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MASTERs 2007

11011 EXP

Advanced 16 bit Peripheral Configuration and MPLAB® C30 Programming Techniques

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Class Objective

- **When you finish this class you will:**
  - Be familiar with using some of the advanced peripherals onboard Microchip's 16-bit devices
  - Be familiar with using MPLAB® IDE with the C30 compiler
  - Be familiar with using the Explorer16 Development Board

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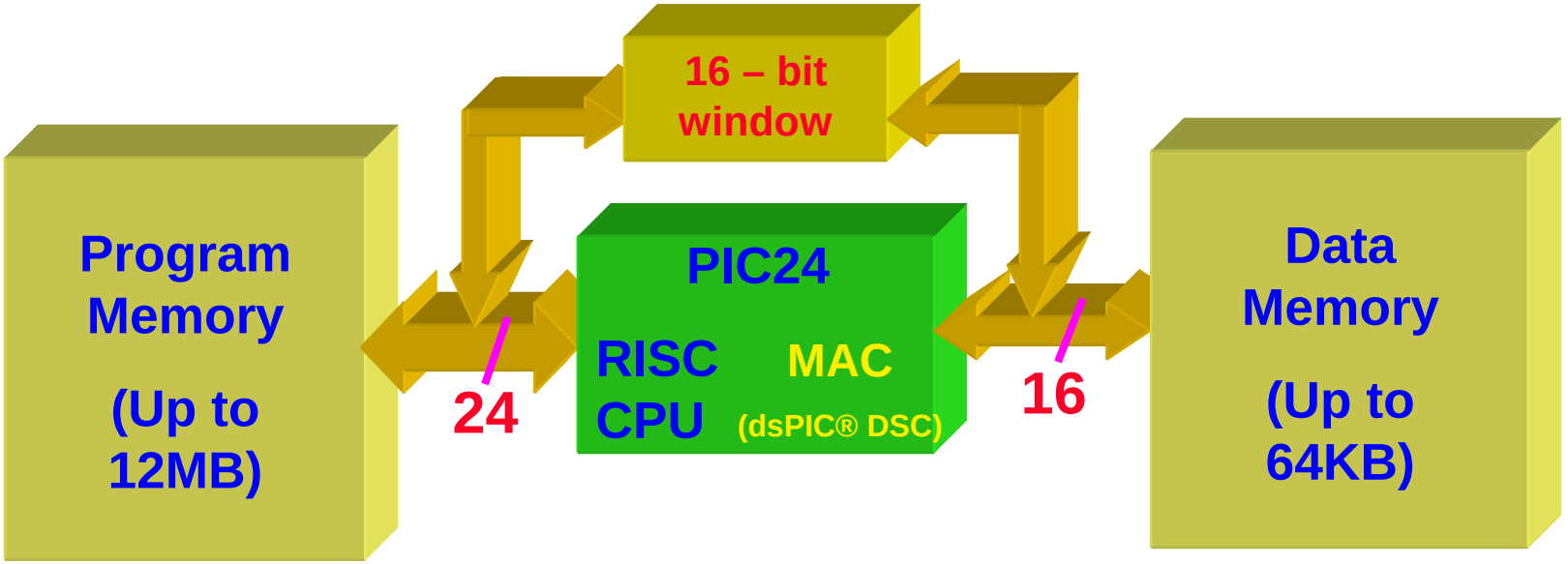
Agenda

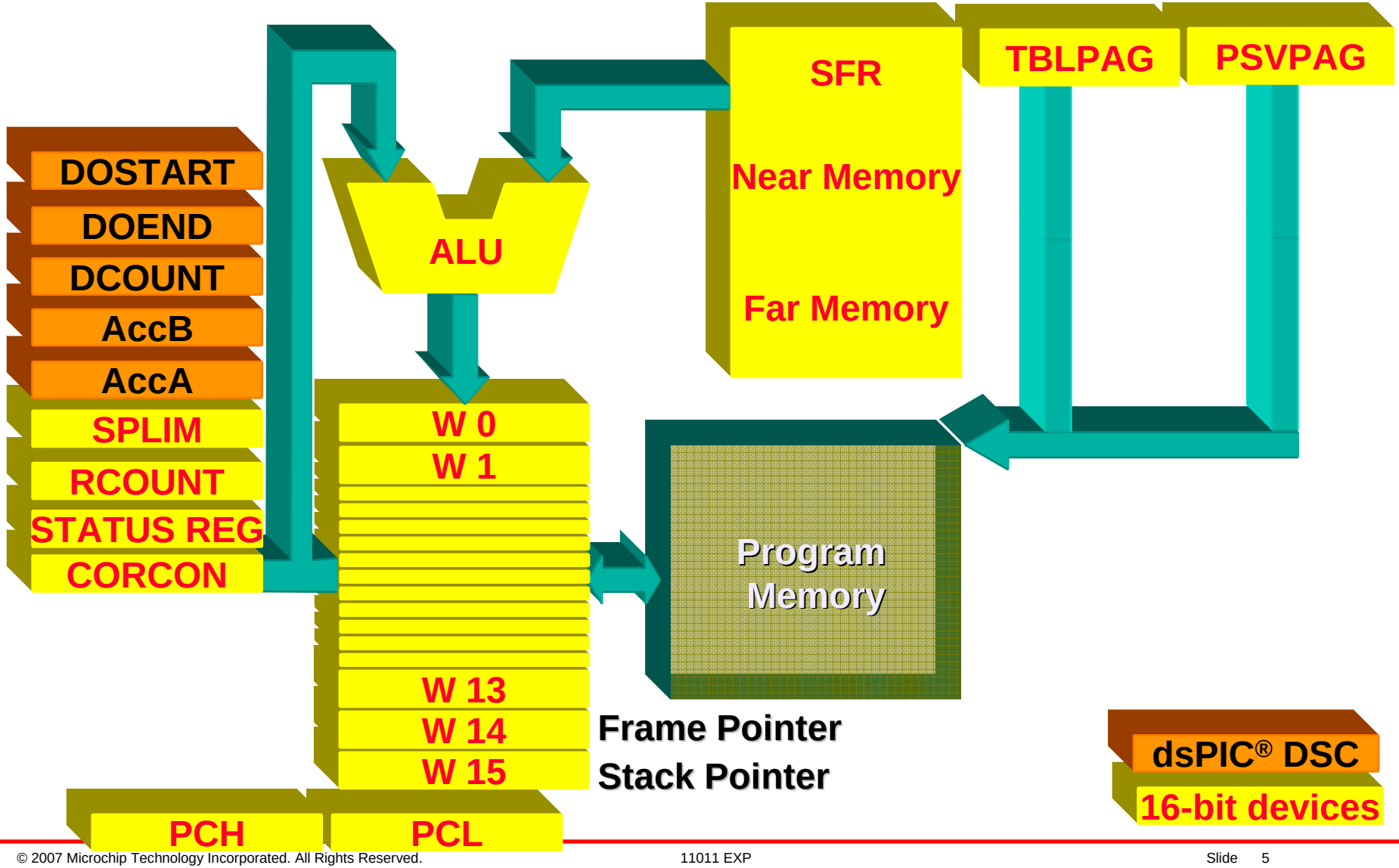
- **16-bit Devices**
  - 16-bit Refresher
    - **CPU architecture**
  - New Peripherals and Features
    - **PPS with hands-on**
    - **PMP with hands-on**
    - **RTCC with hands-on**
    - **CRC Generator with hands-on**
    - **DMA with hands-on**

Harvard Architecture

- 16-bit microcontroller
- 24-bit Instruction width
- Data Transfer Mechanism between PM and DM

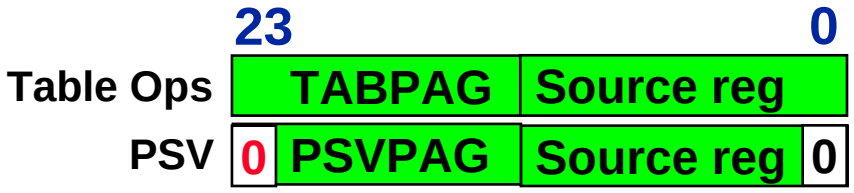


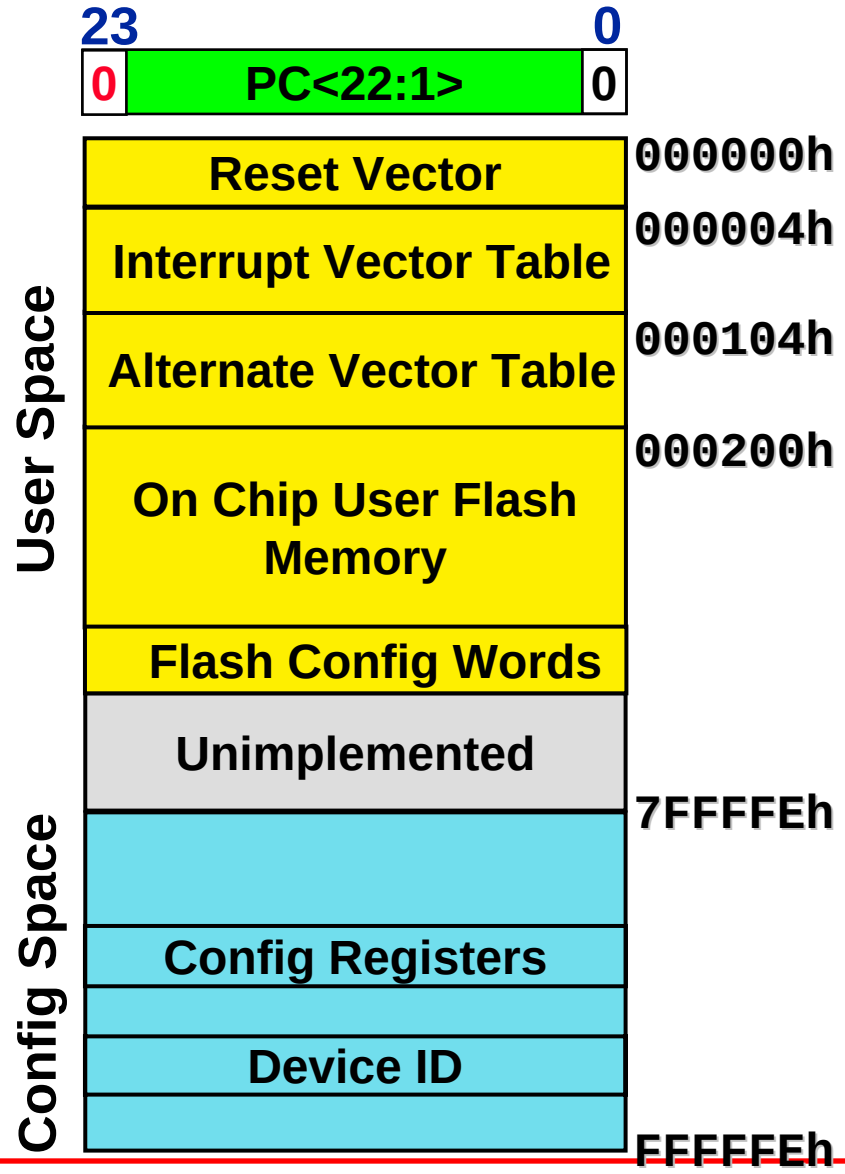
16-bit Architecture
Programmers model



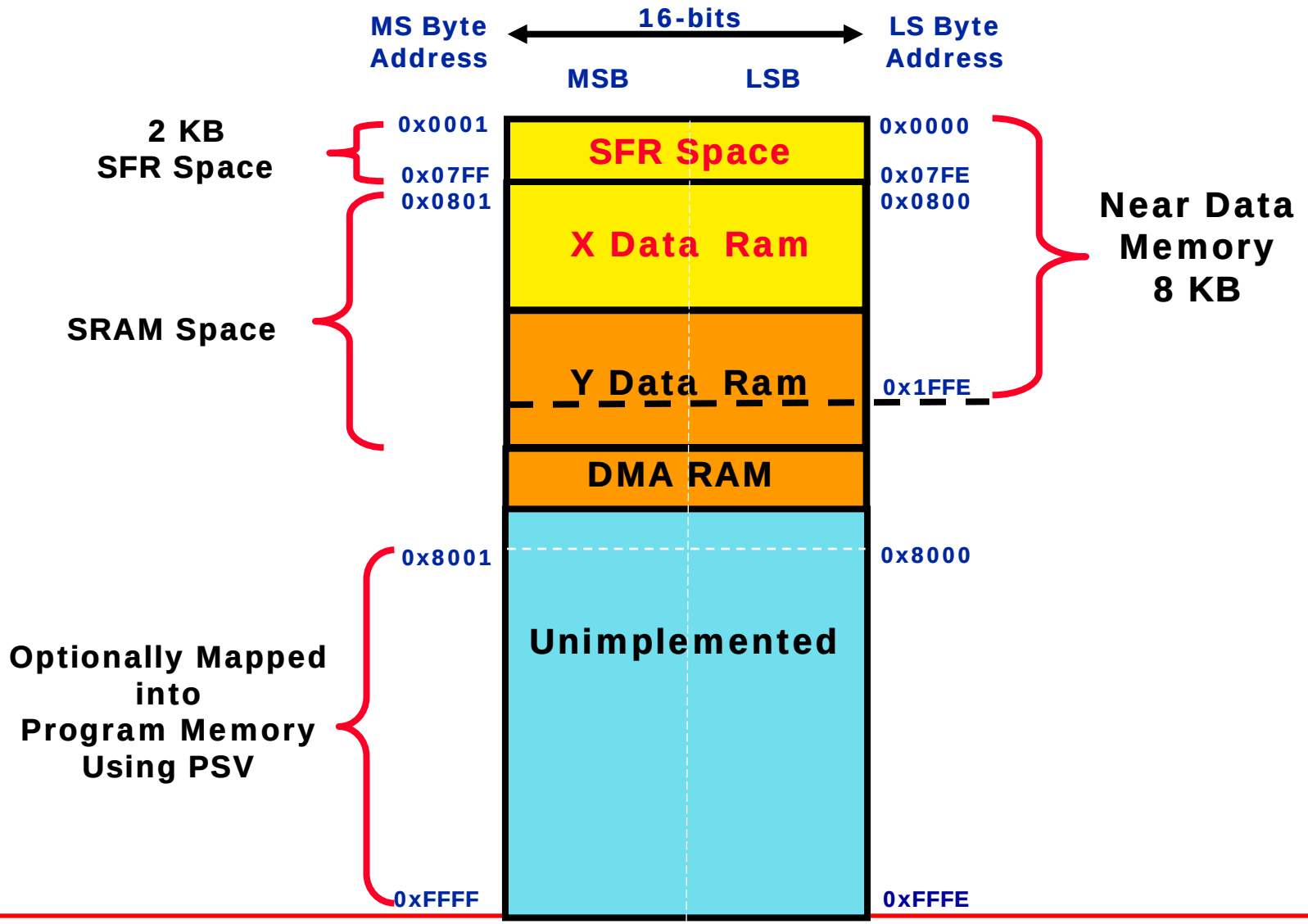
Program Memory

- Maximum 12MB
  - 4MB x 24-bit
  - 23-bit PC (PCH & PCL)
- PC increments in words (LSB always '0')
- Reset Vector at 0
- Interrupt Vector Table from 4h to FEh
- User Code space from 200h to 7FFFFEh (what ever is implemented)





Data Memory Organization



Peripheral Pin Select (PPS)

Peripheral Pin Select

- **What it is…**
  - Pin multiplexing that allows user to select the pin out of digital functions
  - Allows optimal usage of on-board peripherals
  - Allows Pin Redefinition via software
- **What it is not …**
  - Not a method to achieve pin compatibility
  - Analog and special pad pins (e.g., PMP & I^2C™) are still fixed

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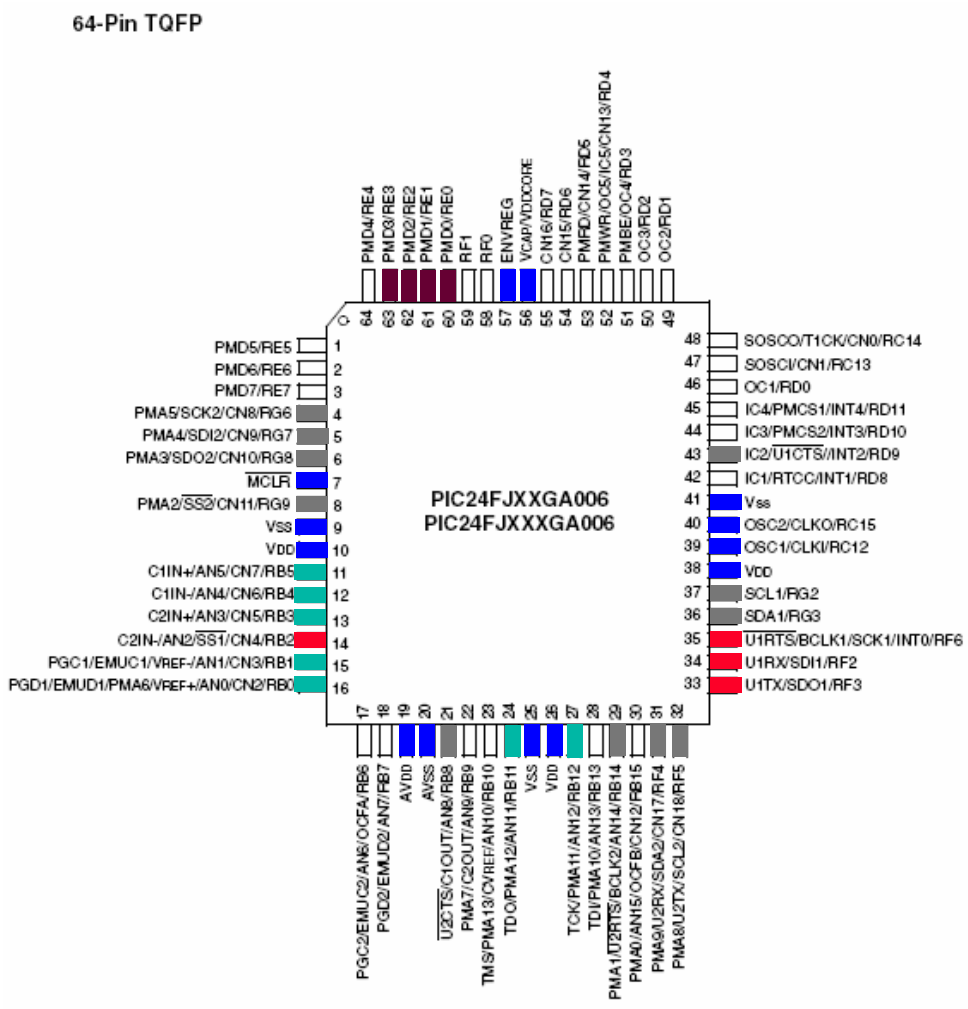
Application Example

- **Memory**
  - 64K Flash
  - 8K RAM
- **Analog**
  - 2 ch ADC
  - Vref +&-
  - Comparator x 2
- **Digital I/O**
  - 4 I/O
- **Serial Channels**
  - I^2C™
  - SPI x 2
  - UART x 2

Easy...

Right?

Application Example



- **Application**
  - 64 KB Flash, 8 KB RAM
  - 2 ch A/D, Ext. VREF
  - 2 Comparators
  - UART x 2, I²C™, SPI x 2
  - 4 Digital I/O
- **Pin multiplexing blocks functions**
  - UART1 and SPI1
  - Comparator2 and SPI1
- **25 spare pins**
  - Must use even larger pin count device
  - Or write SPI in software

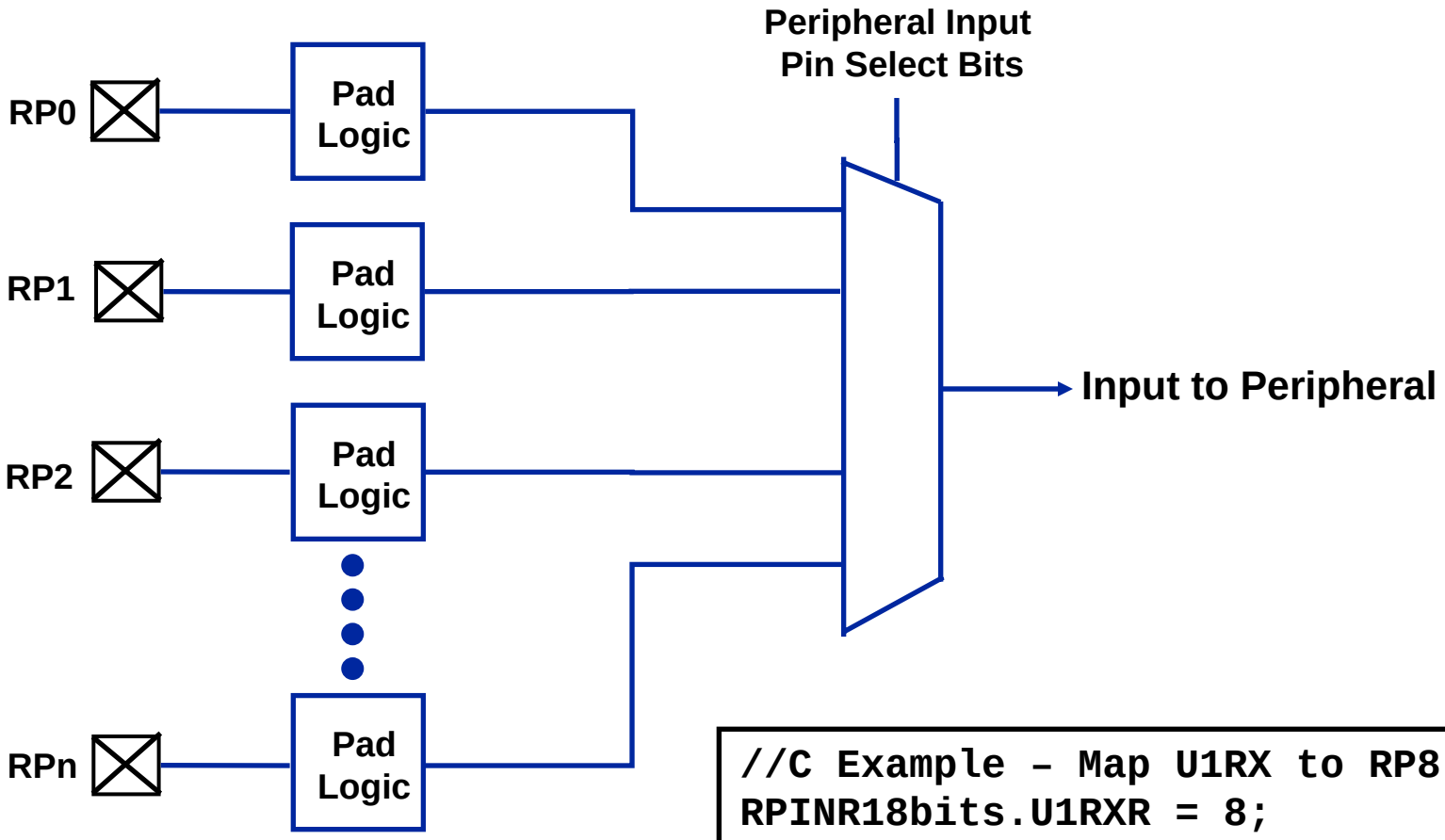
Remappable Functions 16-bit MCU and dsPIC® DSC

- All SPI & UART Functions
- Timer & External Interrupt Inputs
- Input Capture & Output Compares
- Analog Comparator outputs
- PWM Fault Input pins
- Quadrature Encoder Interface Inputs
- Data Converter Interface
- CAN

PPS Implementation Details

- **Any function can remap to any RP pin**
  - Multiple functions on one pin is supported
- **Inputs vs. Outputs**
  - Inputs assign a pin to a specific peripheral
  - Outputs assign a peripheral to a specific pin
- **Pinout is set in software**
  - Allows on-the-fly configuration or one-shot configuration

Remappable Inputs




```
//C Example – Map U1RX to RP8
RPINR18bits.U1RXR = 8;
```

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Remappable Inputs

REGISTER 9-9: RPINR18: PERIPHERAL PIN SELECT INPUT REGISTER 18

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	U1CTSR4	U1CTSR3	U1CTSR2	U1CTSR1	U1CTSR0
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	U1RXR4	U1RXR3	U1RXR2	U1RXR1	U1RXR0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

