11045 UB2

Full-Speed USB Hands-On Training

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Prerequisites

Working knowledge of:

- **PIC18 family of microcontrollers**
- **MPLAB® IDE**
- **C Programming Language**

This training assumes you are familiar with basic USB terminology and concepts

Objectives

Upon completion, participants will:

- Get a hands-on experience in creating USB applications

- Be aware of the factors important in designing USB applications

Agenda

Checking your work station…

Quick USB Review

Demonstration - Microchip USB Solutions

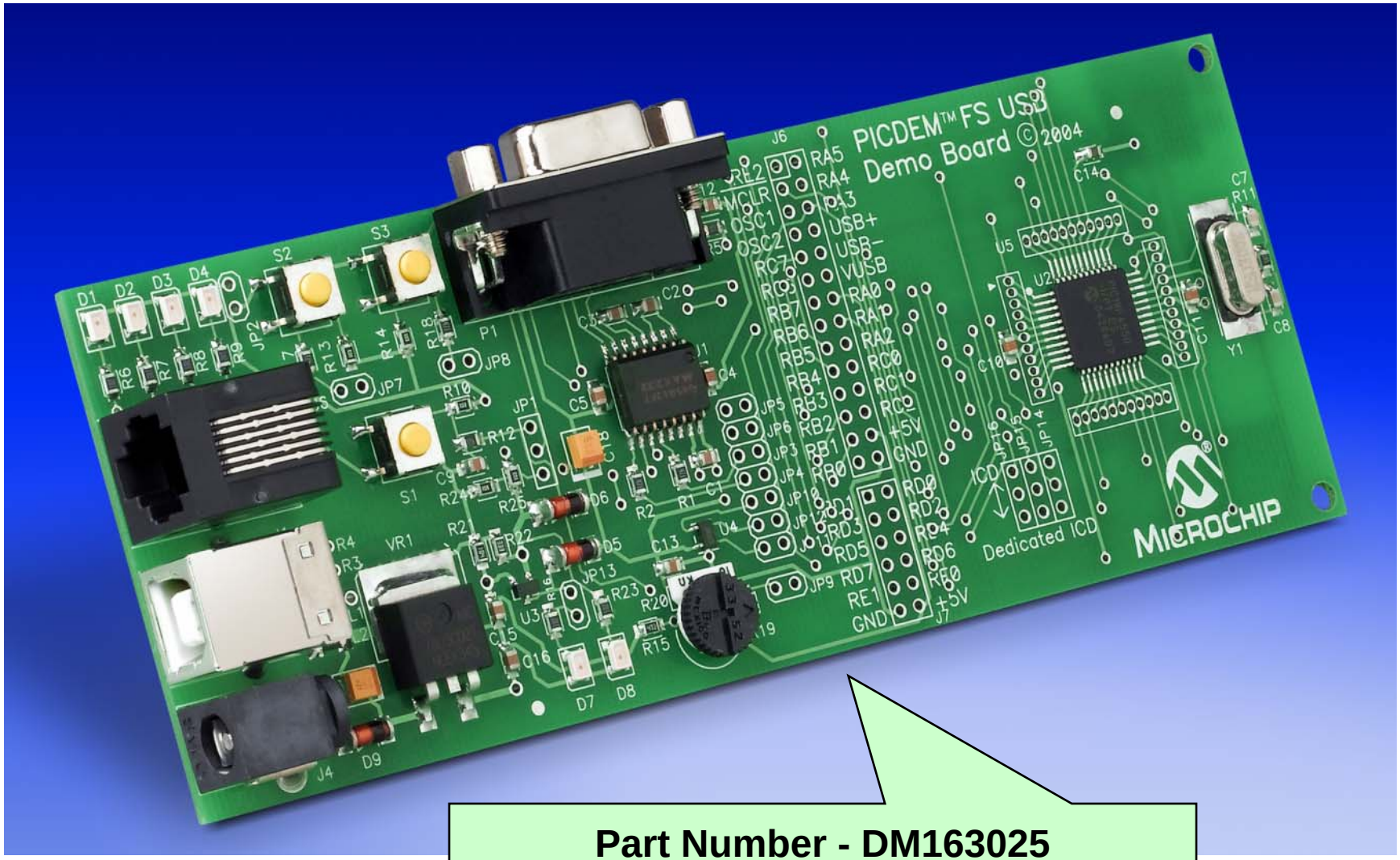
Exercise Group 1: **Your turn to play!**

