8.913 \quad N := 9$$

Actually, the inductance will be about 1.06uH at 9 turns.

4. determine wire size

$$\text{Assume: } J := 13$$

$$\phi := 1.13 \cdot \sqrt{\frac{I_o}{J}} \quad \phi = 0.799$$

This will be AWG20, but the winding space is not enough. So change to AWG21.

The design goes to:

$$N := 9 \quad \text{AWG21}$$

5. Verify the temperature rise

$$T_{30}: \quad MLT := 1.44 \quad A_s := 2.79$$

$$\text{AWG21} \quad \Omega := 12.77 \quad \frac{\Omega}{1000\text{ft}}$$

$$DCR := MLT \cdot \frac{N}{2.54 \cdot 12} \cdot \Omega \quad DCR = 5.43 \quad \text{m}\Omega$$

$$P_{cu} := I_o^2 \cdot DCR \quad P_{cu} = 229.408$$

Because the inductor was designed in continued mode, the AC resistance can be ignored.

Use maximum voltage cross coil to calculate core loss. Here:

$$V_{pk} := V_{in} - V_o$$

$$\Delta B := V_{pk} \cdot \frac{D \cdot 10^8}{2 \cdot A_e \cdot N \cdot f} \quad \Delta B = 86.806 \text{ G}$$

For -8 material: the relationship between loss and AC flux & frequency can be gotten from core catalog.

$$P := \frac{f}{\left(\frac{1.9 \cdot 10^9}{\Delta B^3} \right) + \frac{2 \cdot 10^8}{\Delta B^{2.3}} + \frac{9 \cdot 10^5}{\Delta B^{1.65}}} + 2.5 \cdot 10^{-14} \cdot \Delta B^2 \cdot f^2 \quad P = 284.252$$

$$P_{core} := P \cdot V_e \quad P_{core} = 31.268$$

$$P_t := P_{cu} + P_{core} \quad P_t = 260.675$$

$$\Delta \tau := \left(\frac{P_t}{A_s} \right)^{0.833}$$

$$\Delta \tau = 43.795$$

References:

- [1] Lloyd H. Dixon: Unitrode Magnetics Design Handbook
- [2] Micrometals Catalog, 2000
- [3] Ferroxcube Catalog, 2002

- End -