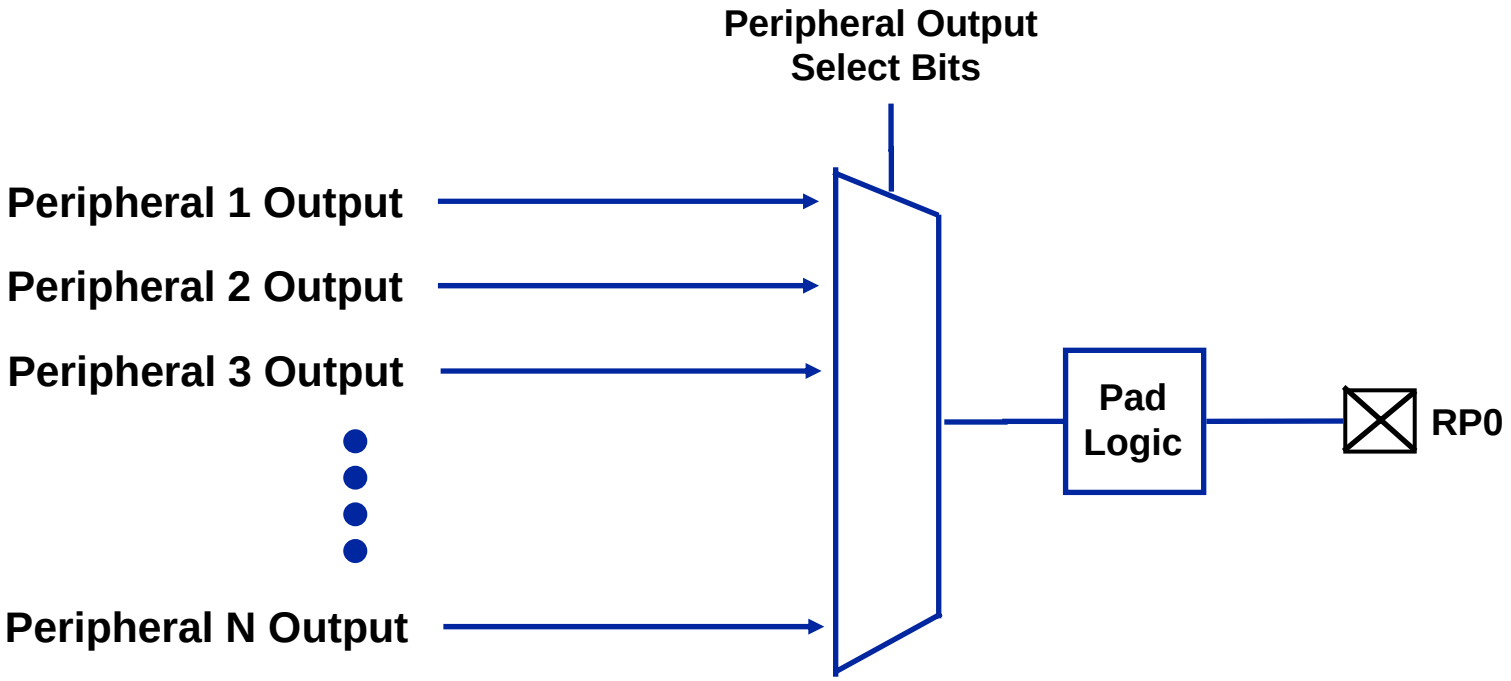
bit 12-8 **U1CTSR4:U1CTSR0:** Assign UART1 Clear to Send (U1CTS) to the Corresponding RPn Pin bits

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **U1RXR4:U1RXR0:** Assign UART1 Receive (U1RX) to the Corresponding RPn Pin bits

Define the location of each function used by modifying xxxxR bits in RPINRn registers

Remappable Outputs




```
//C Example – Map U1TX to RP1
RPOR0bits.RP1R = 3
```

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Remappable Outputs

Function	Output Function Number(1)	Output Name
NULL(2)	0	NULL
C1OUT	1	Comparator 1 Output
C2OUT	2	Comparator 2 Output
U1TX	3	UART1 Transmit
$\overline{\text{U1RTS}}$(3)	4	UART1 Request To Send
U2TX	5	UART2 Transmit
$\overline{\text{U2RTS}}$(3)	6	UART2 Request To Send
SDO1	7	SPI1 Data Output
SCK1OUT	8	SPI1 Clock Output
SS1OUT	9	SPI1 Slave Select Output
SDO2	10	SPI2 Data Output
SCK2OUT	11	SPI2 Clock Output
SS2OUT	12	SPI2 Slave Select Output
OC1	18	Output Compare 1
OC2	19	Output Compare 2
OC3	20	Output Compare 3
OC4	21	Output Compare 4
OC5	22	Output Compare 5

Remappable Outputs

REGISTER 9-17: RPOR2: PERIPHERAL PIN SELECT OUTPUT REGISTER 2

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP5R4	RP5R3	RP5R2	RP5R1	RP5R0
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP4R4	RP4R3	RP4R2	RP4R1	RP4R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

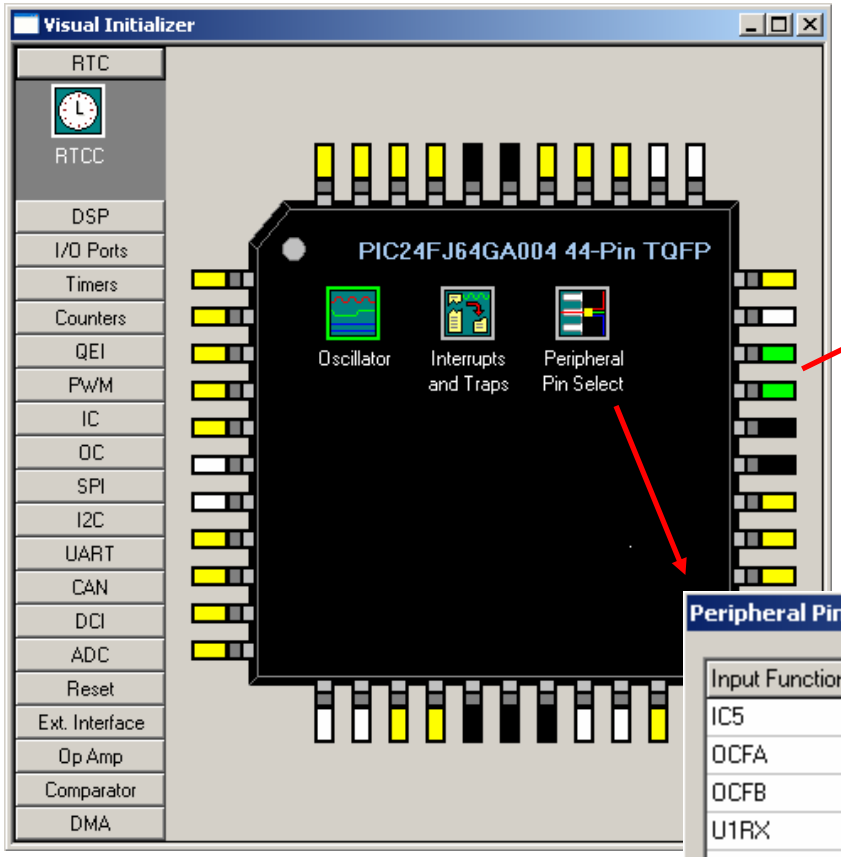
bit 12-8 **RP5R4:RP5R0:** Peripheral Output Function is Assigned to RP5 Output Pin bits (see Table 9-2 for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as '0'

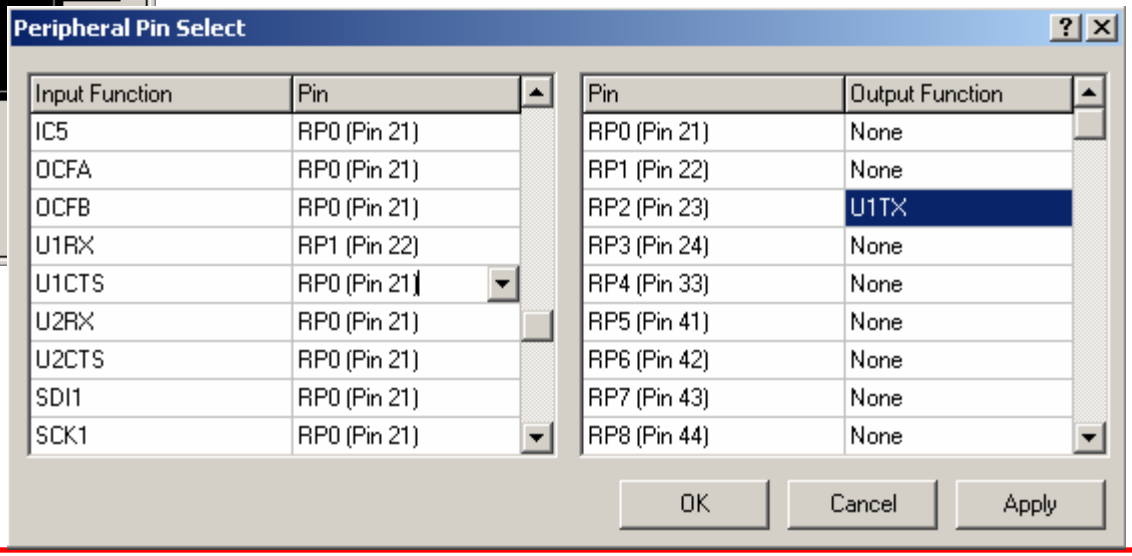
bit 4-0 **RP4R4:RP4R0:** Peripheral Output Function is Assigned to RP4 Output Pin bits (see Table 9-2 for peripheral function numbers)

Define the output functionality on each pin by modifying RPnR bits in RPORn registers

Remapping Pins with VDI



Color coding shows what pins are used and where conflicts may exist



PPS Register Protection

- **HW integrity checking**
  - Bit flip will cause device reset
- **I/O lock feature**
  - RPINRn/RPORn can only be written to while the IOLOCK bit in the OSCCON register = 0; once the IOLOCK is set, the registers cannot be written
- **IOLOCK Protection**
  - The state of the IOLOCK bit can only be changed with an unlocking sequence
  - Protection selectable by configuration bit

Pin Function Priority

- **Peripheral priorities:**

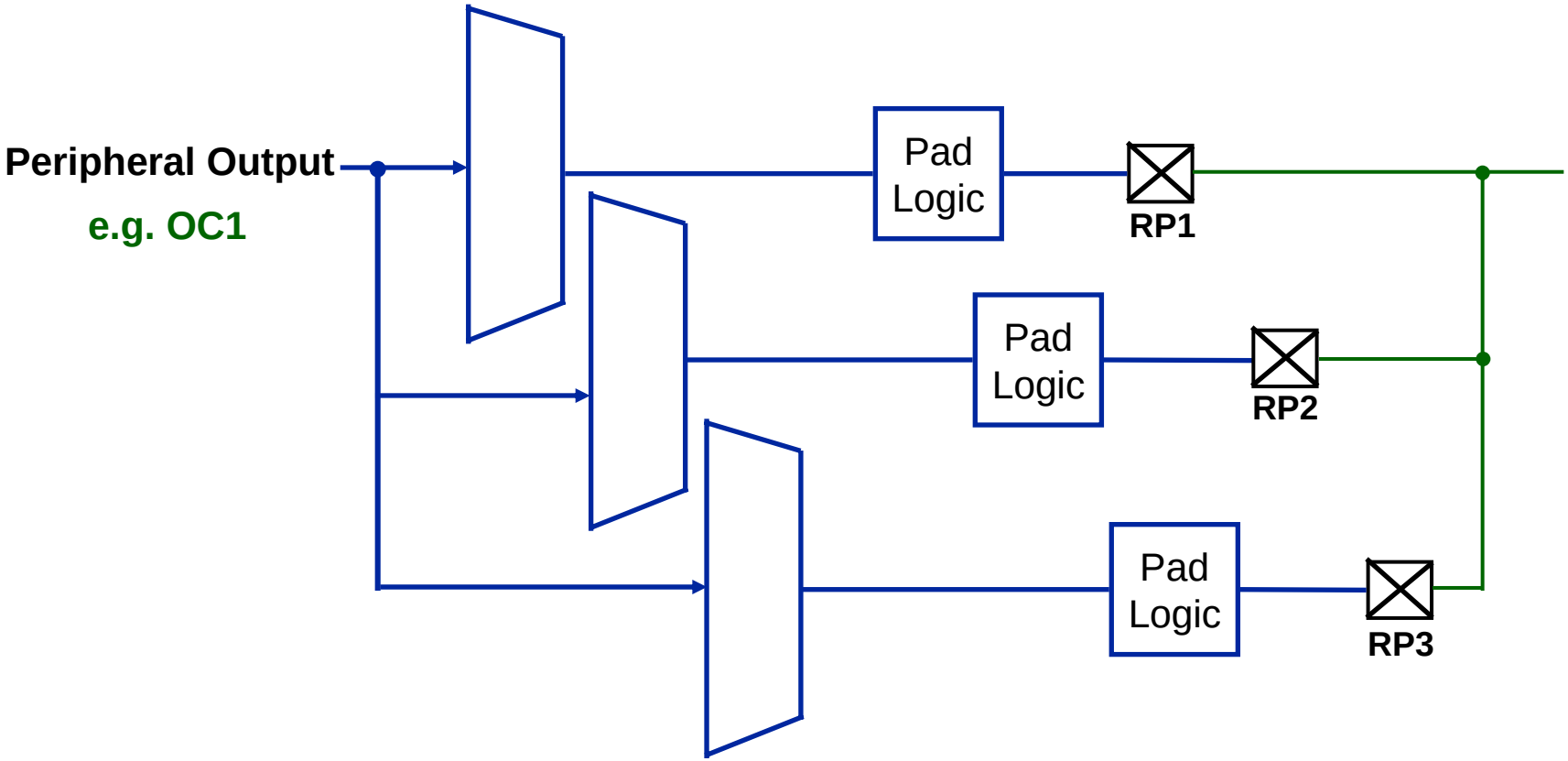
1.	**Analog Functions**	**ANx, Vref+/-**
2.	**PPS Outputs**	**UART TX, SDO, OC**
3.	**PPS Inputs**	**UART RX, SDI, IC**
4.	**Fixed Digital Peripheral Outputs**	**I^2C™, PMP**
5.	**Fixed Digital Peripheral Inputs**	**I^2C, PMP**

Initializing a PPS Application

1. **Design Decision: Static or Dynamic RPn assignment?**
   - Set **`IOL1WAY`** config bit accordingly
2. **Initialize the pinout by mapping the RPn pins to the desired peripheral input/output functions**
   - Map RPn pin(s)→Peripheral Input Function(s)
   - Map Peripheral Output Function(s)→RPn pin(s)
   - Lock the RPn SFRs using 'lock' sequence
3. **Configure Peripherals**
4. **Enable Interrupts (if required)**

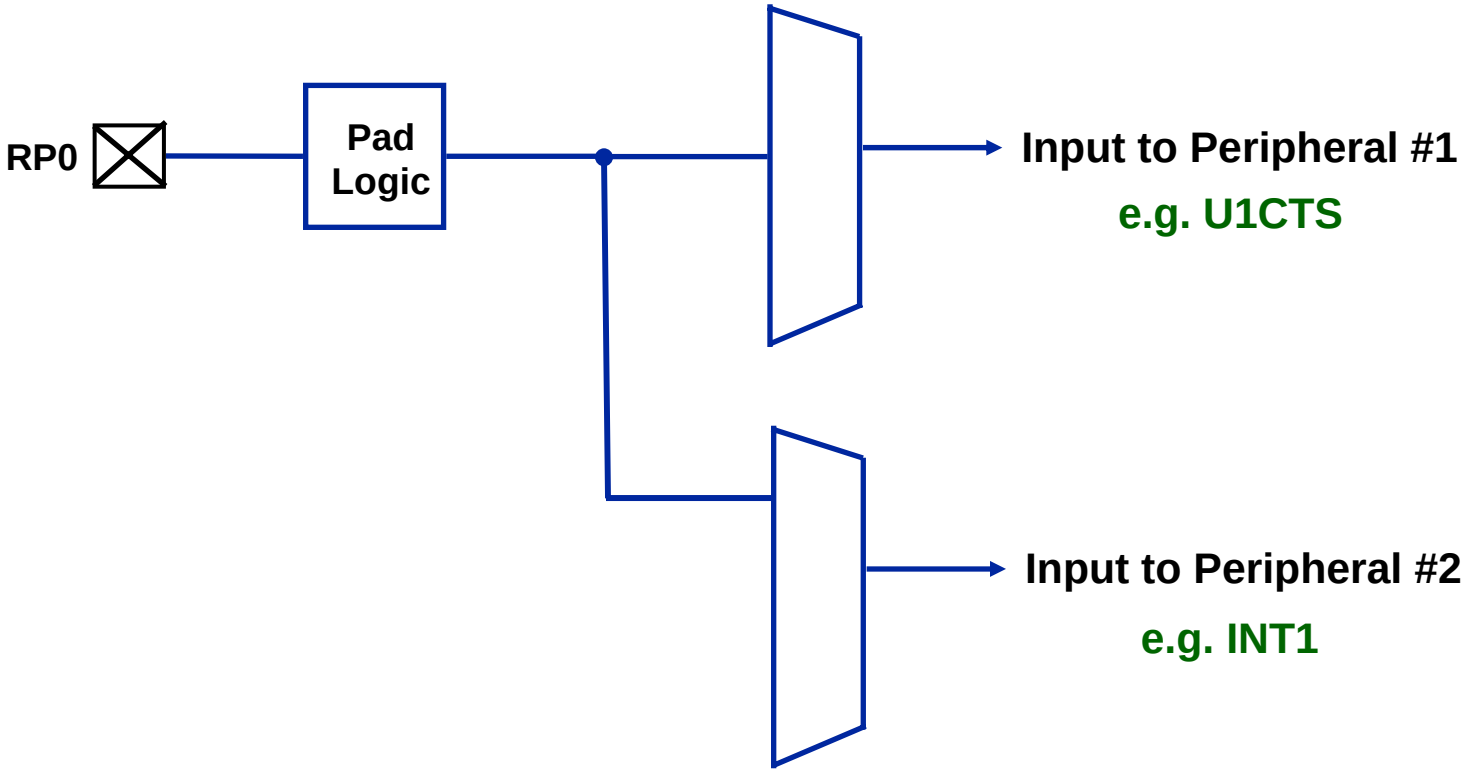
Cool Byproducts

- **Increase drive strength by outputting same peripheral on multiple pins**



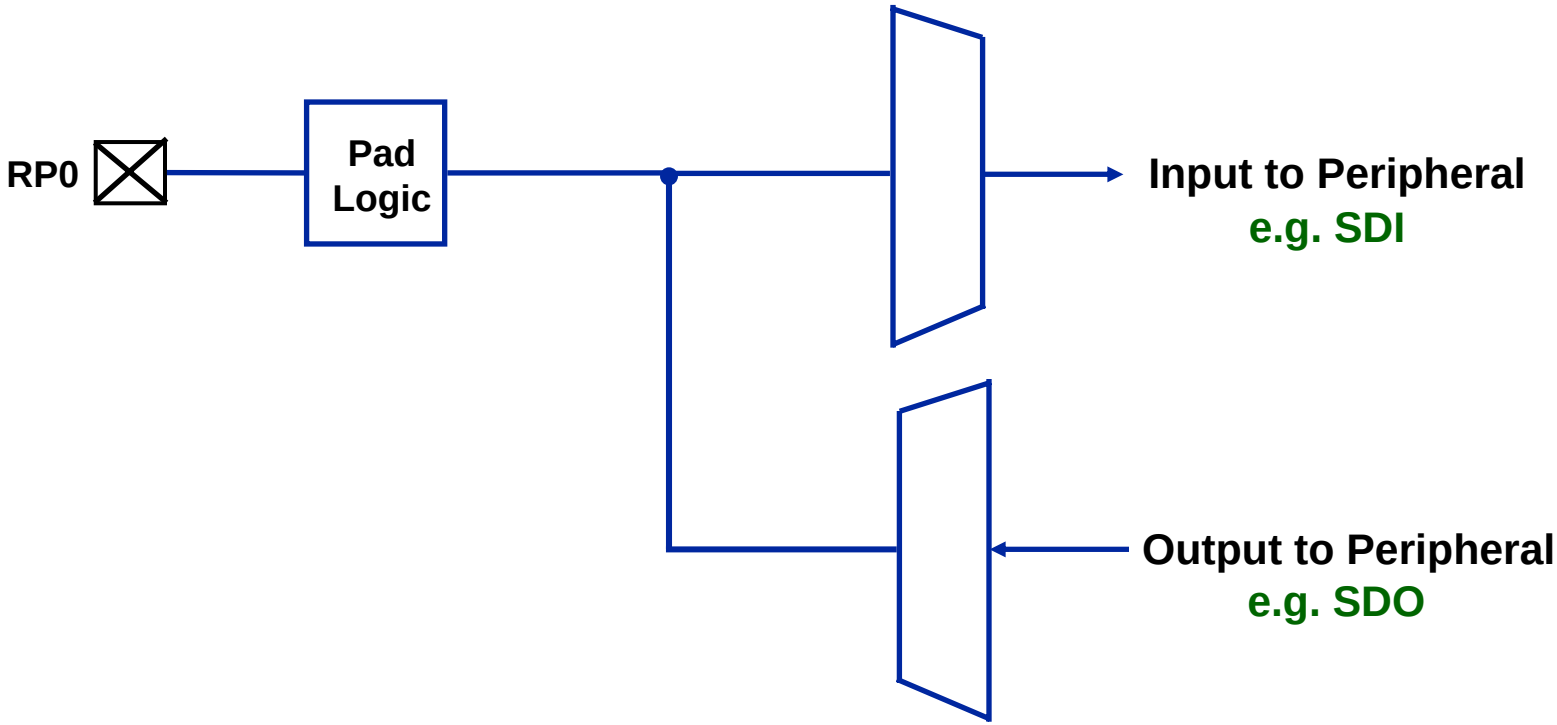
Cool Byproducts

- **Connect one signal to multiple peripheral inputs**



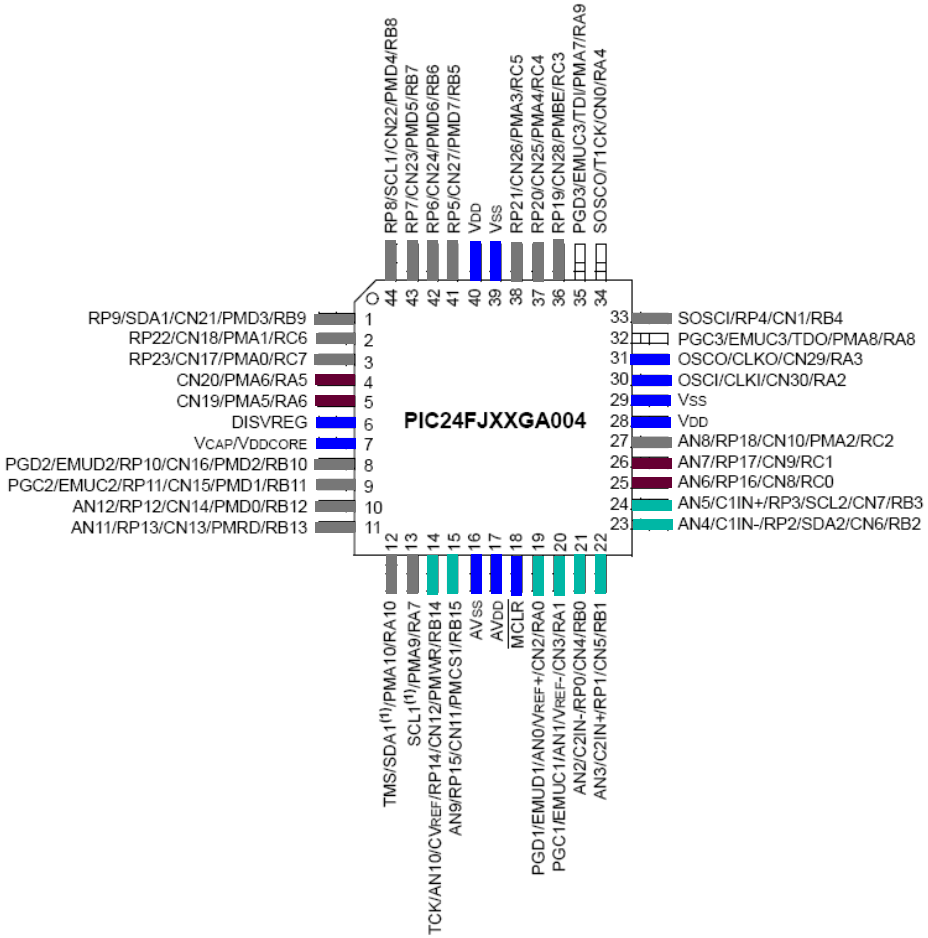
Cool Byproducts

- **Connect peripheral output to another input (Loopback) for debugging**



Application Example Revisited

44-Pin TQFP



- **Application**
  - 64 KB Flash, 8 KB RAM
    - 2 ch A/D, Ext. VREF
    - 2 Comparators
    - UART x 2, I²C™, SPI x 2
    - 4 Digital I/O
- **3 Spare Pins**

Smaller packages, simplified design and lower cost!