Exercise Group 2: **CDC RS-232 Emulation APIs**

Exercise Group 3: **Custom Class using Microchip General Purpose USB Windows Driver**

Wrapping up and Q&A

PICDEM™ FS USB Demo Board



Part Number - DM163025

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Literature Check…

Three documents:

- **PIC18F4550 family data sheet**
- **Application Note 956**
- **PICDEM™ FS USB Demo Board User's Guide**

Please *DO NOT* remove these documents from the classroom. Your fellow attendees will need them in the next session!

Thank you for your cooperation!

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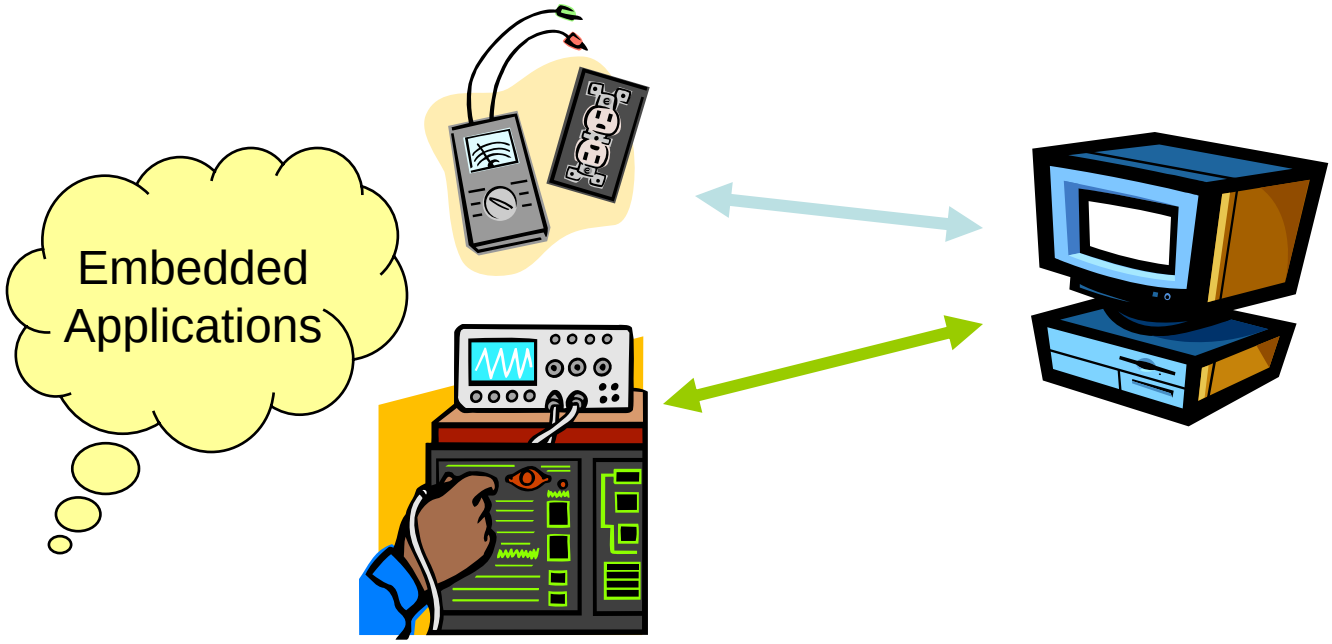
Quick USB Review

Understanding of the following concepts is important in making USB design choices

We will briefly cover materials on:

- **USB in Embedded Applications**
- **Vendor ID (VID) & Product ID (PID)**
- **Device Classes**

Universal Serial Bus



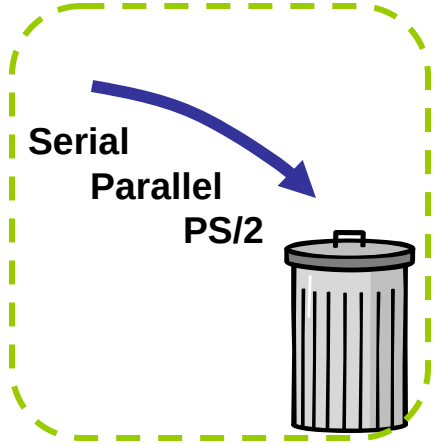
Computer is great

Processing power!