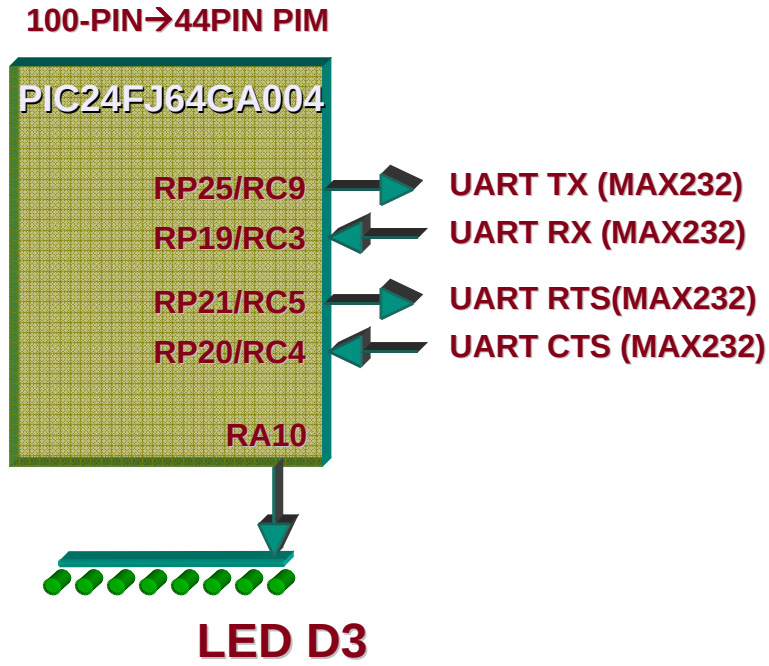
Let’s go Hands on

Lab 1
Peripheral Pin Select

Lab 1: PPS

- **Goal:**
  - Configure simple UART echo to HyperTerminal using PIC24FJ64GA004 on Explorer16

See "PIC24FJ64GA004 PIM Infosheet 51663a.pdf" to see how the 100-pin PIM socket maps to the 44-pin PIC24FJ64 device



Lab 1 – PIM Swap

- **Lab 1 uses the PIC24FJ64GA004 PIM**
- **To swap the processor:**
  - Disconnect Explorer 16 power and ICD2 connections
  - Remove PIC24FJ128GA010 PIM
  - Place PIC24FJ64GA004 PIM on board, making sure to properly align the notched corner
  - Reconnect Power and ICD2

Lab 1 – Required Mapping

- **Desired peripheral input functions:**
  - U2RX → RP19 Input Function
  - U2CTS → RP20 Input Function
- **Desired peripheral output functions**
  - RP25 → U2TX
  - RP21 → U2RTS
  - LED/Switch I/O:
    - **RA10→LED D3**

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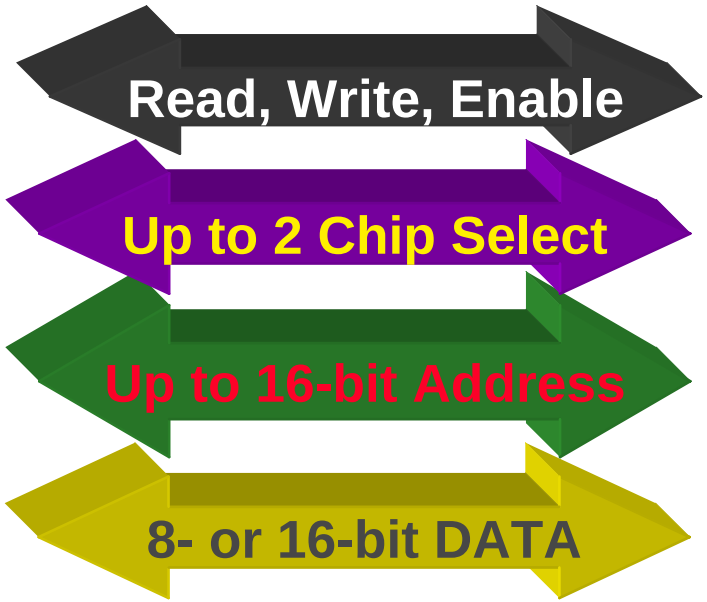
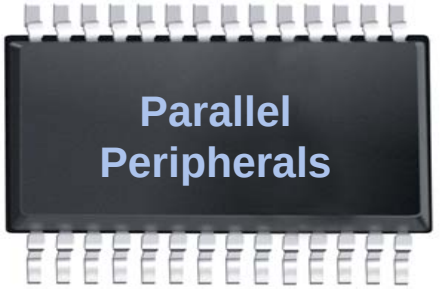
Lab 1: PPS

- **Goal:**
  - Configure simple UART echo to HyperTerminal using PIC24FJ64GA004 on Explorer16
- **To Do:**
  - Read the handout – fill in the code sections
- **Expected Result:**
  - Typed characters echoed back to Hyperterminal (LED D3 flashes for each keystroke)

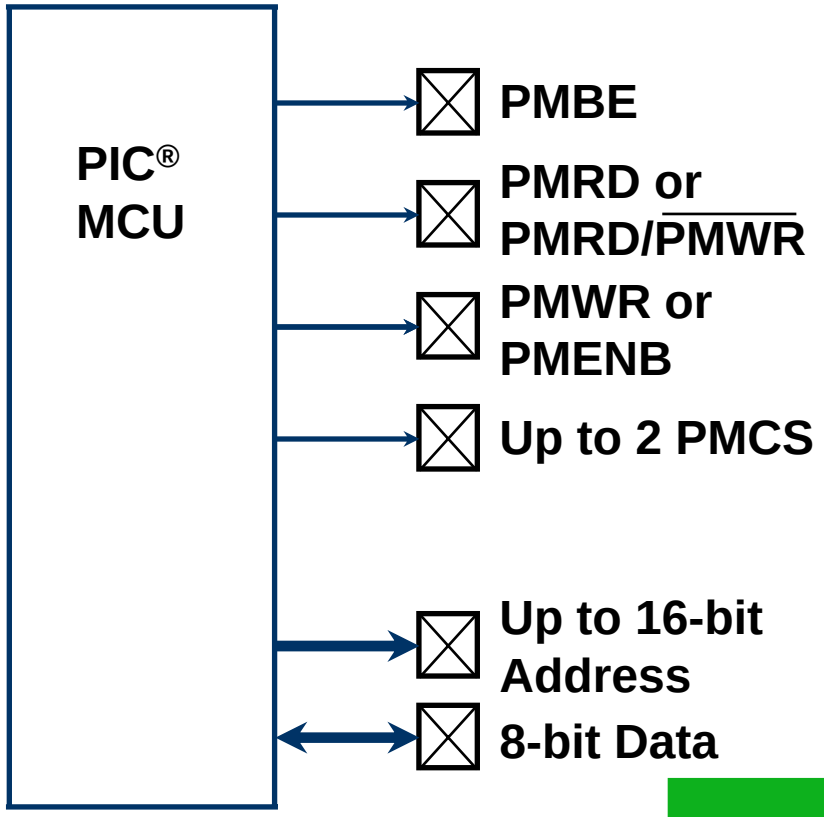
Parallel Master Port (PMP)

Parallel Master Port – PMP





PMP Configuration: Control Signals



The Signal can be individually Enabled or Disabled

PMCON: PTBEEN, PTWREN,
PMPEN: CS2, CS1

The Signal polarity can be individually selected

PMCON: ALP, CS2P, CS1P,
BEP, WRSP, RDSP

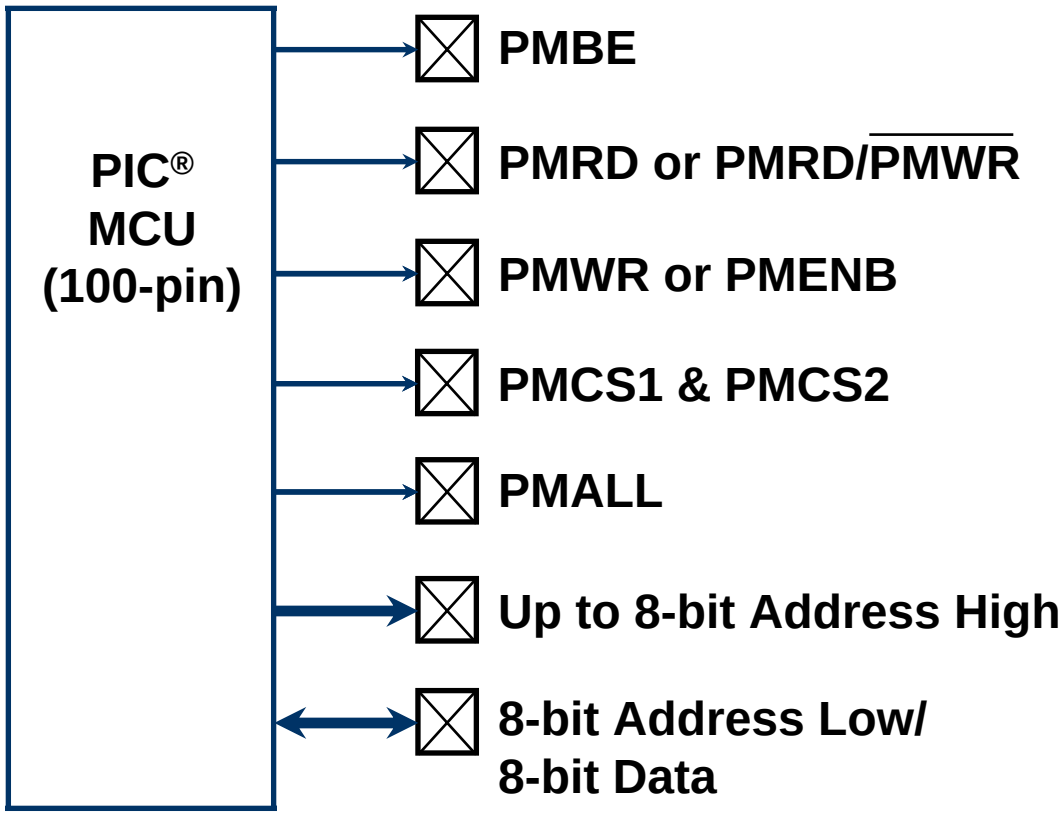
The Address pins can be individually Enabled or Disabled

PMPEN: Reg

PMMODE<INCM1:INCM0>

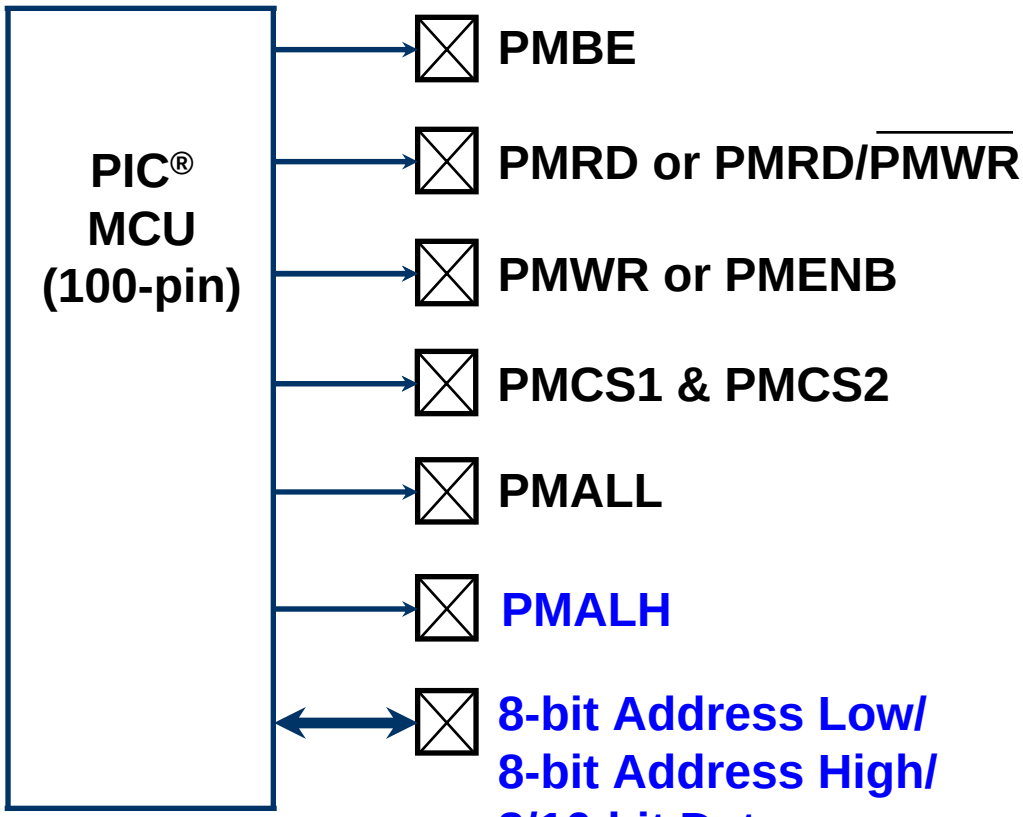
PMCON<CSF1:CSF0>	Chip Select Function
00	CS1, CS2, A15, A14
01	CS1, CS2, A15, A14
10	CS1, CS2, A15, A14

PMP Configuration: Multiplexed Data Bus



PMCON<ADRMUX1:ADRMUX0> = 01

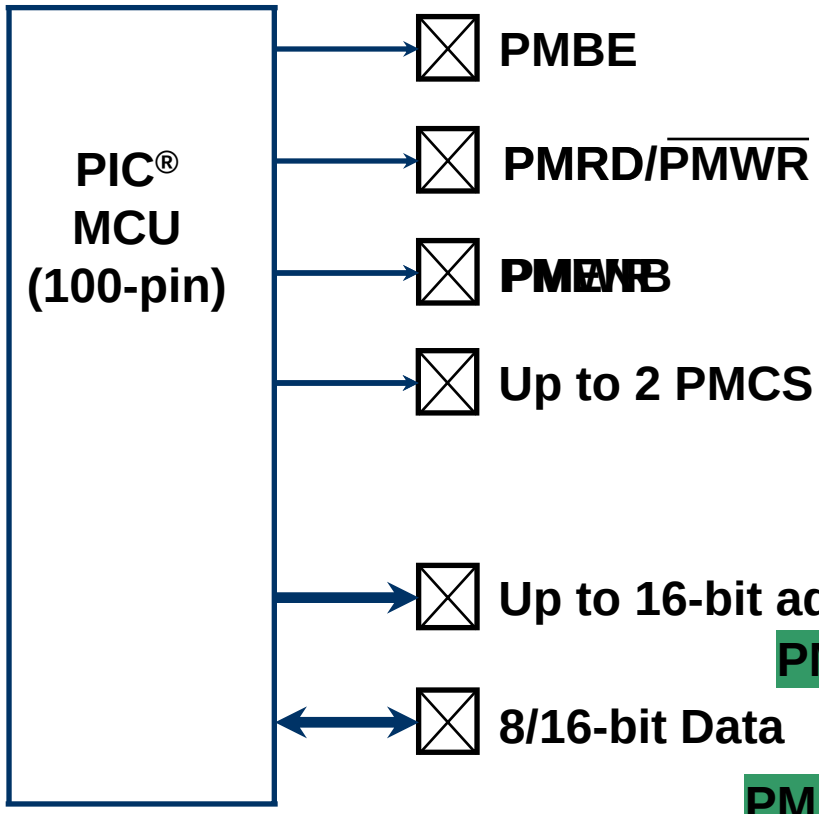
PMP Configuration: Multiplexed Data Bus



PMMODE<MODE16>

PMCON<ADRMUX1:ADRMUX0> = 10

PMP Configuration: Standard Peripherals



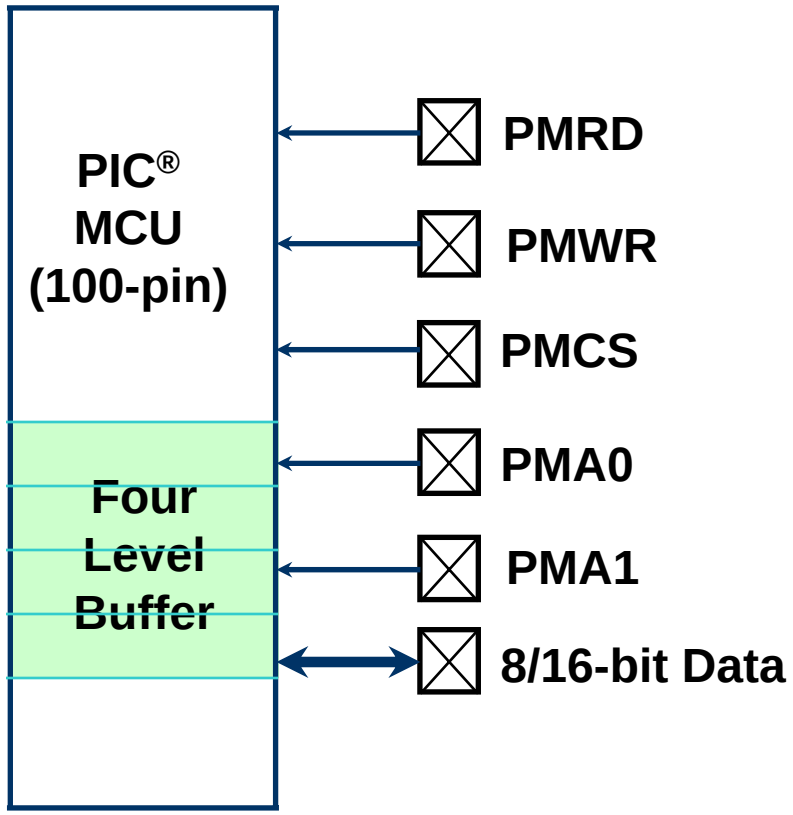
PMMODE<WAITB1:WAITB0>

PMMODE<MODE1:MODE0> = 10

PMMODE<WAITM3:WAITM0>

PMMODE<WAITE1:WAITE0>

PMP Configuration: Slave Mode



PMDIN2:PMDIN1

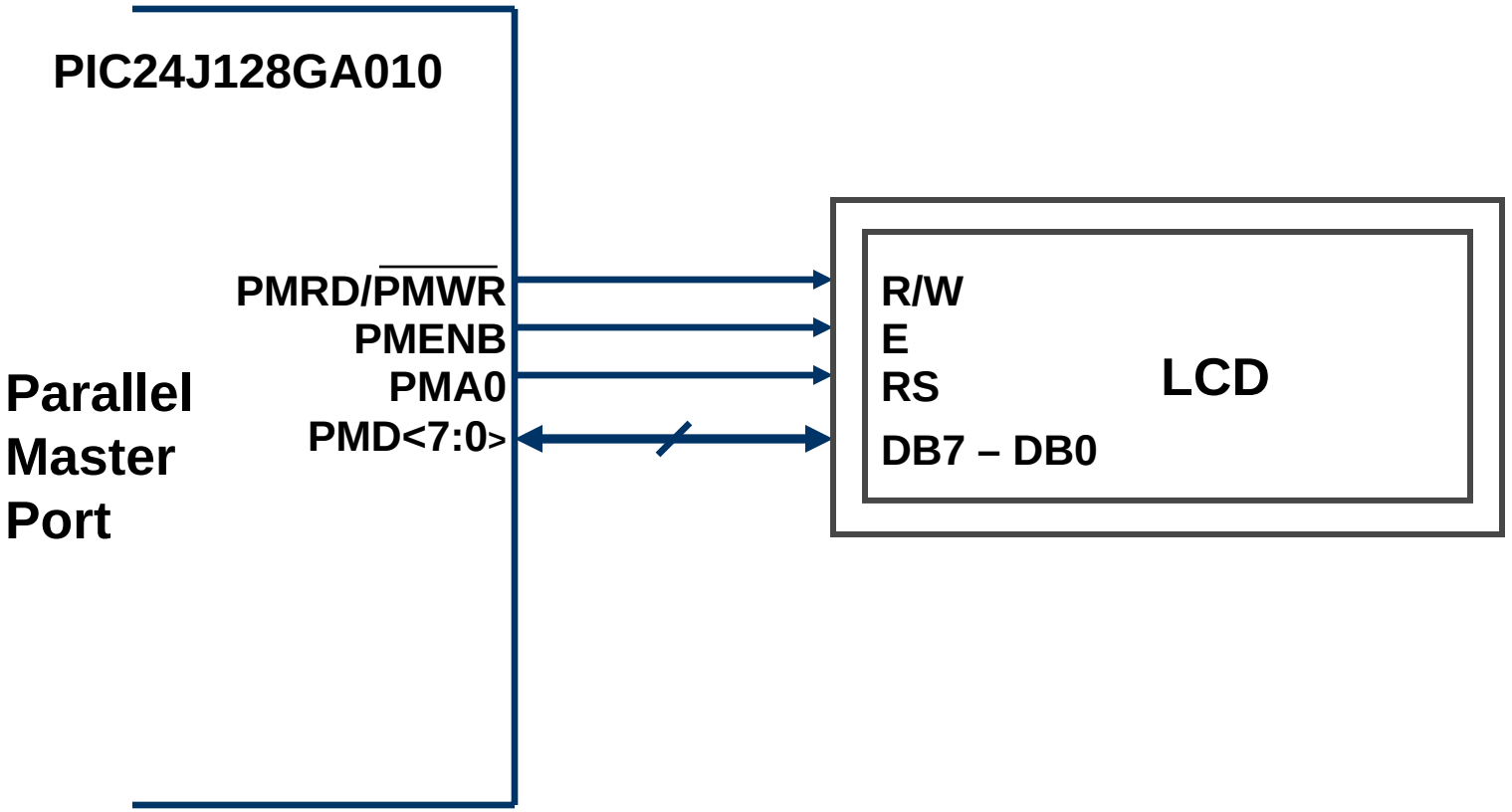
PMDOUT2:PMDOUT1

PMMODE<INCM1:INCM0> = 11

PMMODE<MODE1:MODE0> = 00

Optional Lab
The Parallel Master Port

Opt. Lab – LCD on the PMP

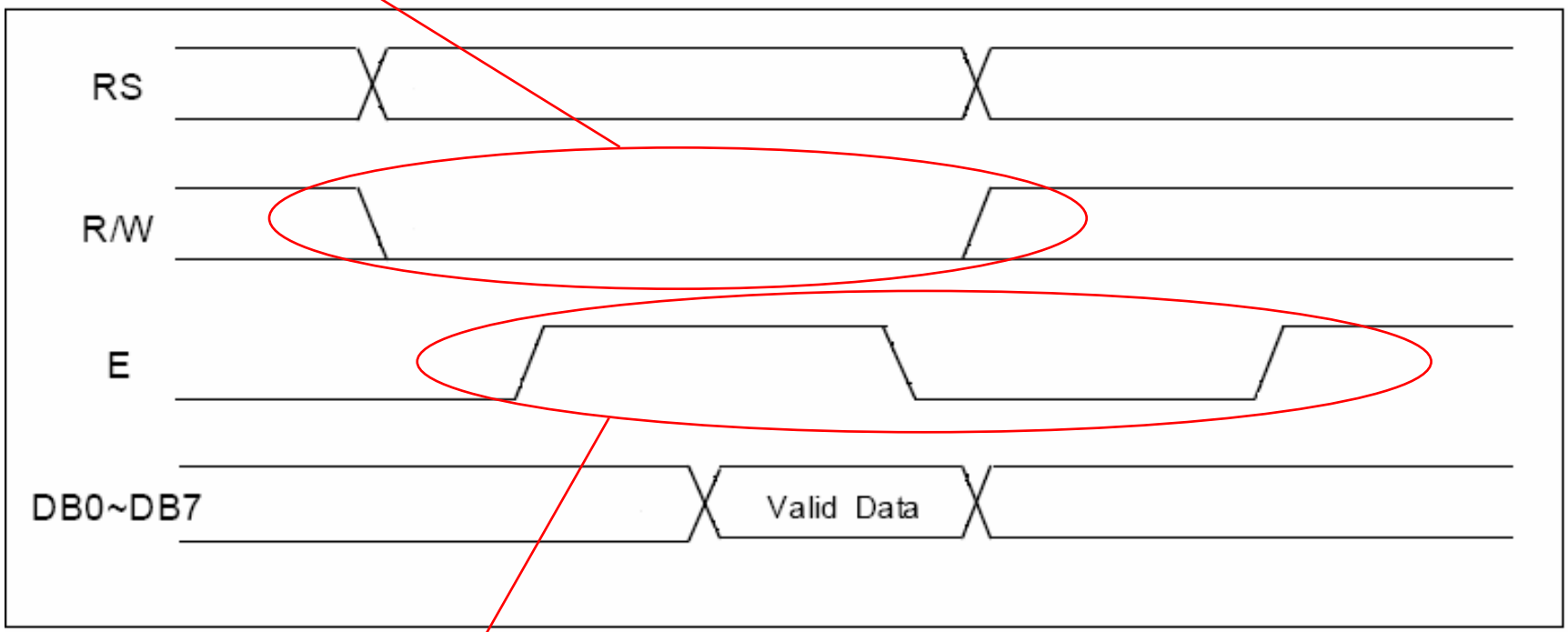


Opt. Lab – LCD on the PMP

- **Setup PMP for an LCD, think about:**
  - Signals
  - Polarity
  - LCD interface
  - Addressing
  - Timing

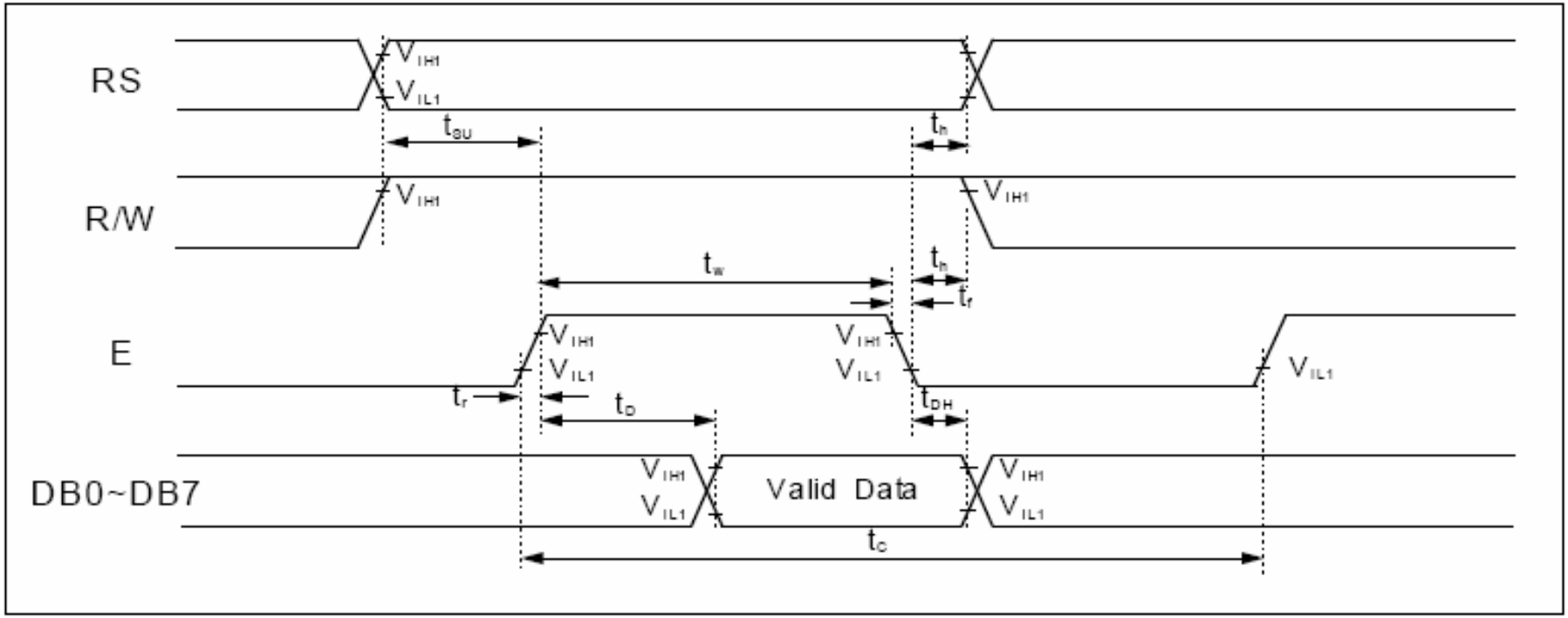
Opt. Lab – LCD Write Timing

Write is active low.
But remember! PMP signal we are using is PMRD/$\overline{\text{PMWR}}$,
so the pin needs to be configured as active high.



Enable is active High.

Opt. Lab – LCD Read Timing



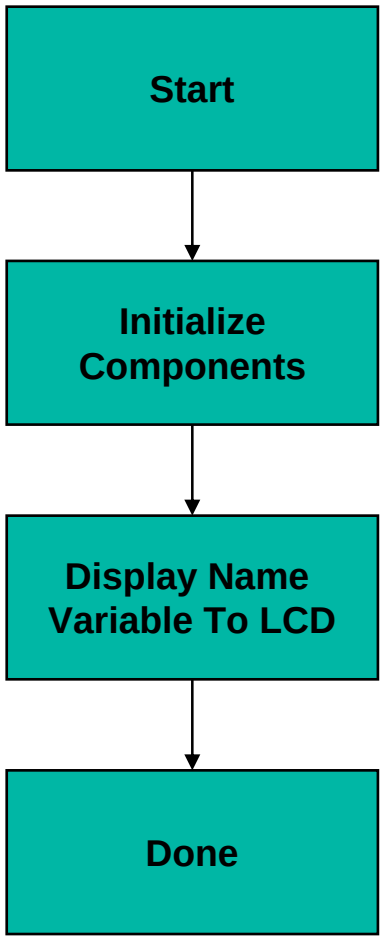
Opt. Lab – LCD Commands

Instruction	Instruction Code										Description	Execution time (fosc= 270 kHz)
	RS	R/W	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0		
Clear Display	0	0	0	0	0	0	0	0	0	1	Write "20H" to DDRAM and set DDRAM address to "00H" from AC	1.53 ms
Return Home	0	0	0	0	0	0	0	0	1	-	Set DDRAM address to "00H" from AC and return cursor to its original position if shifted. The contents of DDRAM are not changed.	1.53 ms
Entry Mode Set	0	0	0	0	0	0	0	1	I/D	SH	Assign cursor moving direction and enable the shift of entire display.	39 µs
Display ON/ OFF Control	0	0	0	0	0	0	1	D	C	B	Set display(D), cursor(C), and blinking of cursor(B) on/off control bit.	39 µs
Cursor or Display Shift	0	0	0	0	0	1	S/C	R/L	-	-	Set cursor moving and display shift control bit, and the direction, without changing of DDRAM data.	39 µs

Opt. Lab – LCD Commands (cont)

Function Set	0	0	0	0	1	DL	N	F	-	-	Set interface data length (DL: 8-bit/4-bit), numbers of display line (N: 2-line/1-line) and, display font type (F:5×11dots/5×8 dots)	39 μs
Set CGRAM Address	0	0	0	1	AC5	AC4	AC3	AC2	AC1	AC0	Set CGRAM address in address counter.	39 μs
Set DDRAM Address	0	0	1	AC6	AC5	AC4	AC3	AC2	AC1	AC0	Set DDRAM address in address counter.	39 μs
Read Busy Flag and Address	0	1	BF	AC6	AC5	AC4	AC3	AC2	AC1	AC0	Whether during internal operation or not can be known by reading BF. The contents of address counter can also be read.	0 μs
Write Data to RAM	1	0	D7	D6	D5	D4	D3	D2	D1	D0	Write data into internal RAM (DDRAM/CGRAM).	43 μs
Read Data from RAM	1	1	D7	D6	D5	D4	D3	D2	D1	D0	Read data from internal RAM (DDRAM/CGRAM).	43 μs

Opt. Lab – LCD on the PMP



Opt. Lab – LCD on the PMP

- **Goals**
  - Learn about the Parallel Master Port (PMP)
  - Refresh knowledge of the common LCD interface
  - Do some coding for PIC24
- **Lab**
  - Add setup code to initialize the PMP
  - Put your name on the display

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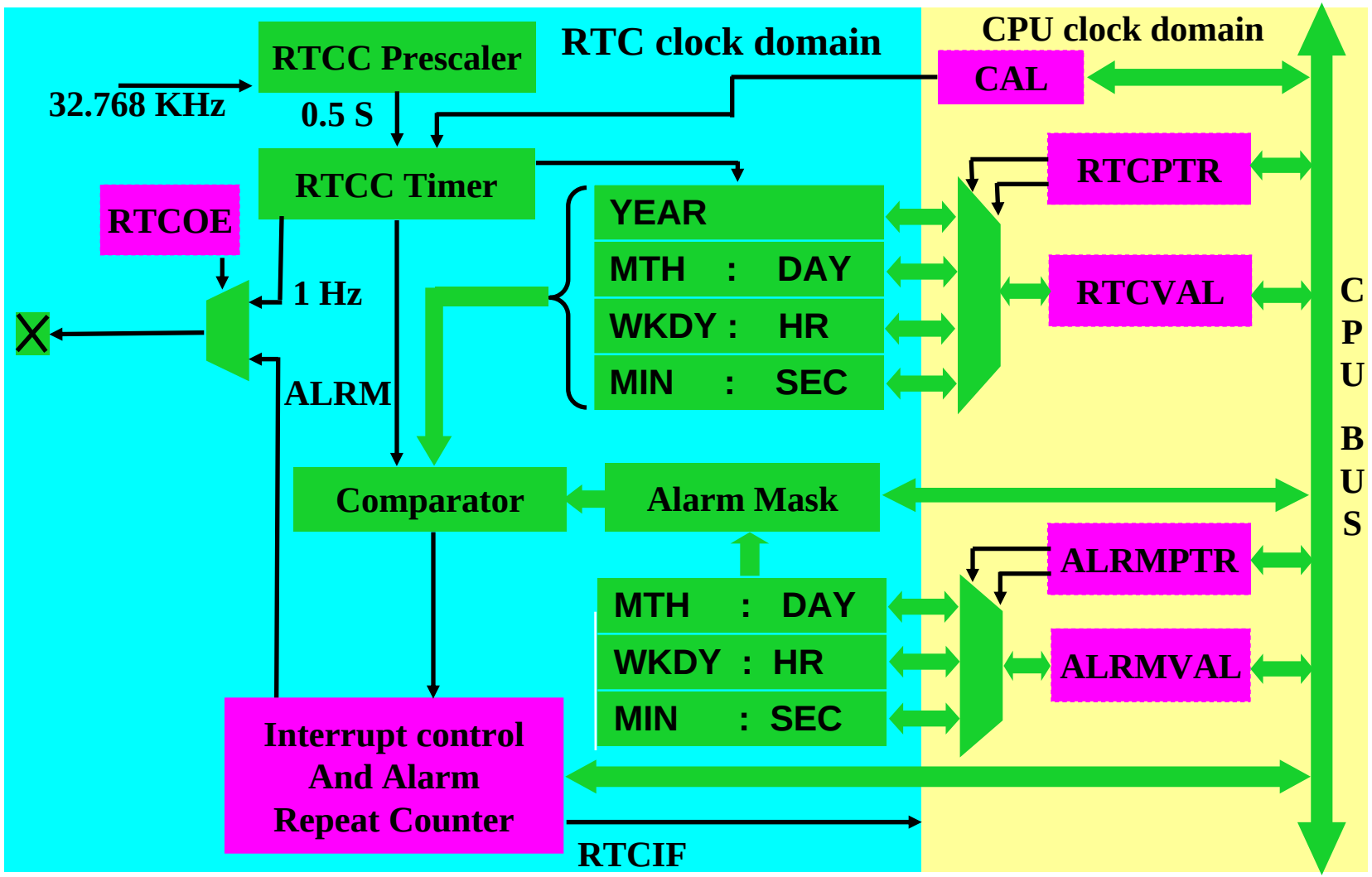
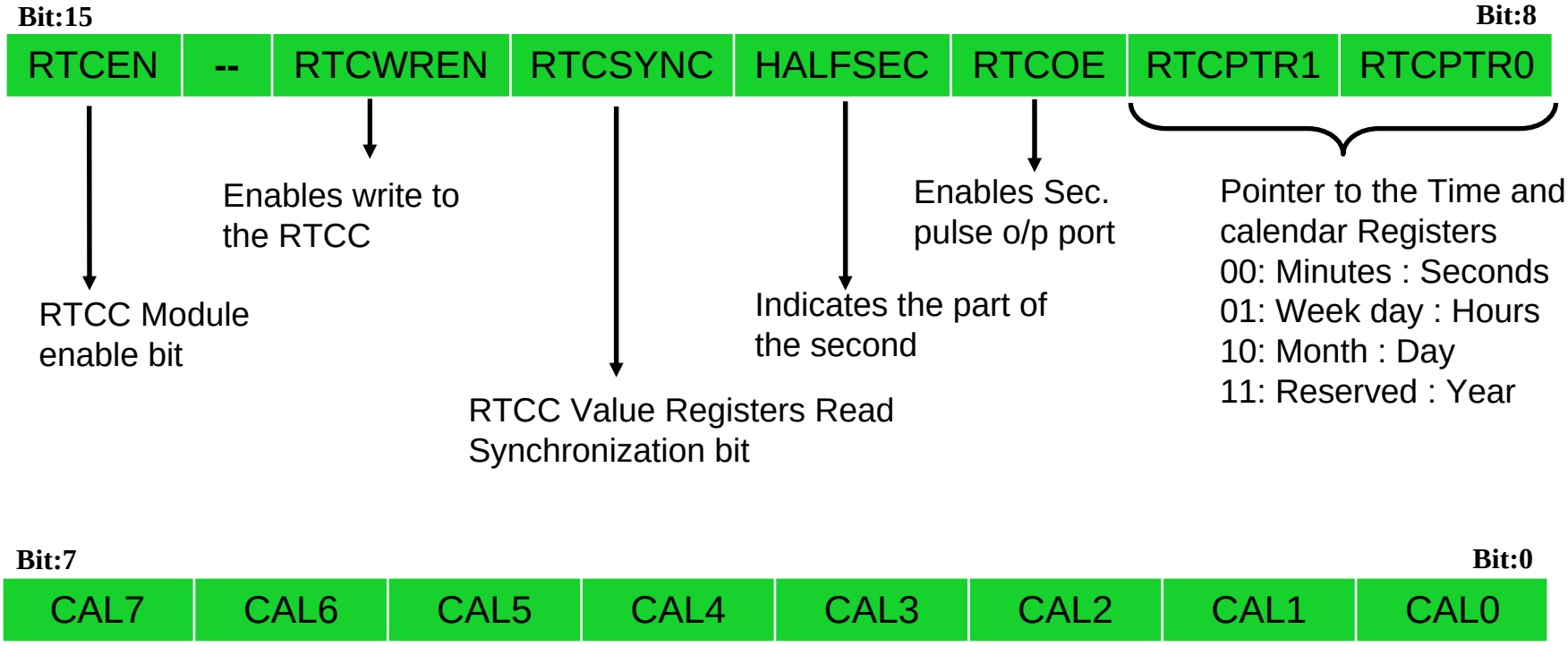
Real-time Clock & Calendar (RTCC)

RTCC: Block Diagram



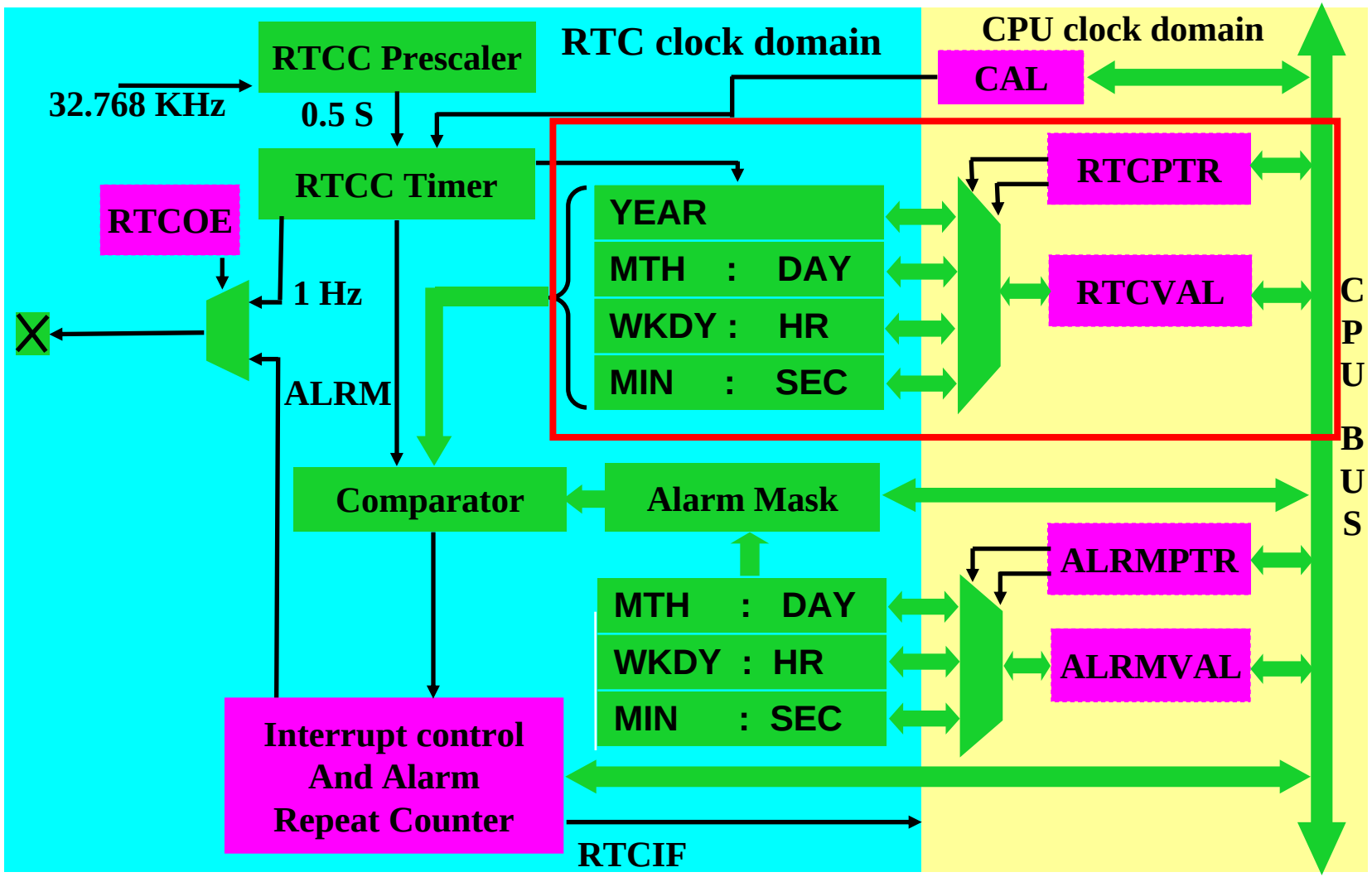
RTCC: Configuration

RCFGCAL: RTCC Calibration and Configuration register

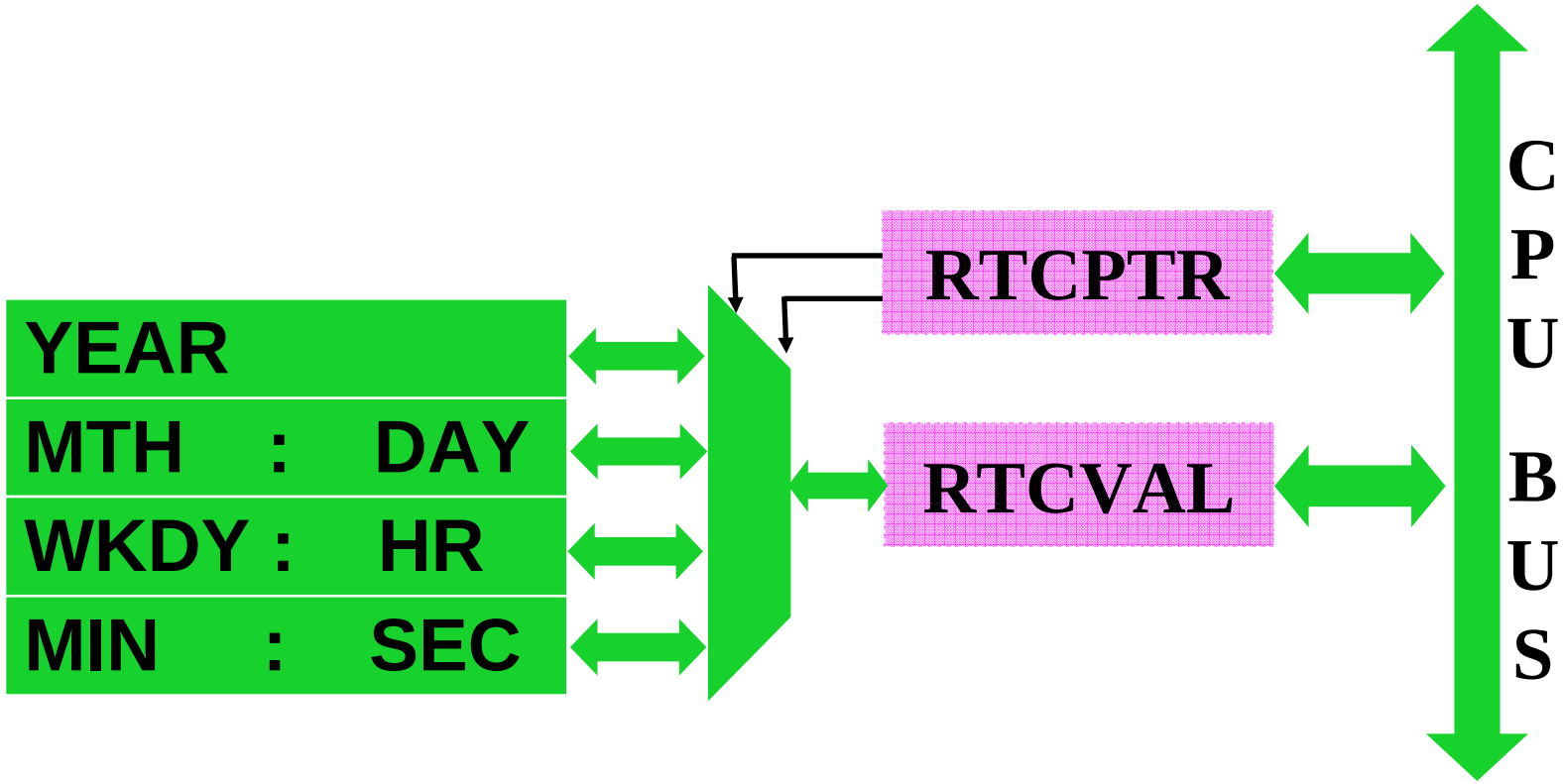


Crystal offset calibration bits (RTCC Drift calibration bits)

RTCC: Block Diagram



RTCC: Registers



RTCC: Registers

RTCVAL: RTCC Value Register

- Pointer bits, RTCPTR<1:0>, indicate which register is read from and written to RTCVAL
- RTCPTR<1:0> auto decrements when RTCVAL<15:8> is read or written until it reaches '00'

RTCPTR<1:0>	RTCVAL<15:8>	RTCVAL<7:0>
11	---	YEAR
10	MONTH	DAY
01	WEEKDAY	HOURS
00	MINUTES	SECONDS

RTCC: Registers

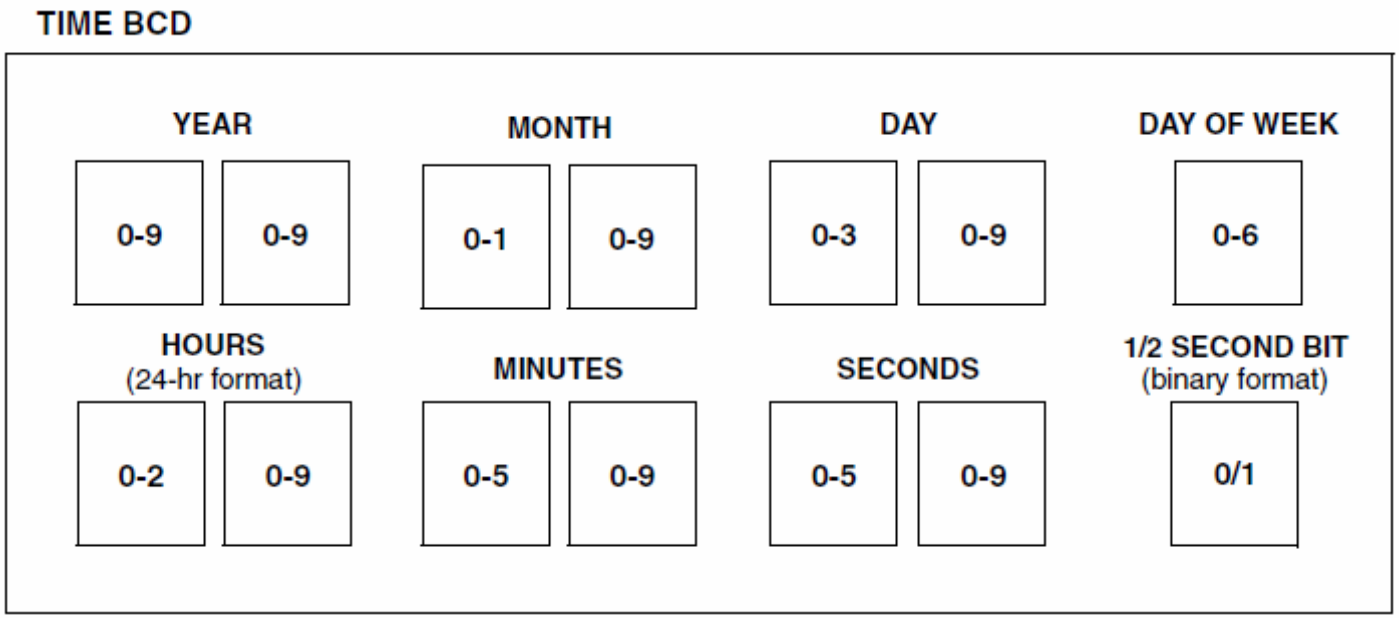
ALRMVAL: RTCC Alarm Value Register

- **Pointer bits, ALRMPTR<1:0> indicate what is read from and written to ALRMVAL**
- **ALRMPTR<1:0> auto decrements when ALRMVAL<15:8> is read or written until it reaches '00'**

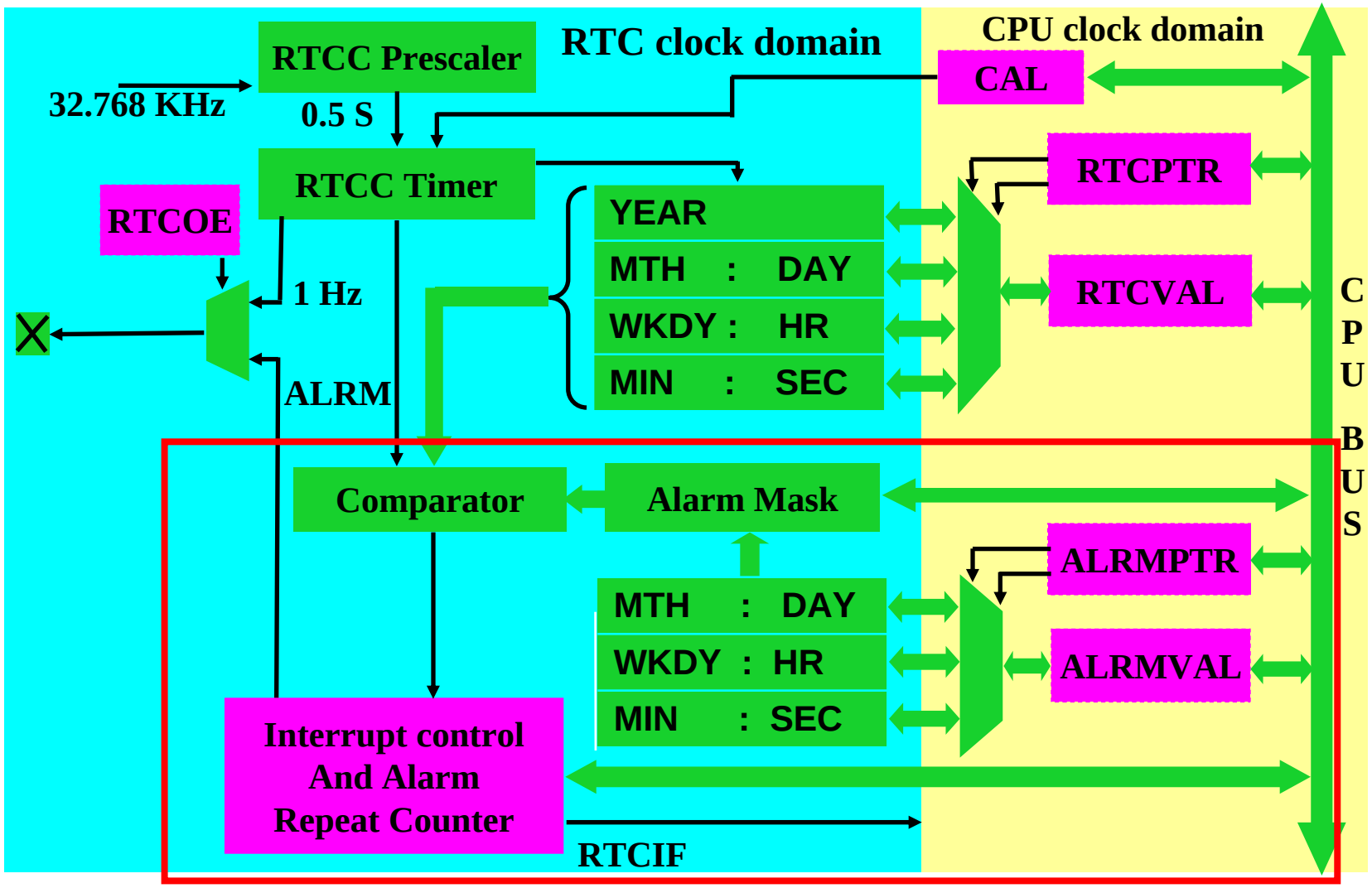
ALRMPTR<1:0>	ALRMVAL<15:8>	ALRMVAL<7:0>
11	---	---
10	ALRMMNTH	ALRMDAY
01	ALRMWD	ALRMHR
00	ALRMMIN	ALRMSEC