Data Analysis, Data Logging, Firmware Updates, Diagnostic

- **Auto detection & configuration (Plug&Play)**
- **Easy expansion using hubs**
- **Bus power**

- **Three speeds:**
  Low- 1.5, Full- 12, High- 480 Megabits / second



Vendor ID & Product ID

Vendor ID (VID) *16-bit number*

- Required to market your product
- http://www.usb.org/developers/vendor/
- USD $2,000
- Technical & Legal trouble if not using your own VID

Product ID (PID) *16-bit number*

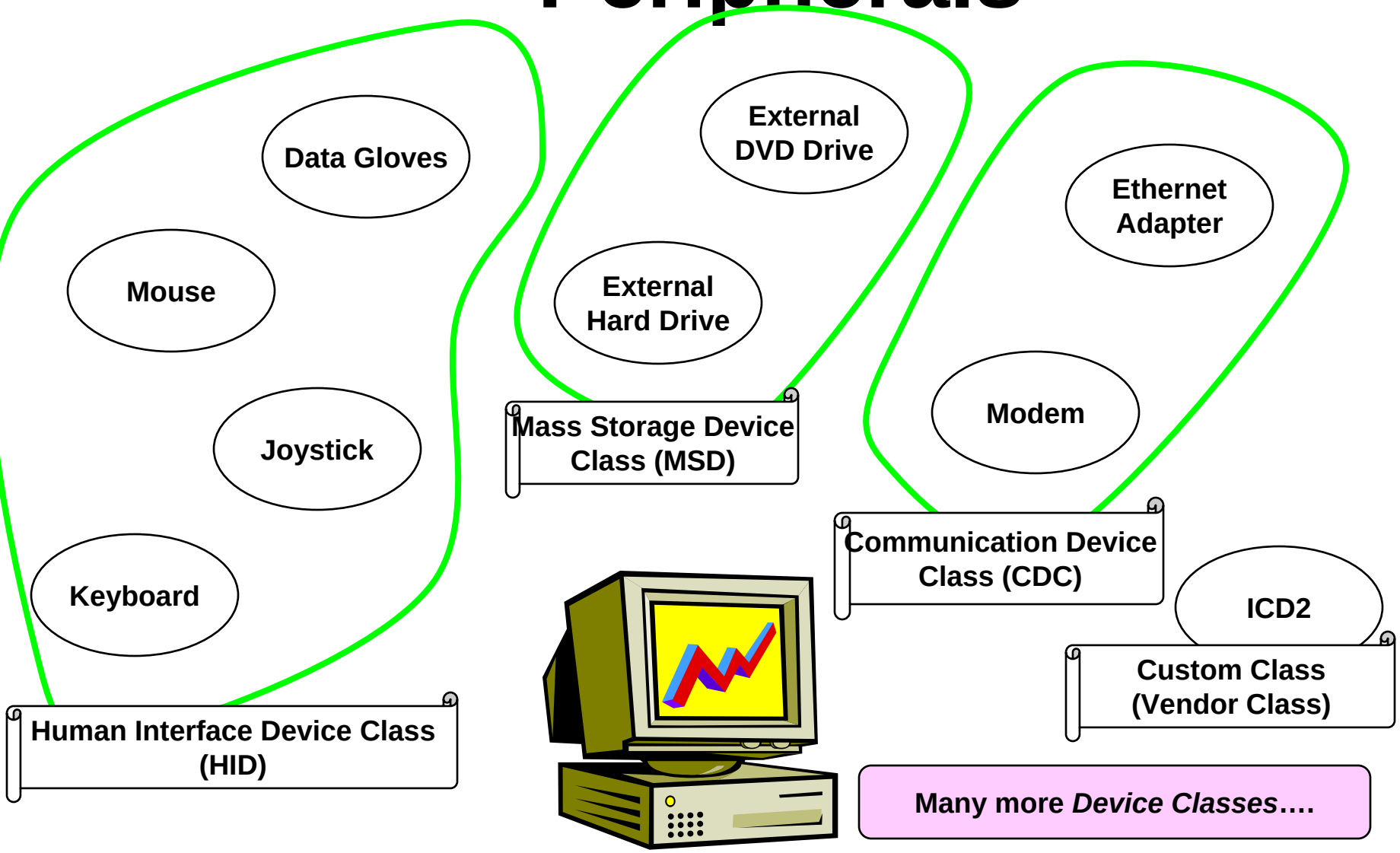
- Microchip's Sub-licensing Program