RTCC: Registers

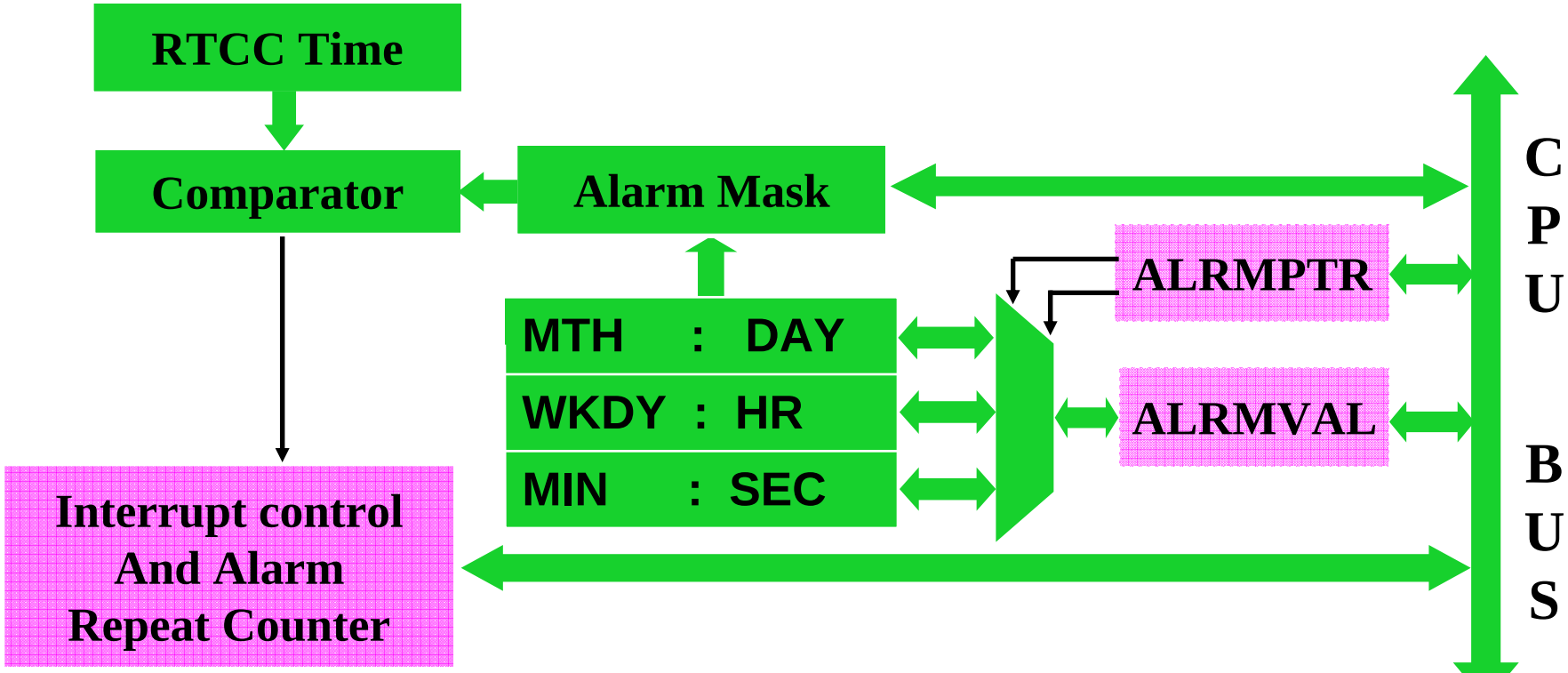
- **RTCVAL and ALRMVAL registers use BCD format**
- **In BCD, each nibble (4 bits) of a word encodes a number from 0-9**



RTCC: Block Diagram

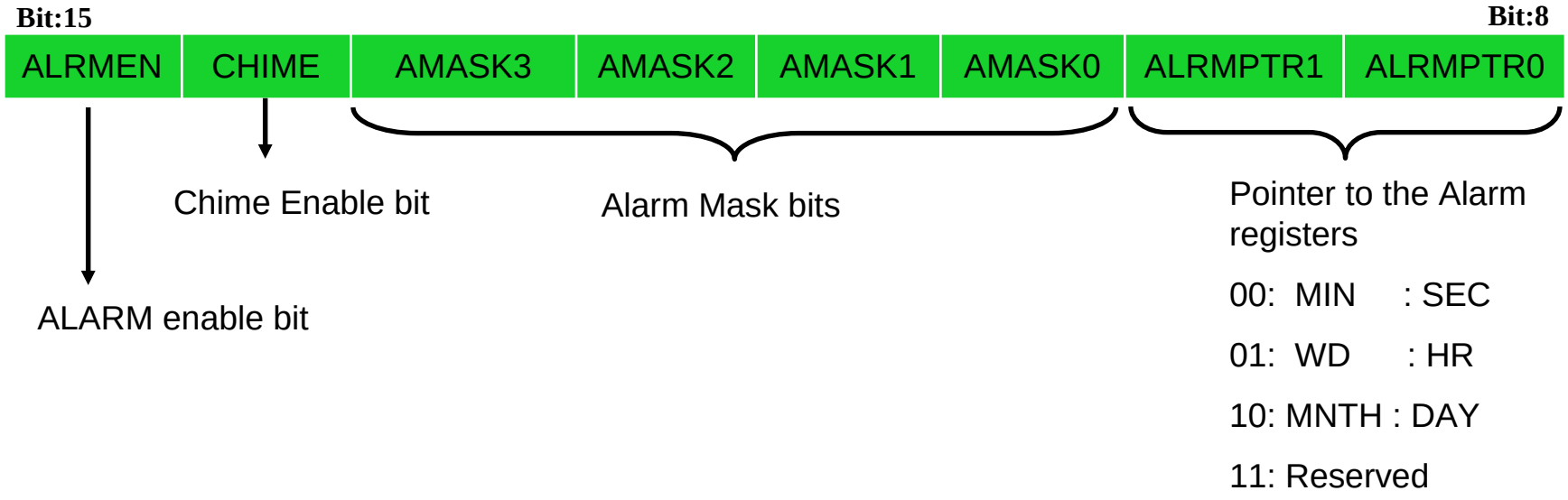


RTCC: Alarm



RTCC: Configuration

ALCFGRPT: RTCC Calibration and Configuration register



Alarm Repeat Counter Value bits (Repeat count = 2^n)

RTCC: Alarm

- **AMASK<3:0> controls which registers of ALRMVAL and RTCVAL are compared to generate an alarm**

Alarm Mask Setting AMASK<3:0>	Day of the Week	Month	Day	Hours	Minutes	Seconds
0000 – Every half second 0001 – Every second						
0010 – Every 10 seconds						s
0011 – Every minute						s s
0100 – Every 10 minutes					m	s s
0101 – Every hour					m m	s s
0110 – Every day				h h	m m	s s
0111 – Every week	d			h h	m m	s s
1000 – Every month			d d	h h	m m	s s
1001 – Every year(1)		m m	d d	h h	m m	s s

Note 1: Annually, except when configured for February 29.

RTCC: Alarm

Alarm Mask Setting AMASK<3:0>	Day of the Week	Month	Day	Hours	Minutes	Seconds
0111 – Every week	d		/	h h	: m m	: s s

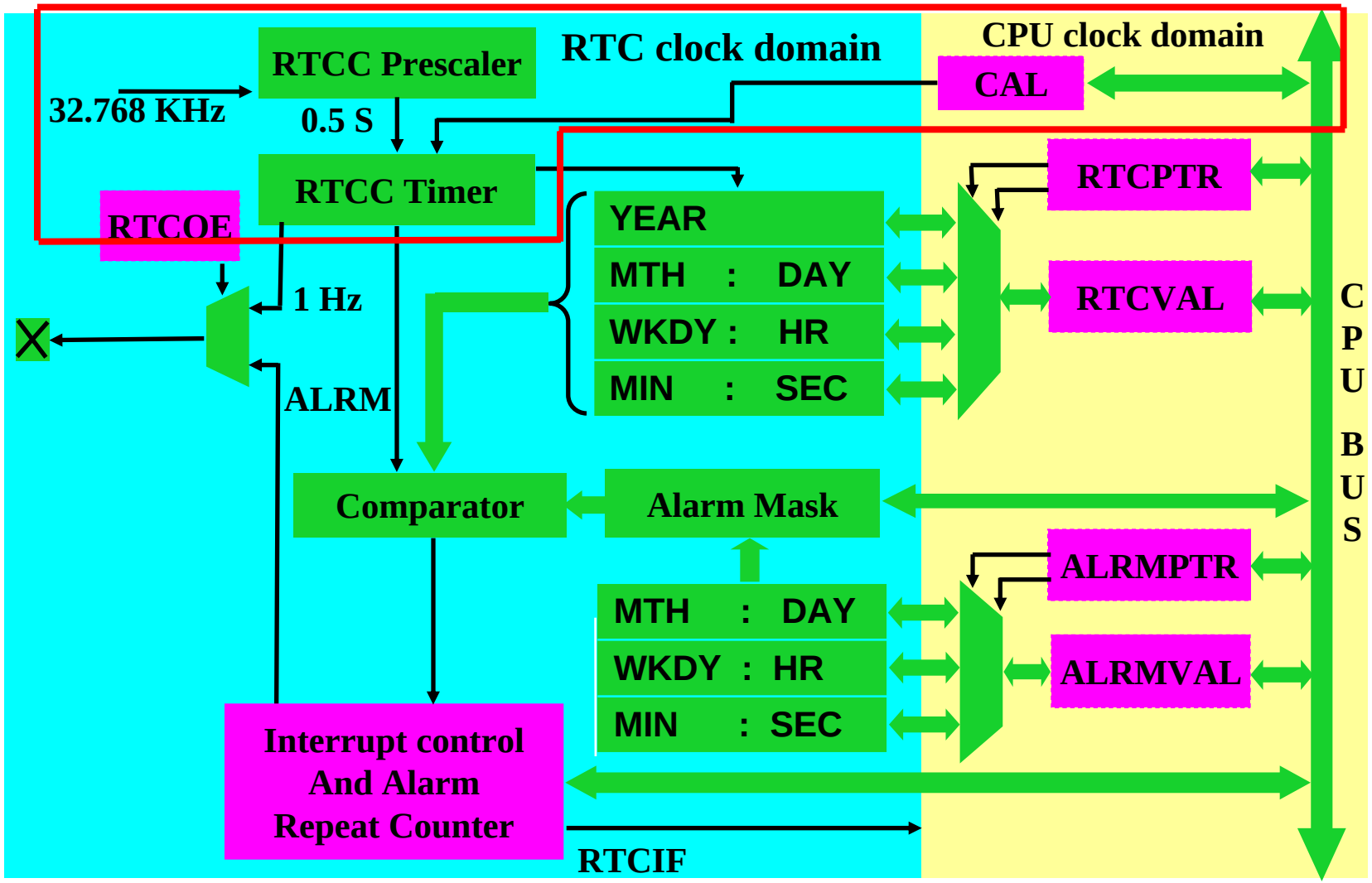
ALRMMNTH	ALRMDAY	ALRMWD	ALRMHR	ALRMMIN	ALRMSEC
12	24	Tuesday	4	45	53

YEAR	MONTH	DAY	WEEKDAY	HOURS	MINUTES	SECONDS
06	9	5	Tuesday	4	45	52

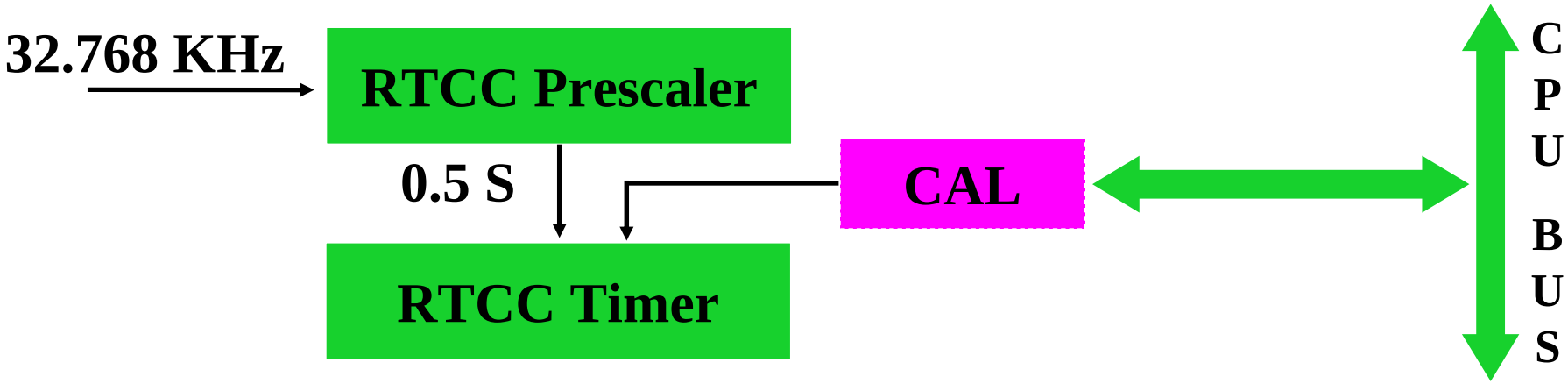
ALARM INTERRUPT

- **Chime allows ARPT to rollover from 00 to FF**
  - Alarms can be repeated indefinitely

RTCC: Block Diagram

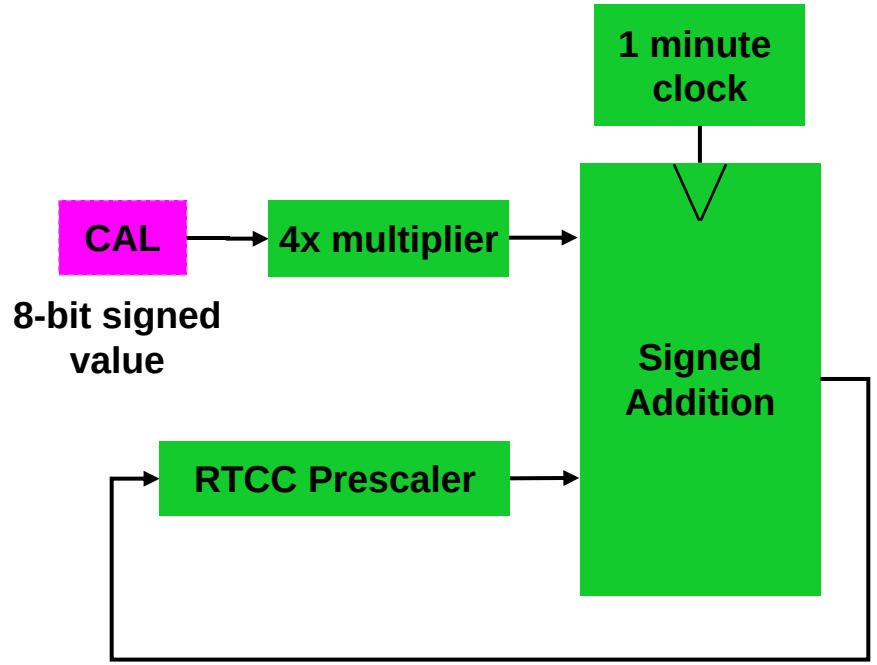


RTCC: Clock Calibration

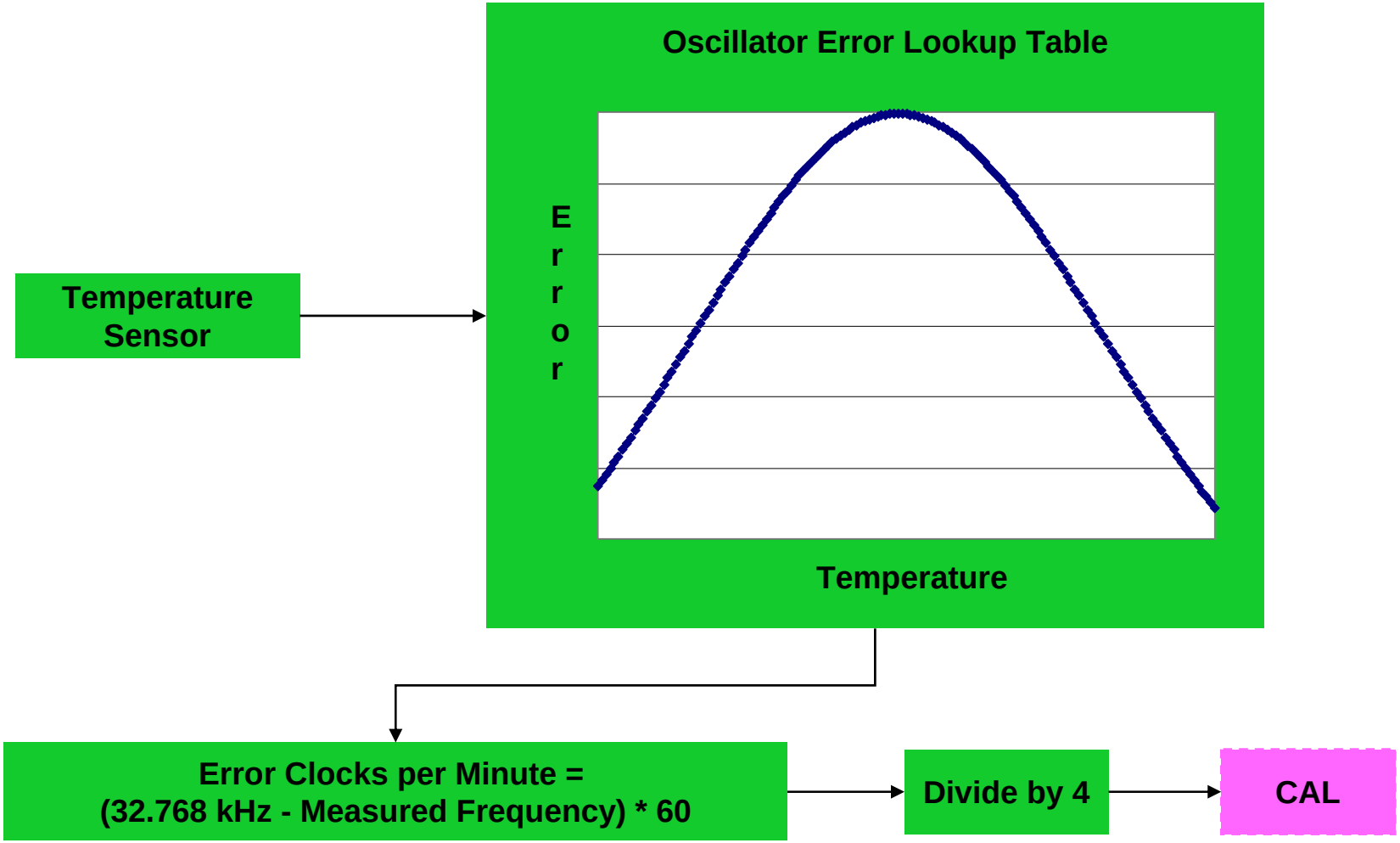


RTCC: Clock Calibration

- Calibrating the RTCC allows for accuracy with error less than 3 seconds per month



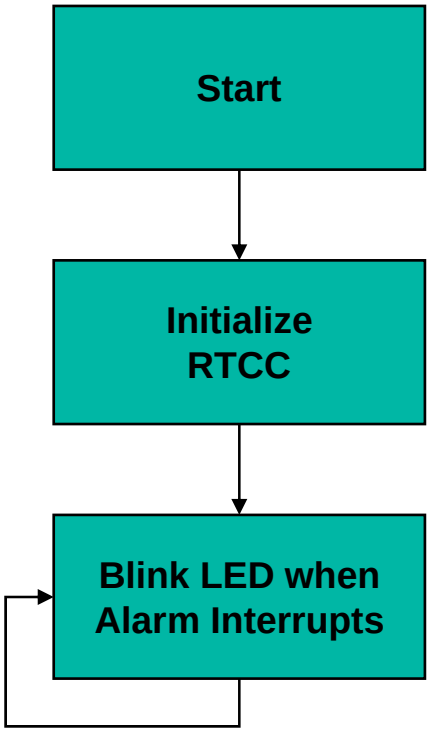
RTCC: Temperature Compensation



Lab 2

Real-time Clock and Calendar

Lab 2 – RTCC



Lab 2 – RTCC

- **Goals**
  - Learn about the Real-Time Clock and Calendar (RTCC)
  - Do some more coding for PIC24
- **Three parts to this lab**
  - Add code to unlock RTCC registers (rtcc.c)
  - Add code to set the time (rtcc.c)
  - Add code to set an alarm (rtcc.c)

Programmable Cyclic Redundancy Check Generator (CRC)

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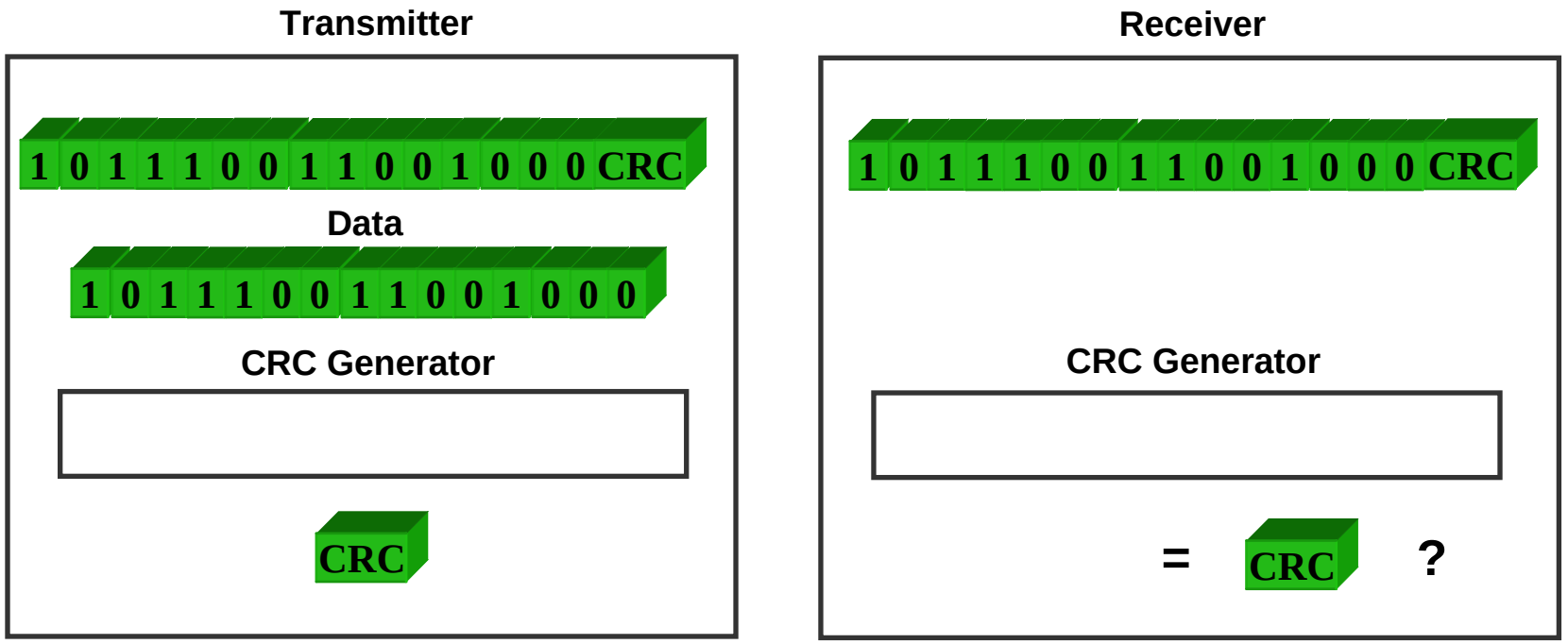
What Is CRC?

- CRC - Cyclic Redundancy Check
- CRC provides a simple and powerful method for the detection of errors in memory and communications
- CRC is a technique to detect errors but not for correcting errors

CRC Checksum

- The CRC Checksum is appended to the end of the data
- The receiver runs the data through a CRC Generator and compares the result with the received CRC checksum



CRC Messages

- **The CRC method treats the data as a polynomial**
- **For example, if data is 11100101**
  - Data: 1 1 1 0 0 1 0 1
  - Poly: x7 x6 x5 x4 x3 x2 x 1
- **So the data polynomial will be**
  - x7+x6+x5+x2+1

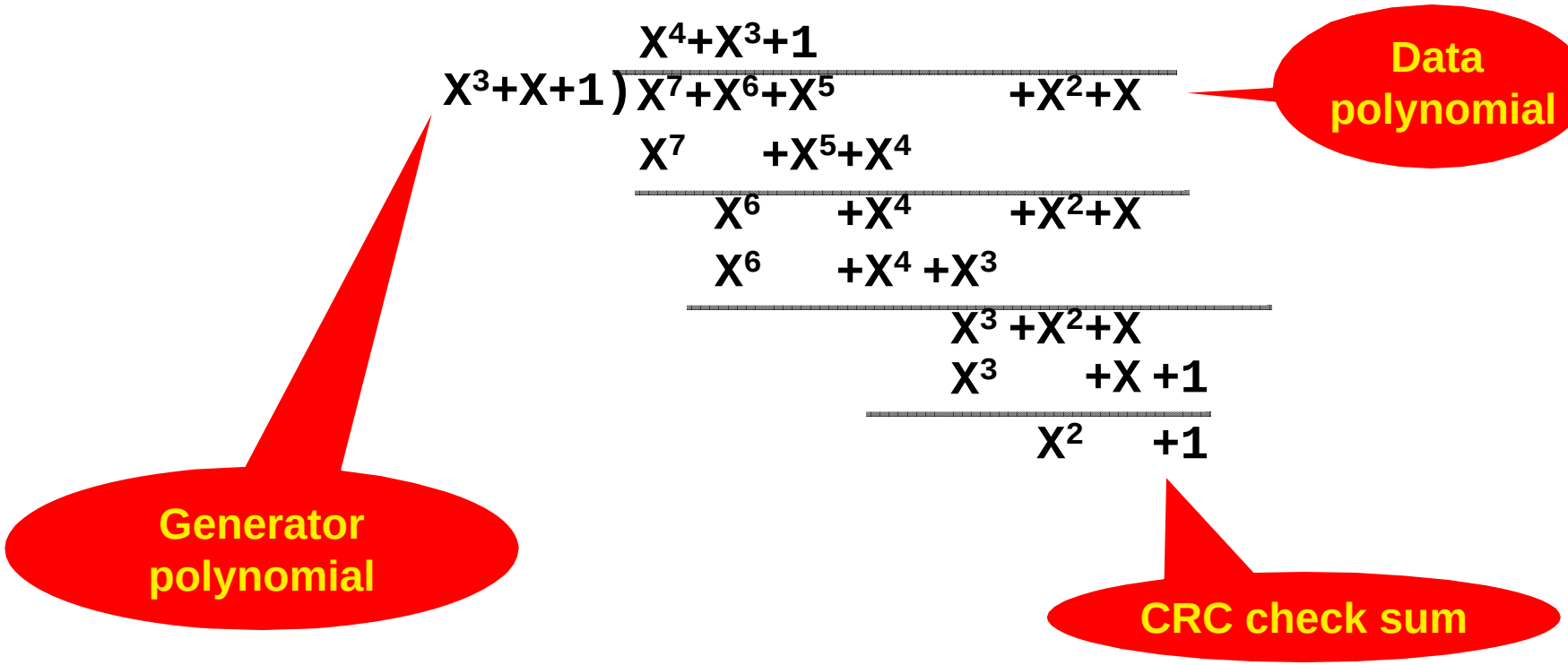
Configuring The CRC Generator Registers

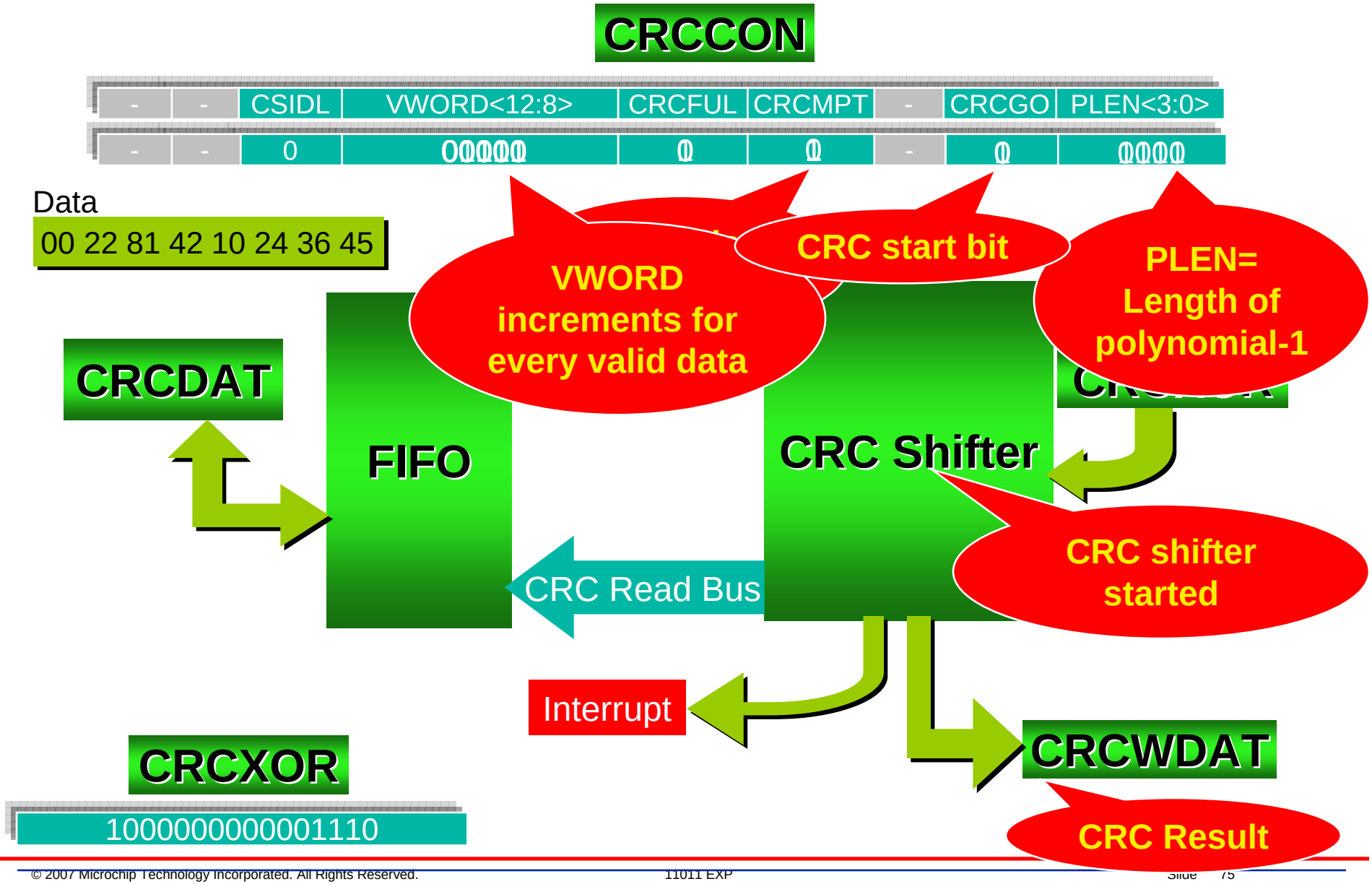
- **Generator Polynomial Example**
  - Polynomial = $x^{16} + x^{15} + x^3 + x^2 + x + 1$
  - Polynomial Length (PLEN) is the highest order term minus one (i.e. 15)
  - CRCXOR Register is configured by setting a 1 for polynomial terms between [15:1] (i.e. 0x800E)

x^{15}	x^{14}	x^{13}	x^{12}	x^{11}	x^{10}	x^9	x^8	x^7	x^6	x^5	x^4	x^3	x^2	x^1	N/A
1	**0**	**0**	**0**	**0**	**0**	**0**	**0**	**0**	**0**	**0**	**0**	**1**	**1**	**1**	**0**

Programmable CRC Generator

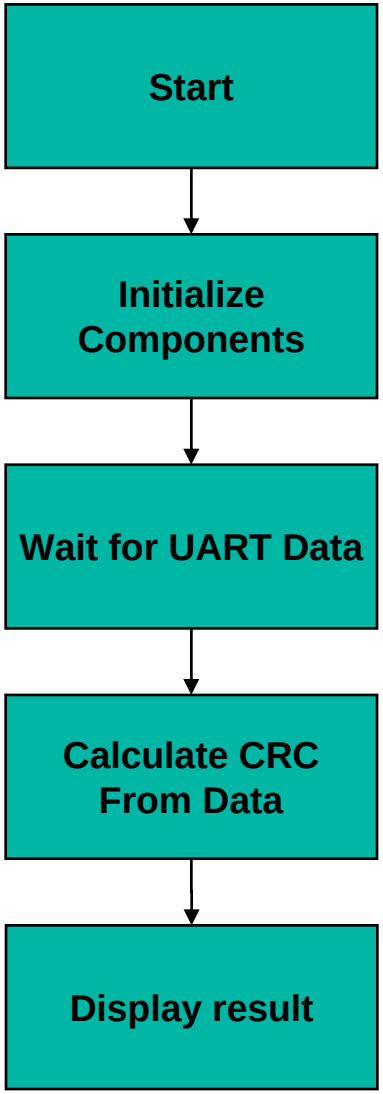
- For example,
- Assume data polynomial to be $x^7+x^6+x^5+x^2+x$
- Assume a generator polynomial to be x^3+x+1





Lab 3
Programmable CRC Generator

Lab 3 CRC



Lab 3 – CRC

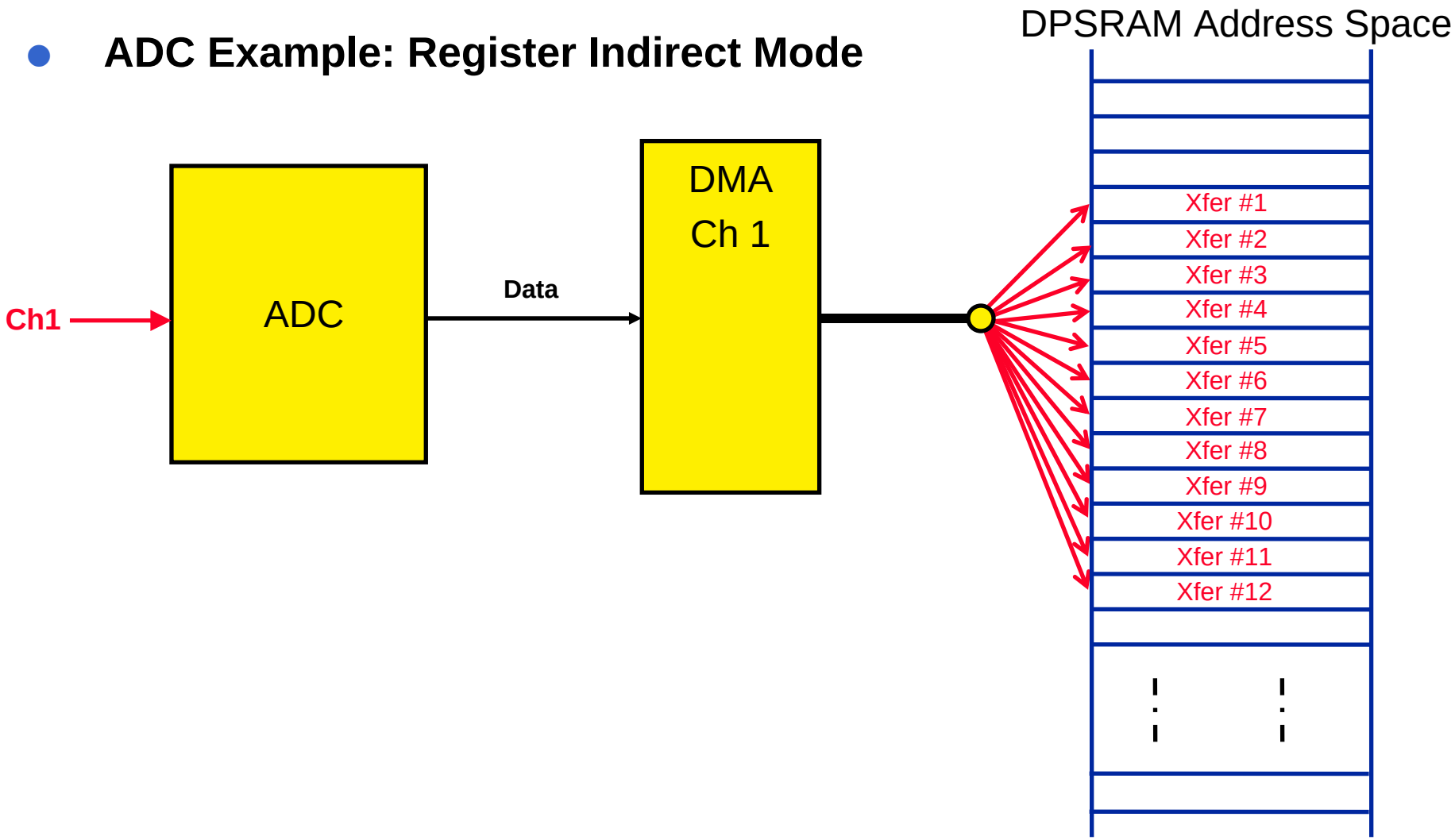
- **Goals**
  - Learn about the Programmable CRC Generator
  - Do some more coding for PIC24
- **Three parts to this lab**
  - Add code to configure the CRC generator for the polynomial $x^{16} + x^{15} + x^2 + 1$ (main.c)
  - Add code to start CRC generator (main.c)
  - Check results of CRC generation and verification on LCD Display

DMA

Direct Memory Access

DMA Example: ADC

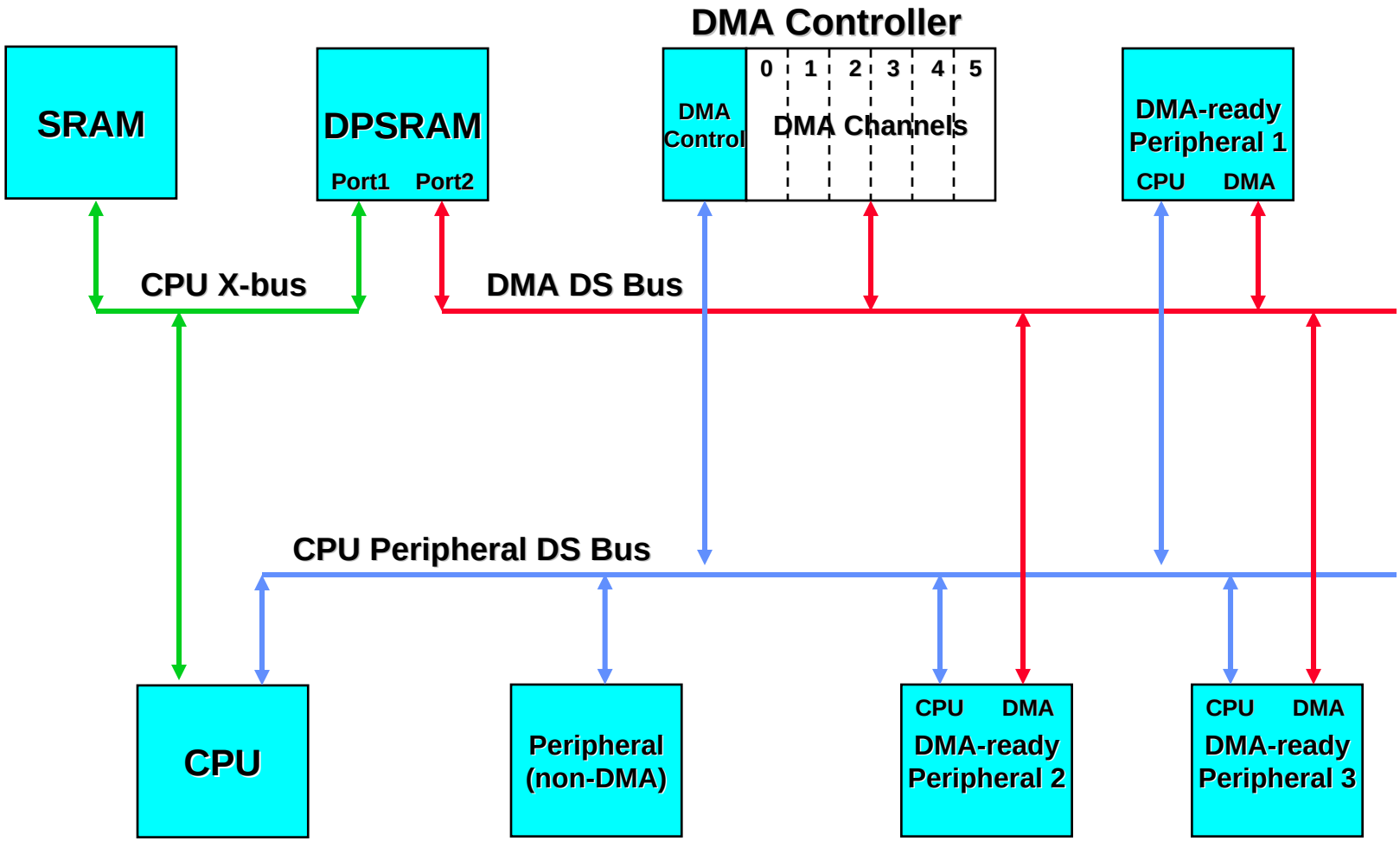
- **ADC Example: Register Indirect Mode**



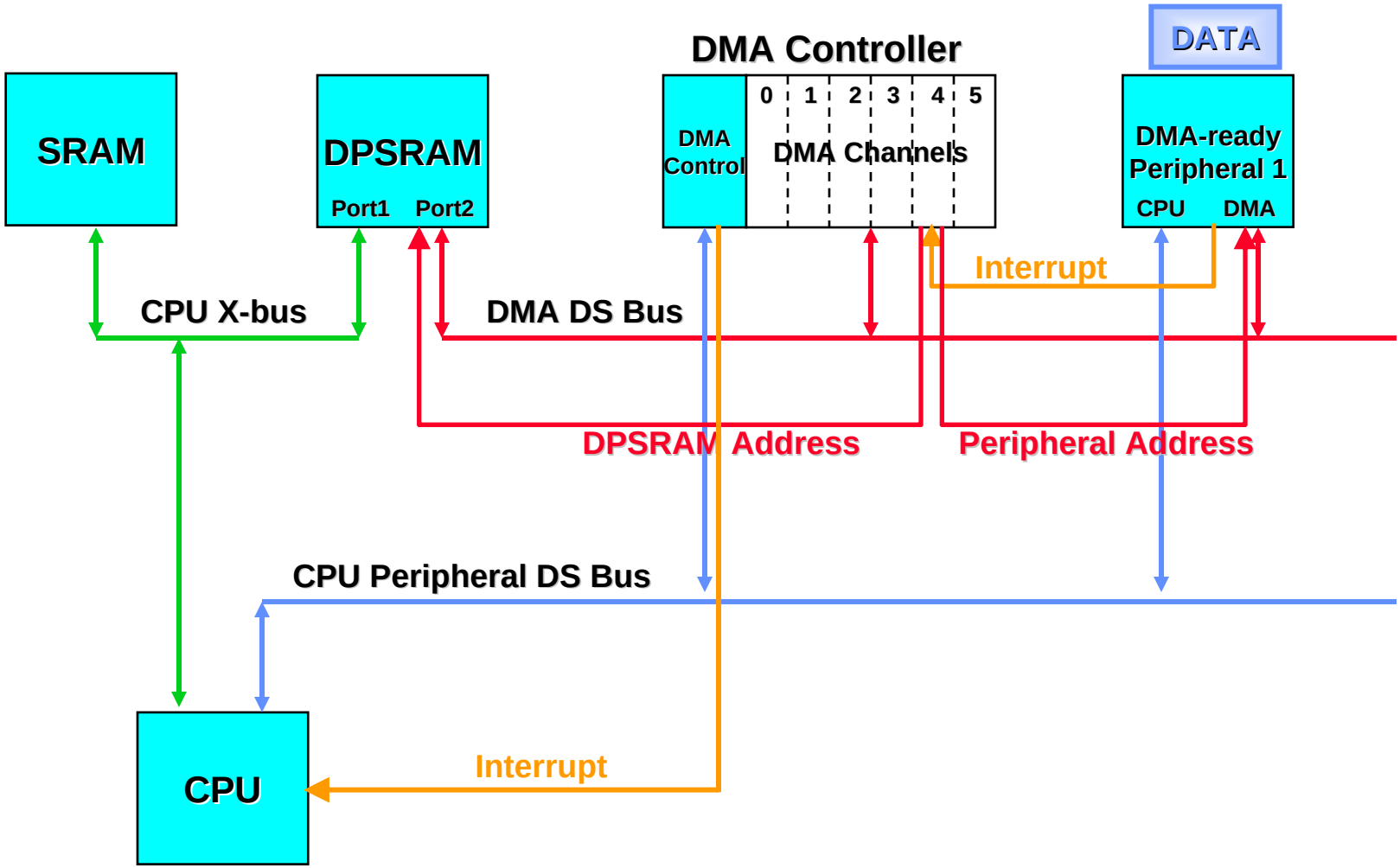
DMA Features

- 8 DMA channels
- Register indirect with post increment addressing mode
- Peripheral indirect addressing mode
  - Peripheral generates destination address
- CPU interrupt after half or full block transfer complete
- Byte or word transfers
- Fixed priority channel arbitration
- Manual or Automatic transfers
- One-shot or Auto-Repeat transfers
- 'Ping-pong' mode
  - Automatic switch between two buffers
- DMA request for each channel can be selected from any supported interrupt sources
- Debug support features

DMA Controller Block Diagram



DMA Controller Operation



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DMA Support

- **Supported 16-bit Families**
  - PIC24H
  - dsPIC33F
- **Supported 16-bit Peripherals**
  - ECAN™ Module
  - Data Converter Interface (DCI)
  - 10-bit/12-bit A/D Converter
  - Serial Peripheral Interface (SPI)
  - UART
  - Input Capture
  - Output Compare
- **DMA Request Support Only**
  - Timers
  - External Interrupts

Enabling DMA Operation

1. Associate DMA channel with peripheral
2. Configure DMA capable peripheral
3. Initialize DPSRAM data start addresses
4. Initialize DMA transfer count
5. Select appropriate addressing and operating modes

Step 1: Associate DMA and Peripheral

- Associate peripheral IRQ with DMA via DMAxREQ
- Provide peripheral read/write address via DMAxPAD

Example: Associate DMA Channel 0 and 1 with UART2 Transmitter and Receiver respectively

```
DMA0REQbits.IRQSEL = 0x1F;
DMA0PAD = (volatile unsigned int) &U2TXREG;

DMA0REQbits.IRQSEL = 0x1E;
DMA0PAD = (volatile unsigned int) &U2RXREG;
```

Step 2: Configure DMA-Ready Peripheral

- Configure peripherals to generate interrupt for every transfer (if applicable)

Example: Configure UART2 to generate DMA request after each Tx and Rx character

```
U2STAbits.UTXISEL0 = 0;   // Interrupt after one Tx character is transmitted
U2STAbits.UTXISEL1 = 0;
U2STAbits.URXISEL  = 0;   // Interrupt after one RX character is received
```

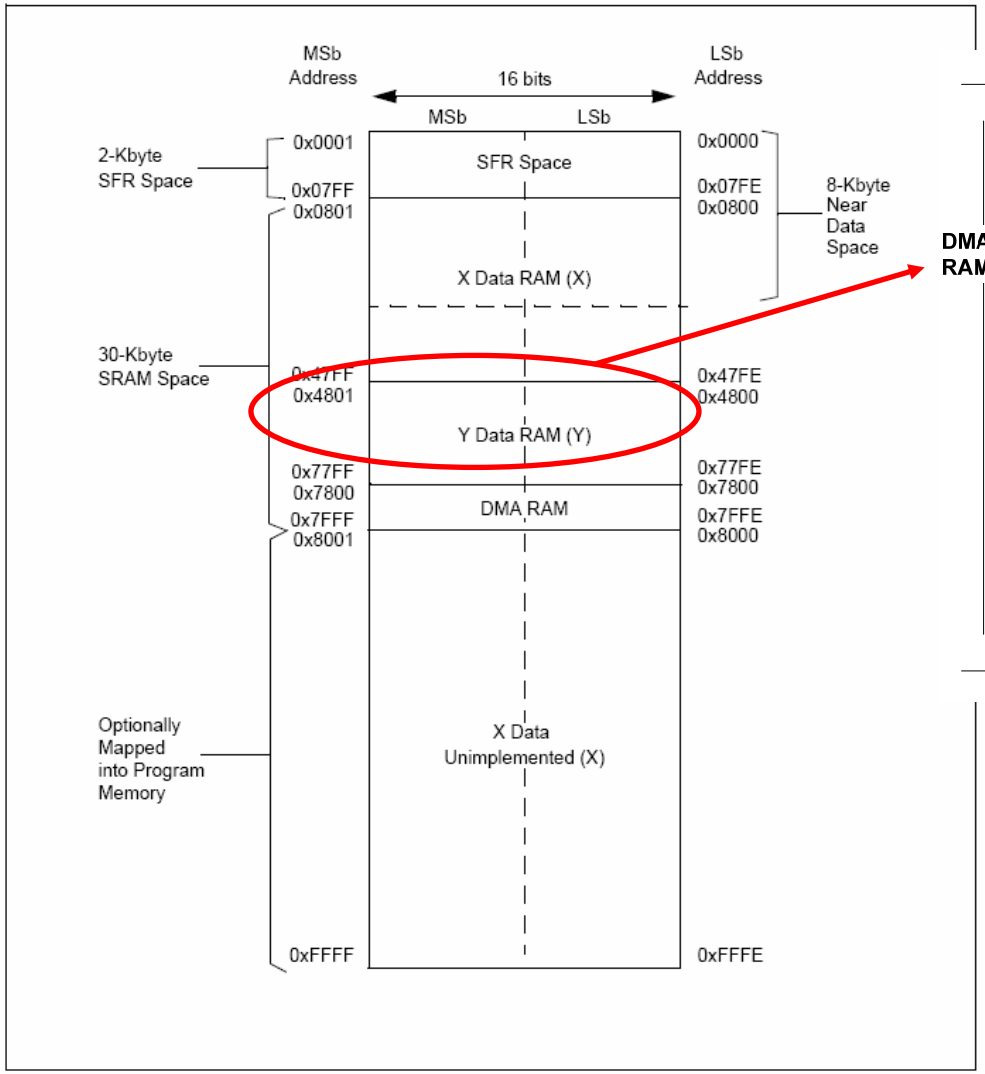
- Enable Error interrupts (if applicable)