Every product is required to have a unique combination of VID and PID

Compliance Testing

- Must pass to use USB logo
- USD $1,500

Categorizing USB Peripherals



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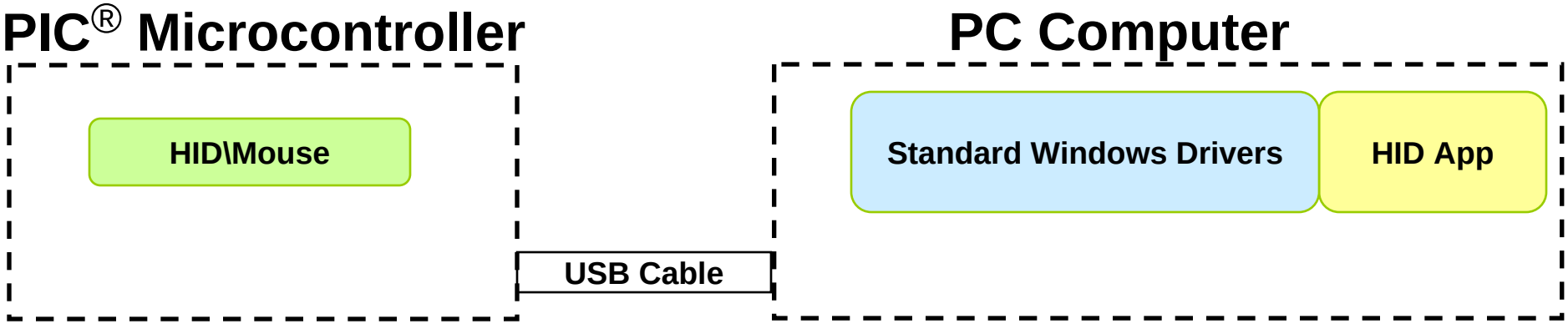
Human Interface Device (HID)

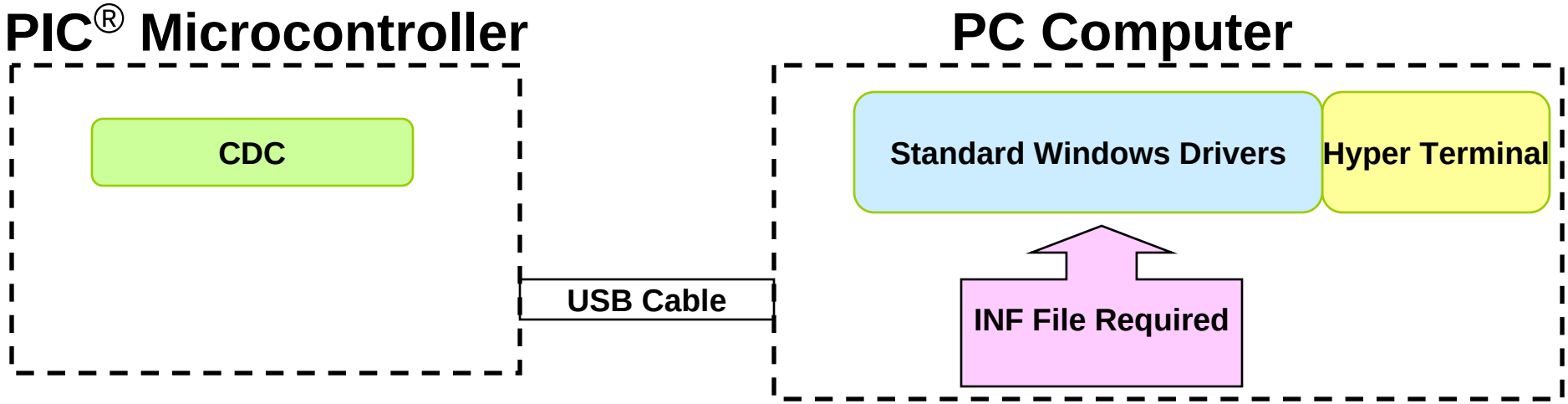


Design Considerations:

- § 64 KB/s max
- § Interrupt Transfer Type
- § Standard Windows driver
- § Custom PC application can access HID data through Win32 APIs

PICkit™ 2 Kit Uses HID Class!