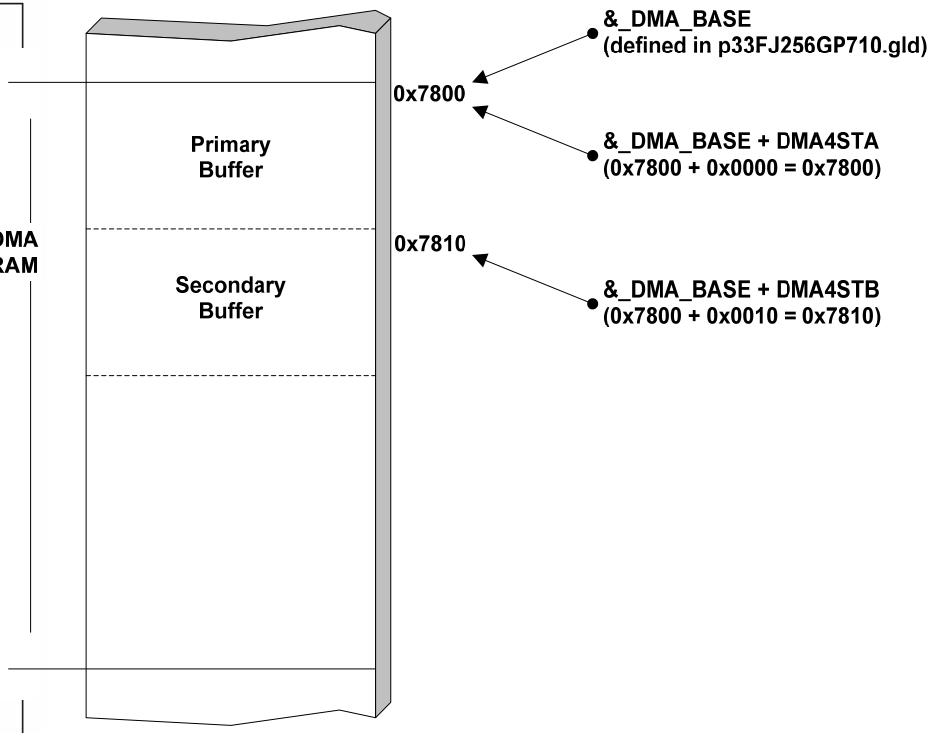
Example: Enable and process UART2 error interrupts

```
IEC4bits.U2EIE = 0;                 // Enable UART2 Error Interrupt

void __attribute__((__interrupt__)) _U2ErrInterrupt(void)
{
      /* Process UART 2 Error Condition here */

      IFS4bits.U2EIF = 0; // Clear the UART2 Error Interrupt Flag
}
```

Step 3: Initialize DPSRAM data start addresses

FIGURE 3-5: DATA MEMORY MAP FOR dsPIC33F DEVICES WITH 30 KBs RAM

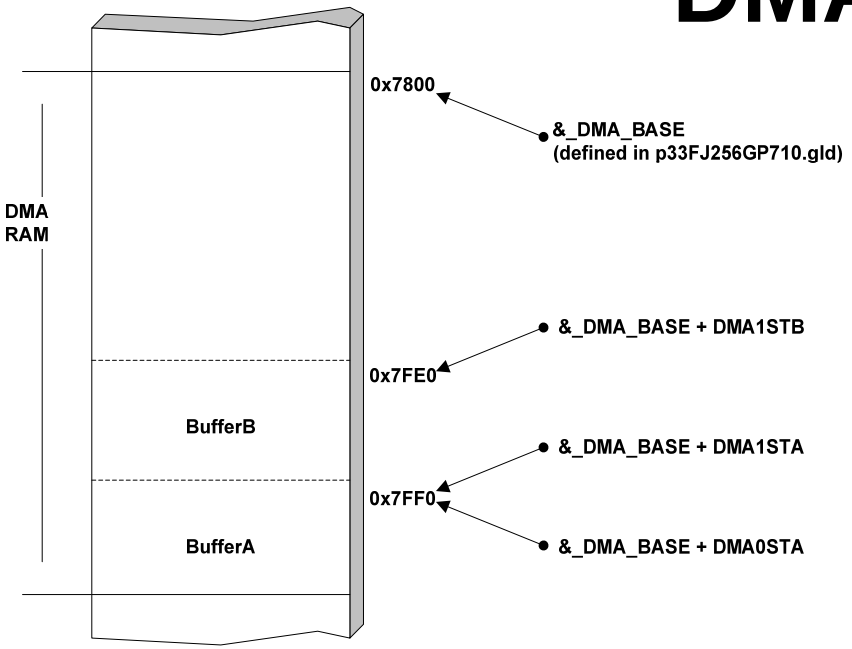




Example: Setup Primary and Secondary DMA Channel 4 buffers at 0x7800 and 0x7810

```
DMA4STA = 0x0000;
DMA4STB = 0x0010;
```

Step 3: MPLAB® IDE Support for DMA

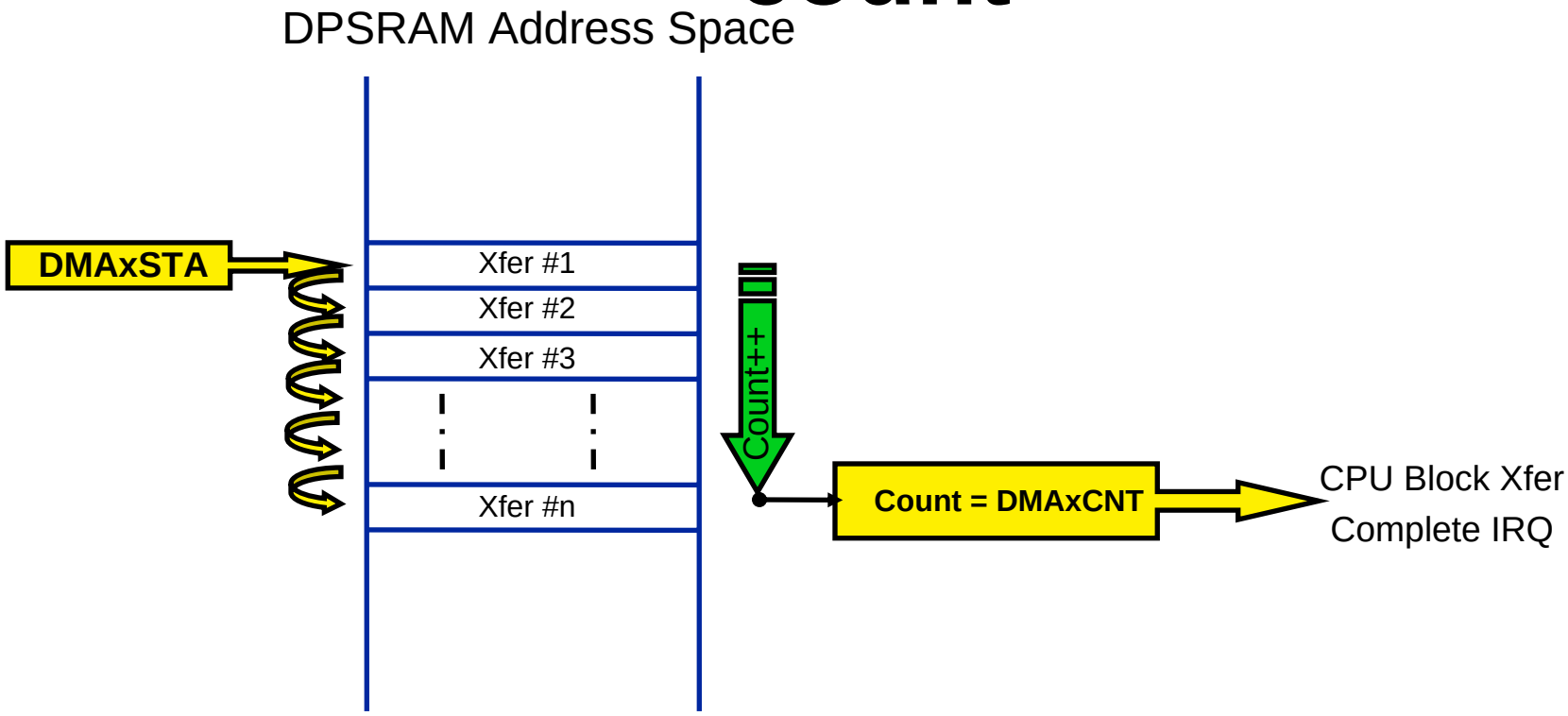


- Use __attribute__(space(dma)) and __builtin_dmaoffset()

Example: Allocate two buffers 8 words each in DMA memory for DMA Channel 1; Associate DMA Channel 0 with one of the buffers as well

```
unsigned int BufferA[8] __attribute__(space(dma));
unsigned int BufferB[8] __attribute__(space(dma));

DMA1STA = __builtin_dmaoffset(BufferA);
DMA1STB = __builtin_dmaoffset(BufferB);

DMA0STA = __builtin_dmaoffset(BufferA);
```

Step 4: Initialize DMA transfer count



Example: Setup DMA Channel 0 and 1 to handle 8 DMA requests

```
DMA0CNT = 7;   // 8 DMA Requests
DMA1CNT = 7;   // 8 DMA Requests
```

Step 5: Select appropriate DMA addressing and operating modes

- Word or byte size data transfers
- Peripheral to DPSRAM, or DPSRAM to peripheral transfers
- Post-increment or static DPSRAM addressing
- One-shot or continuous block transfers
- Interrupt the CPU when the transfer is half or fully complete
- Auto switch between two start addresses offsets (DMAxSTA or DMAxSTB) after each transfer complete ('ping-pong' mode)
- Peripheral indirect addressing
- Null data write mode
- Manual Transfer mode

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DMA Modes: Size and Direction

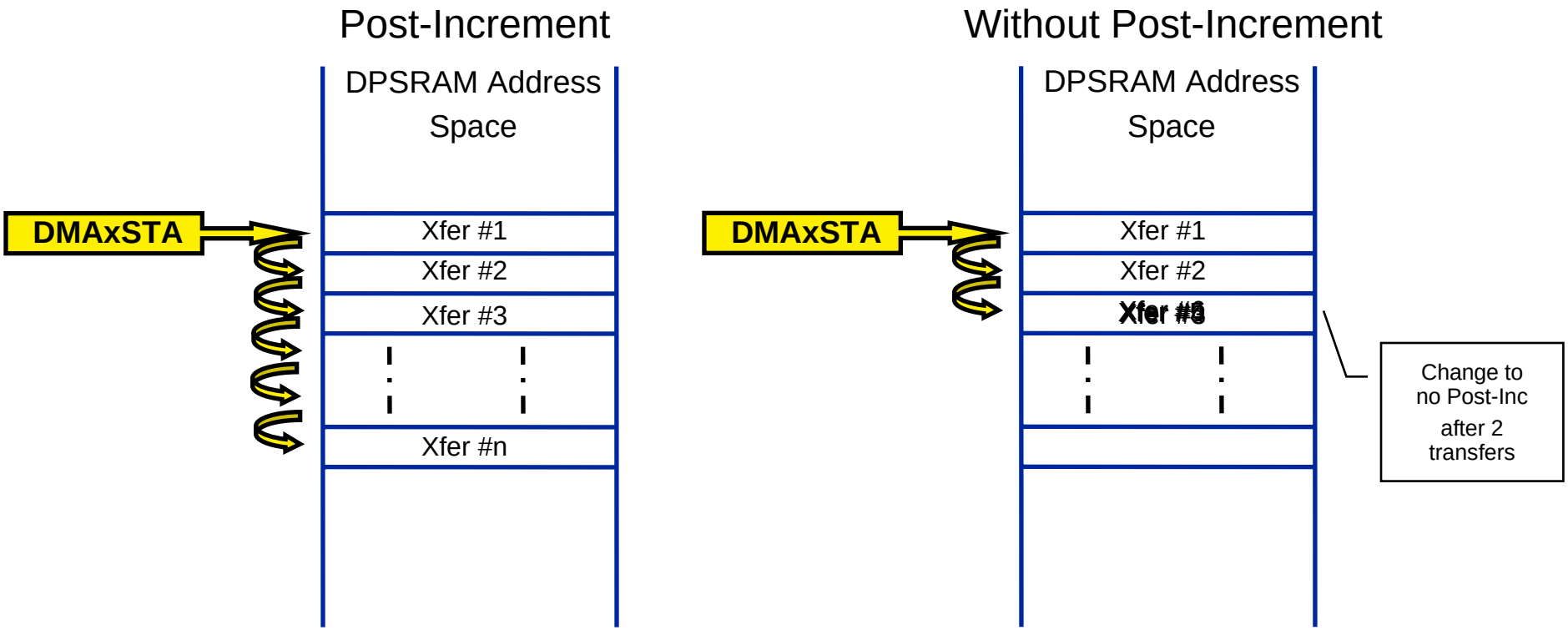
- Word or byte size data transfers
- Peripheral to DPSRAM, or DPSRAM to peripheral transfers

Example: Setup DMA Channel 0 and Channel 1 to transfer words to and from peripheral respectively

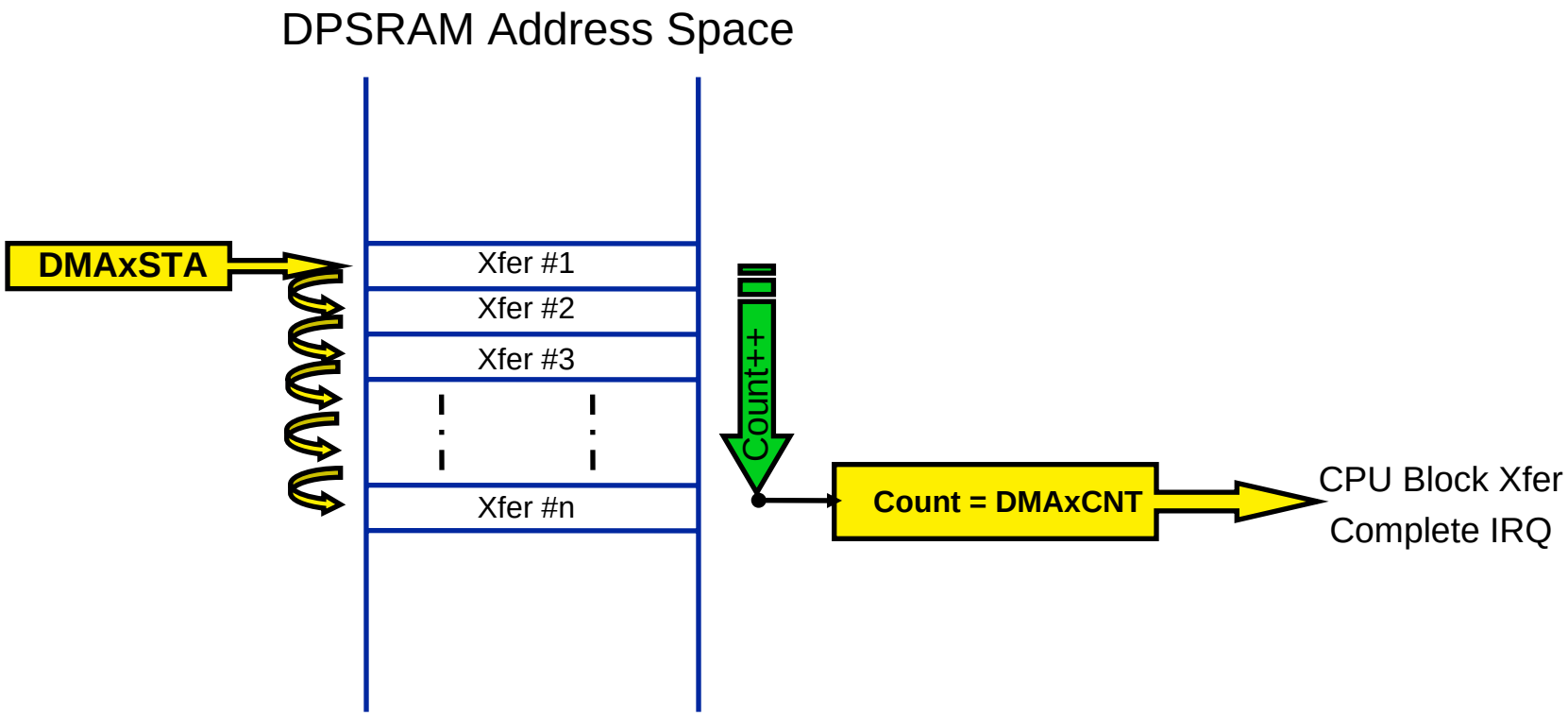
```
DMA0CONbits.SIZE = 0;   // Word transfers
DMA0CONbits.DIR  = 1;   // RAM-to-Peripheral direction

DMA1CONbits.SIZE = 0;   // Word transfers
DMA1CONbits.DIR  = 0;   // Peripheral-to-RAM direction
```

DMA Modes: Register Indirect Addressing

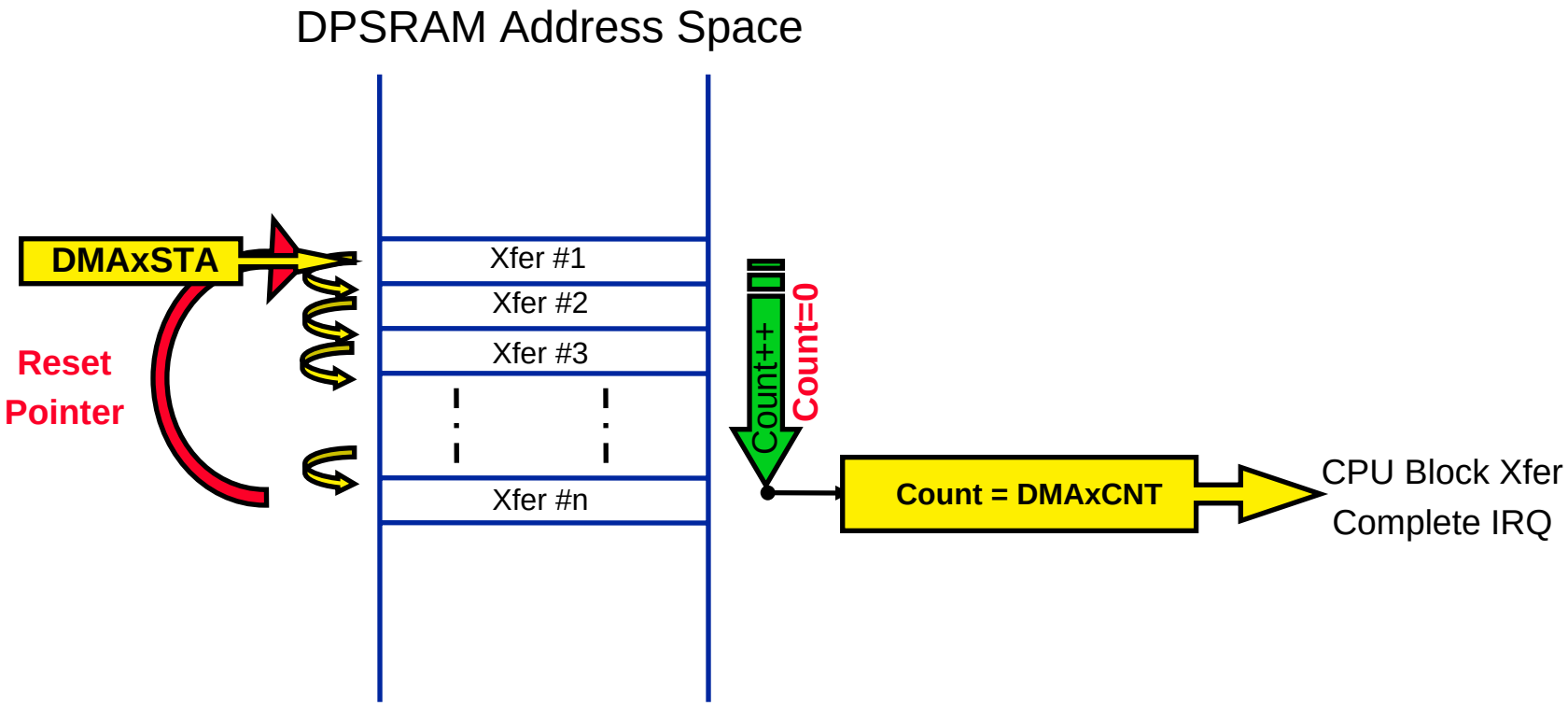


DMA Modes: One-Shot



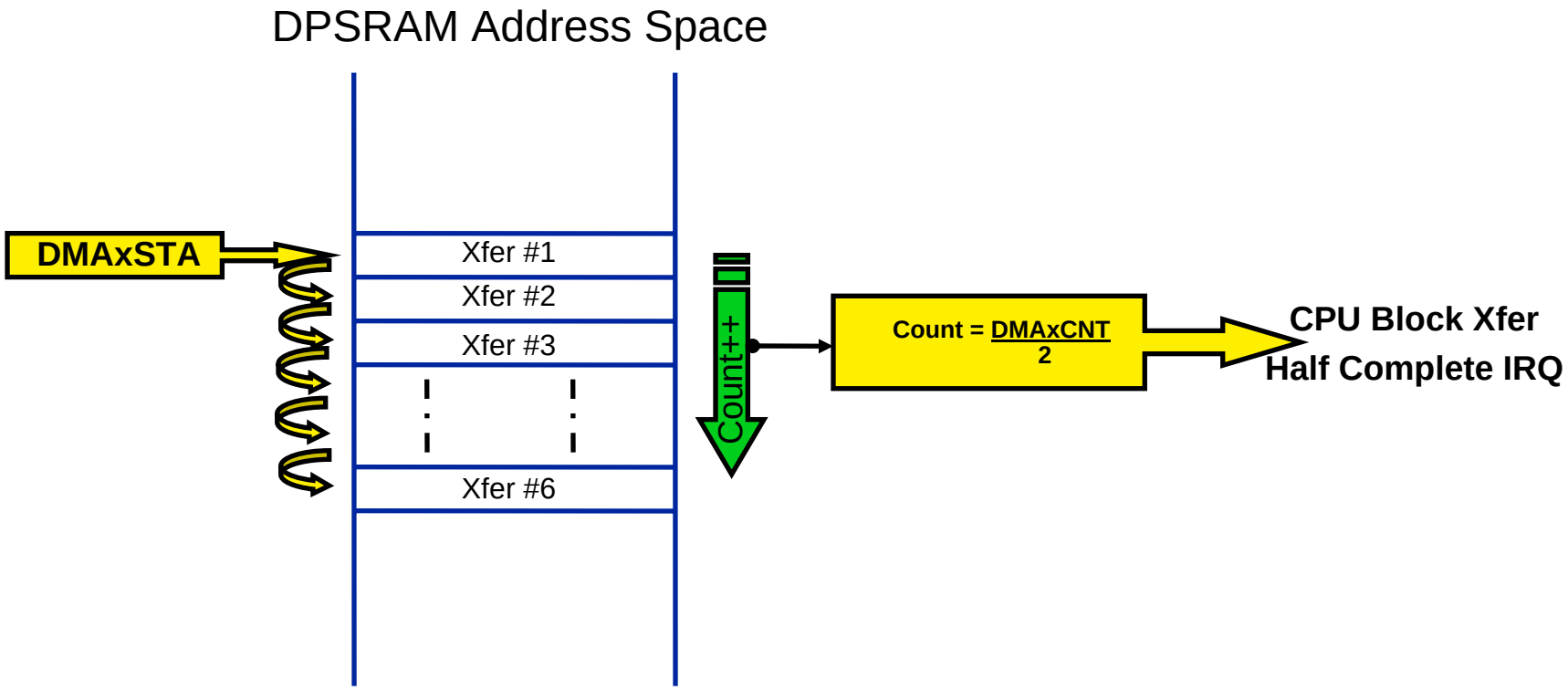
- Move 1 block of data then disable channel

DMA Modes: Continuous



- Move a block of data then automatically configure channel ready to repeat transfer

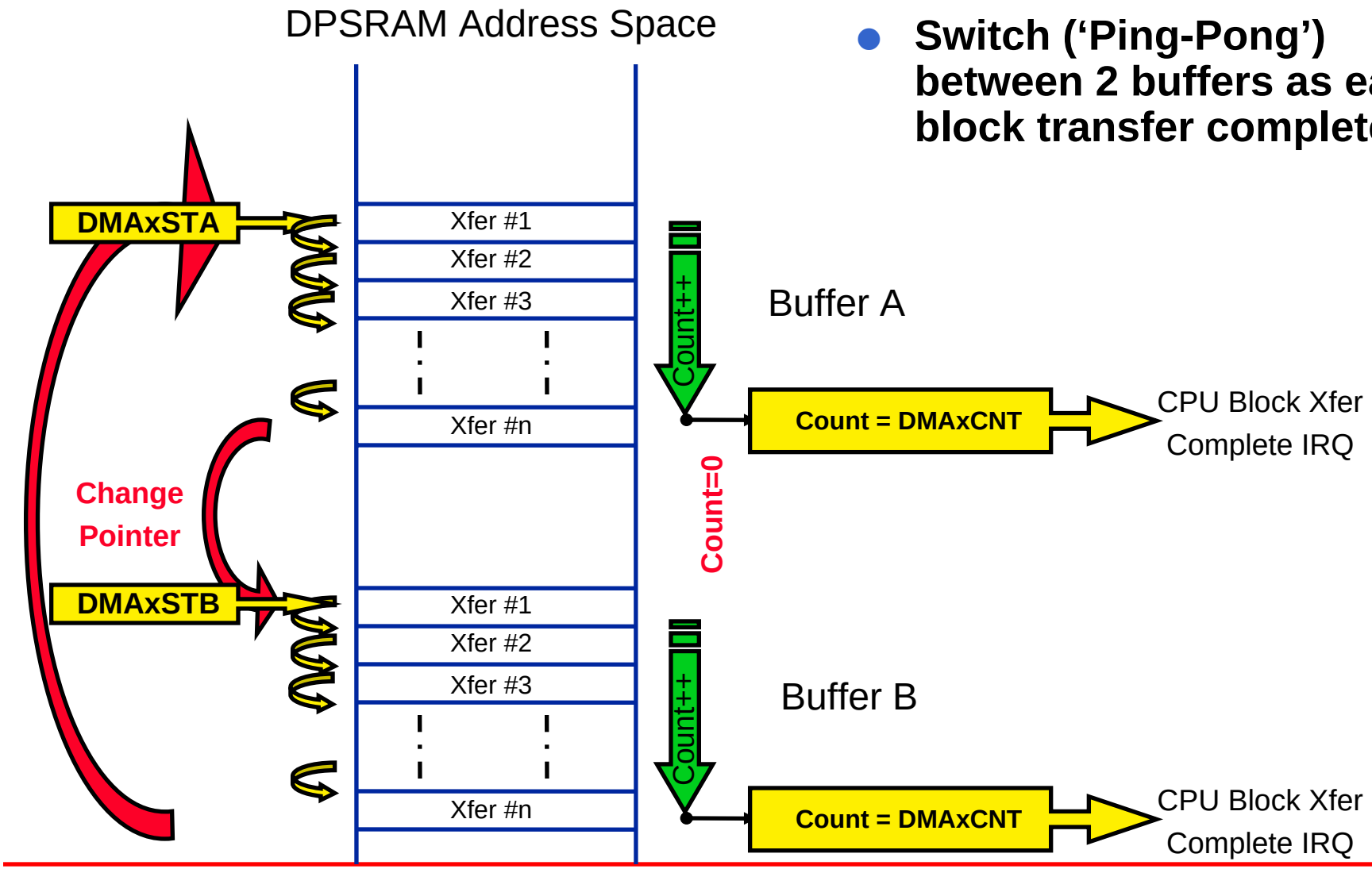
DMA Modes: Half or Full Transfer



- Move ½ block of data then issue interrupt
- Continue moving second ½ block of data

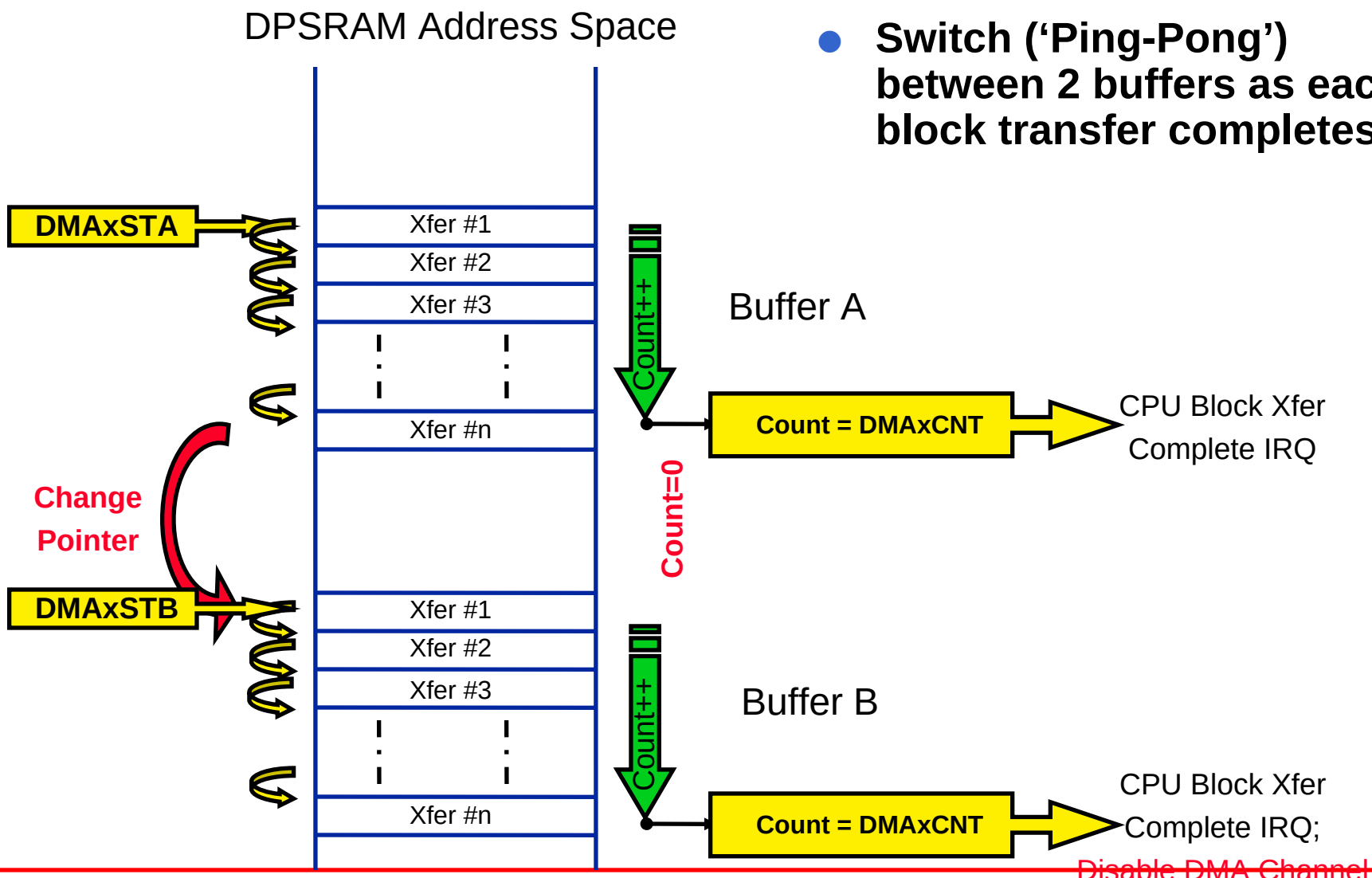
DMA Modes: 'Ping-Pong' and Continuous

- **Switch ('Ping-Pong') between 2 buffers as each block transfer completes**



DMA Modes: 'Ping-Pong' and One-Shot

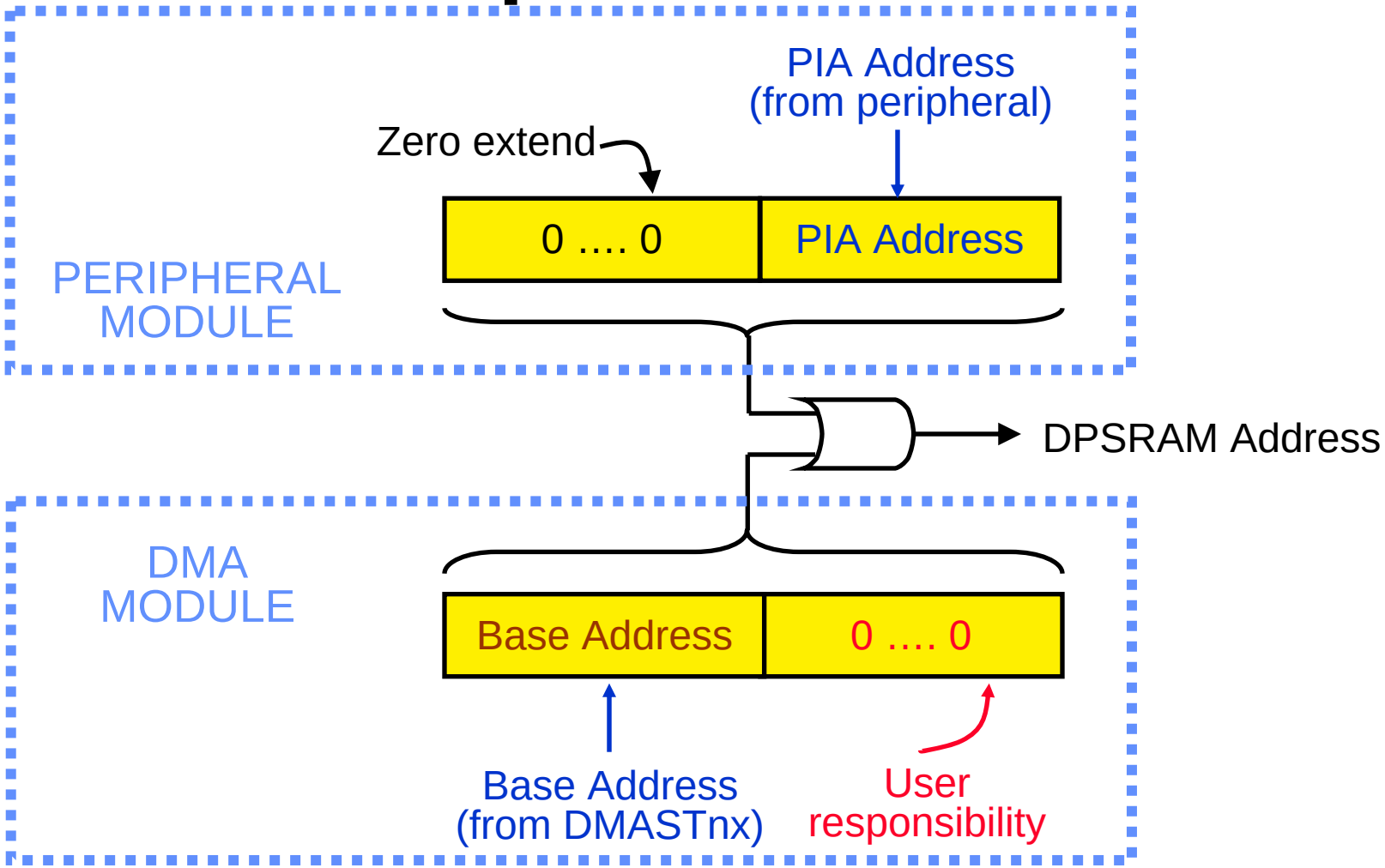
- **Switch ('Ping-Pong') between 2 buffers as each block transfer completes**



DMA Modes: Peripheral Indirect

- Least significant bits of address supplied by DMA request peripheral
- Allows ‘scatter/gather’ addressing schemes to be tailored to the needs of each peripheral

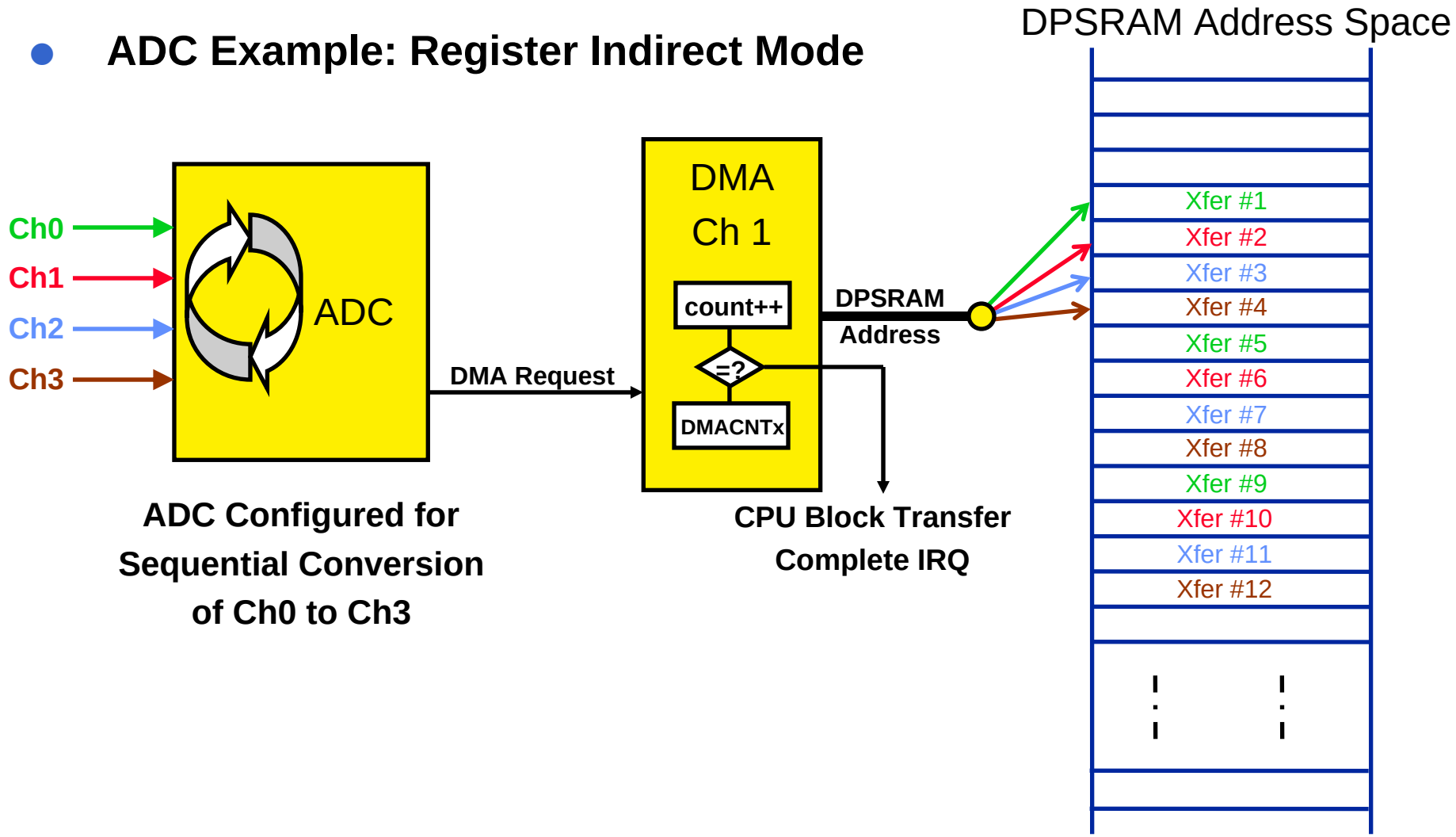
DMA Modes: Peripheral Indirect



- PIA Mode is also compatible with Auto-Repeat and 'Ping-Pong' modes

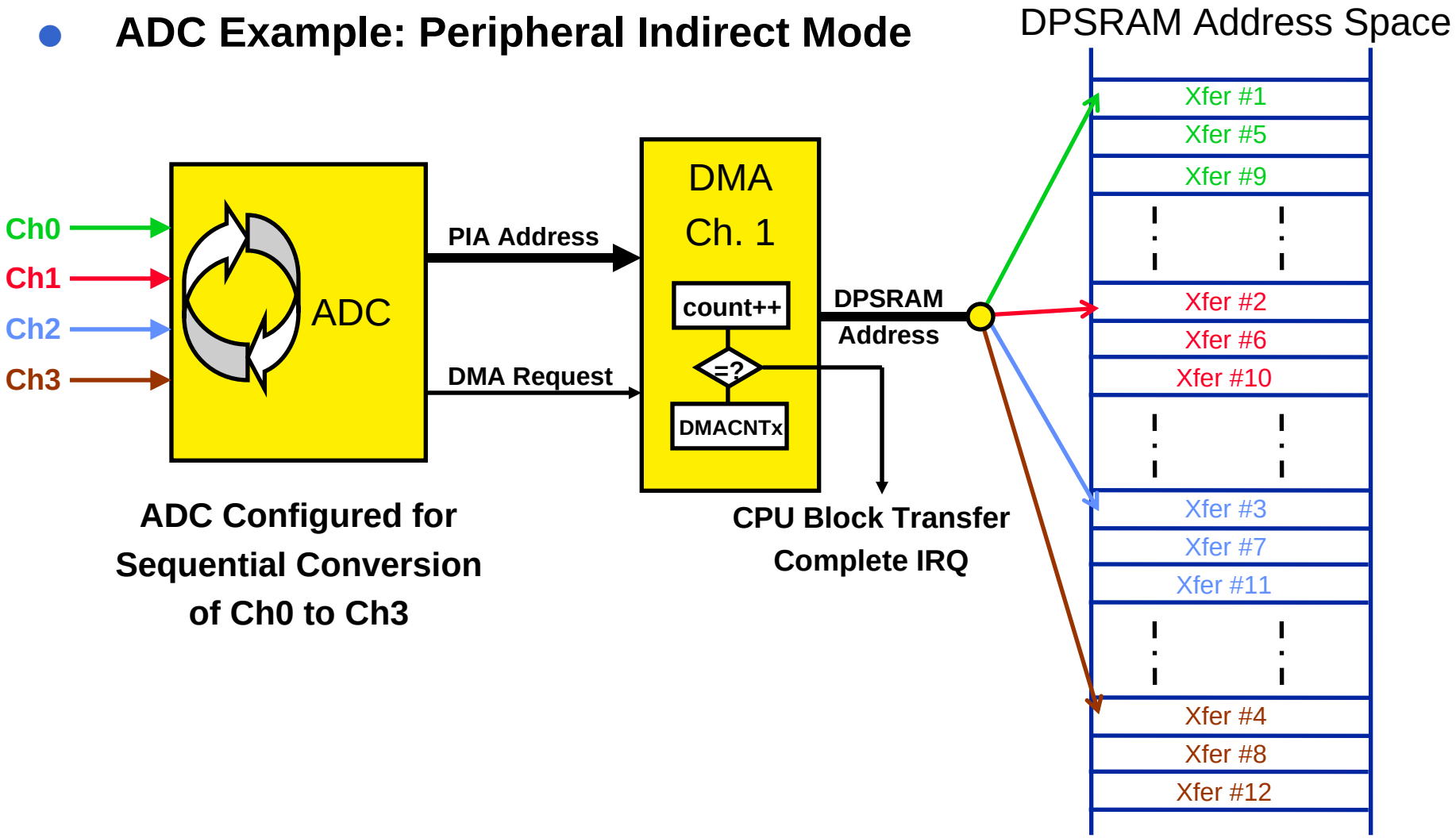
DMA Modes: Peripheral Indirect

- **ADC Example: Register Indirect Mode**



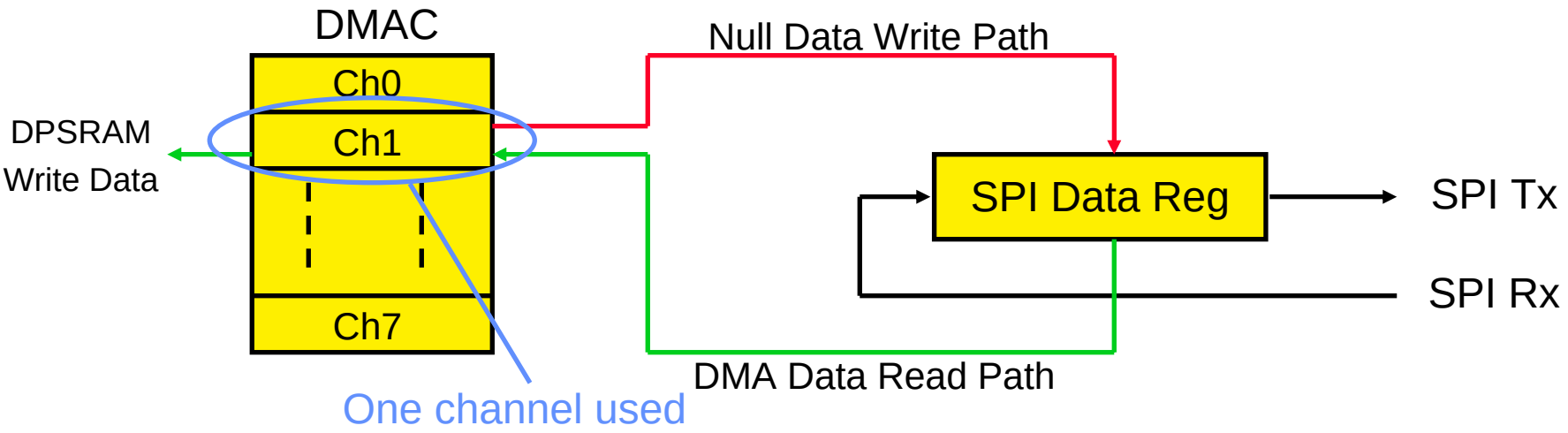
DMA Modes: Peripheral Indirect

- **ADC Example: Peripheral Indirect Mode**



DMA Modes: Null Data Write

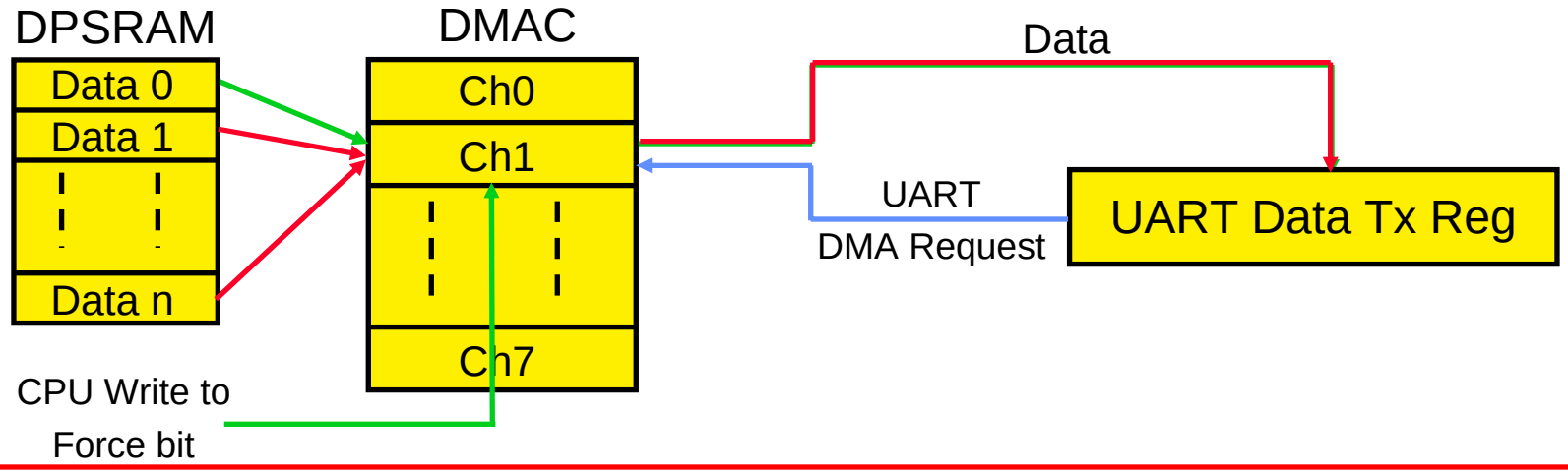
- **SPI has a single peripheral read/write data address**
  - Requires that data be transmitted (written) in order for external data to be received (read)
  - If only data reception required, “null” (zero) write necessary



- **“Null write” mode simplifies DMAC operation with SPI**
  - Automatically writes null (zero) data to peripheral data register after each DMA read
  - Avoids wasting another channel for null write

DMA Modes: Manual Transfer

- **Provides a means to start a DMA transfer using software**
  - Setting the FORCE bit in the selected DMA channel mimics a DMA request
- **Useful for sending the first element from a block of data to a serial peripheral (e.g. UART)**
  - Starts the sequence of DMA request to load data into a peripheral
  - When peripheral data buffer is empty (data sent), peripheral will issue a DMA request for the next data element



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DMA Modes: Examples

Example: Configure DMA Channel 0 for: One-Shot,
Post-Increment,
RAM-to-Peripheral,
Single Buffer

```
DMA0CONbits.AMODE = 0;   // Register Indirect with Post-Increment
DMA0CONbits.MODE  = 1;   // One-Shot, Single Buffer
DMA0CONbits.DIR   = 1;   // RAM-to-Peripheral direction
```

Example: Configure DMA Channel 1 for: Continuous,
Post-Increment,
Peripheral-to-RAM
Ping-Pong

```
DMA1CONbits.AMODE = 0;   // Register Indirect with Post-Increment
DMA1CONbits.MODE  = 2;   // Continuous, Ping-Pong
DMA1CONbits.DIR   = 0;   // Peripheral-to-RAM direction
```

DMA Interrupts

- **Transfer Complete Interrupt**
- **Write Collision Interrupt (DMA Trap)**
  - Should never happen but if they do, handled robustly
  - CPU will win; DMAC write ignored
  - Cause DMA Fault trap and set channel write collision flag

Example: Enable and process DMA Channel 0 and 1 interrupts

```
IFS0bits.DMA0IF  = 0;              // Clear DMA 0 Interrupt Flag
IEC0bits.DMA0IE  = 1;              // Enable DMA 0 interrupt
IFS0bits.DMA1IF  = 0;              // Clear DMA 1 interrupt
IEC0bits.DMA1IE  = 1;              // Enable DMA 1 interrupt

void __attribute__((__interrupt__)) _DMA0Interrupt(void)
{
      /* Process DMA Channel 0 interrupt here */
      IFS0bits.DMA0IF = 0;         // Clear the DMA0 Interrupt Flag
}
void __attribute__((__interrupt__)) _DMA1Interrupt(void)
{
      /* Process DMA Channel 1 interrupt here */
      IFS0bits.DMA1IF = 0;         // Clear the DMA1 Interrupt Flag
}
```

DMA Controller
Debug Support

- **2 DMA debug assist registers included**
  - DSADR<15:0> : Captures the DPSRAM address of the most recent DMA transfer
  - DMACS1 :
    - **LSTCH<2:0> : Captures the ID of the most recently active DMA channel**
    - **PPSTx : 'Ping-Pong' mode status bits, one per channel.**
      Indicates which buffer is active (A or B)

Lab 4

DMA

Lab 4 – Using DMA

- **Goals**
  - Learn DMA module
- **Lab**
  - Implement UART loop back utilizing DMA for receiving and transmitting
  - Receive and buffer 8 characters one at a time
  - Transmit all 8 characters back

Lab 4 – PIM Swap

- **Lab 4 uses the PIC33FJ256GP710**
- **To swap the processor:**
  - Disconnect Explorer 16 power and programmer connections
  - Remove PIC24FJ128GA010 PIM
  - Place PIC33FJ256GP710 PIM on board, making sure to properly align the notched corner
  - Reconnect Power and programmer

Summary

- We learned how to use some of the new peripherals onboard the 16-bit devices
- We used the Microchip Development Tools Suite for developing with the 16-bit PIC® MCUs
- We became familiar with some of the PIC24 and dsPIC33 documentation

Development Tools Used

- **MPLAB® REAL ICE™ Emulator**
  - DV244005

- **Explorer 16 with PIC24FJ128GA010 PIM & dsPIC33FJ256GP710 PIM**
  - DM240001

- **PIC24FJ64GA004 PIM**
  - DM240002 OR MA240013

References

- PIC24 & dsPIC33 Datasheet
- Explorer 16 User's Guide
- MPLAB® IDE
- C30 Compiler
- ICD2 In Circuit Debugger

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All Done!

Thank you all for attending

Please remember the evaluation sheets

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