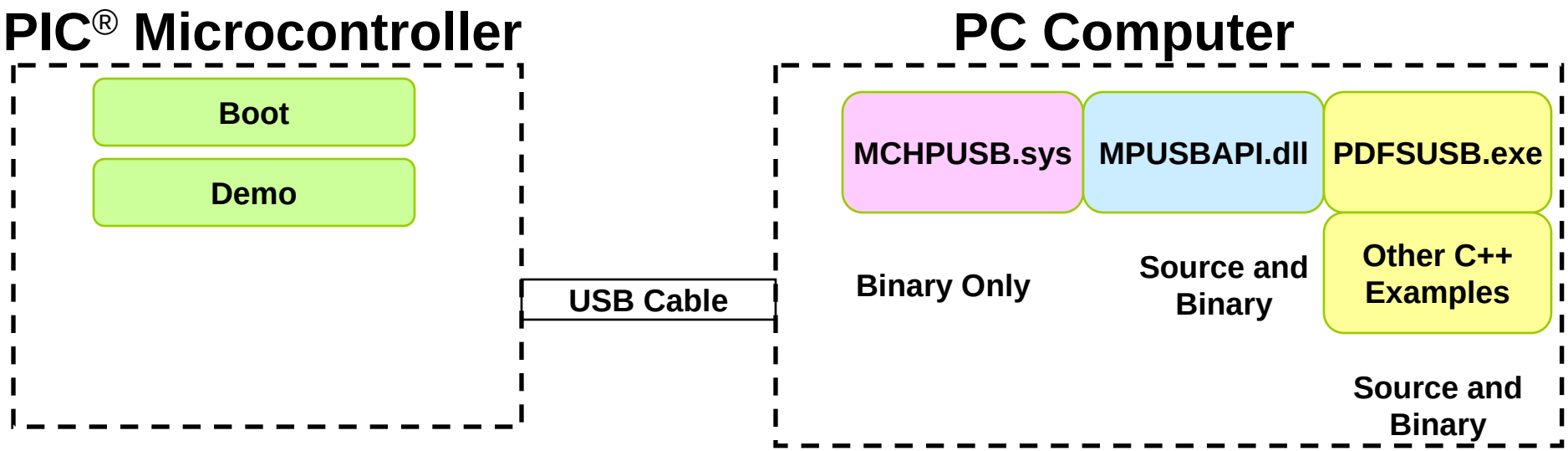
CDC - RS-232 Emulation



Design Considerations:

- ~80 KB/s max
- PC applications can access the device as though it is connected to a serial COM port

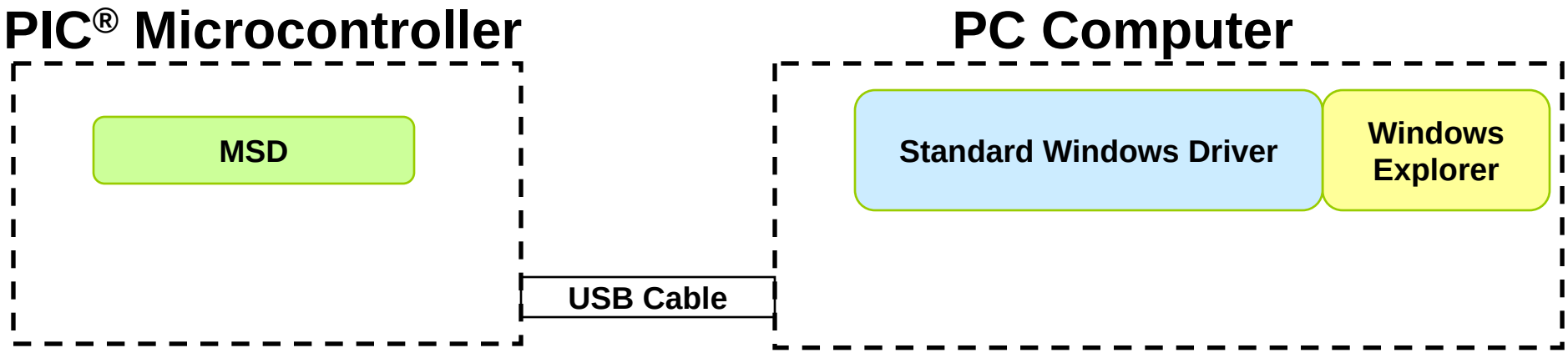
General Purpose Driver



Design Considerations:

- § ~1,088 KB/s max
- § Very flexible
- § Not a standard Windows driver
- § PC programming is required

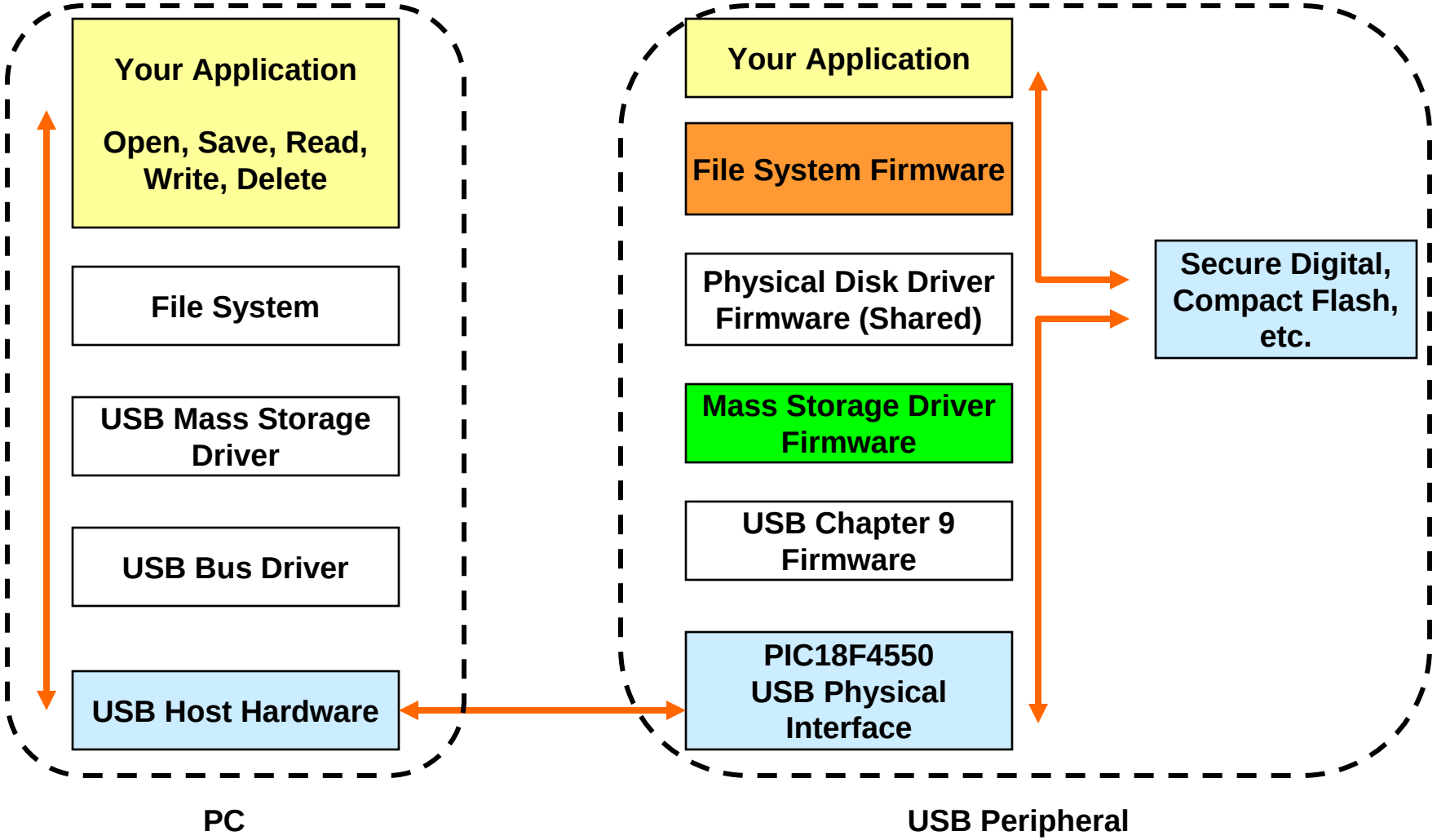
Mass Storage Device (MSD)



Design Considerations:

- Acts like a disk drive
- Fast data transfer over USB
- Speed is limited depending on the physical media interface
- For usefulness, a File System should also be implemented in firmware

Typical MSD Application



What Does Your Application Need?

HID

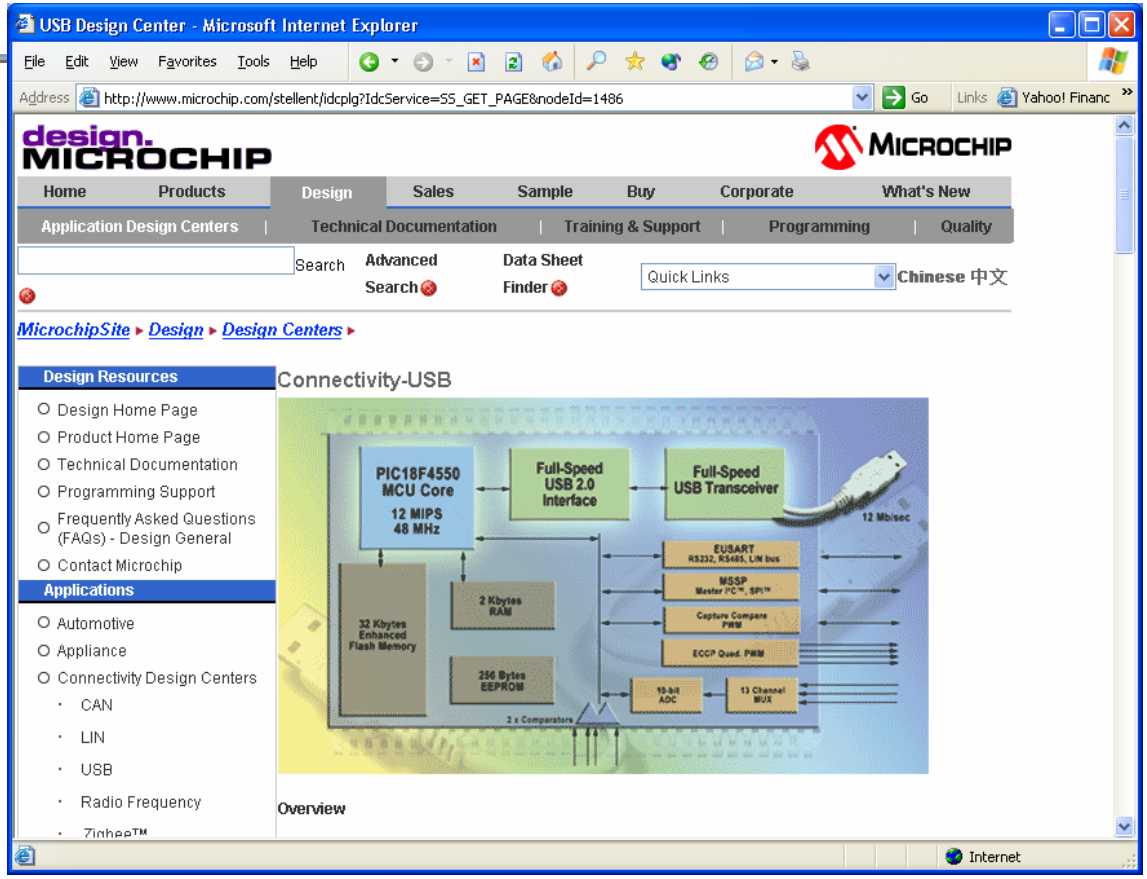
CDC – RS-232 Emulation

General Purpose

MSD

Others..?

Software Package



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Wrapping up and Q&A

Exercise Group 1: Your turn to play!

At this point, 35-40 minutes should have lapsed

Exercise Group 1 should take approximately 30 minutes to complete

Exercise Group 1: Objectives

Familiarize you with the development environment

We will not be writing any code

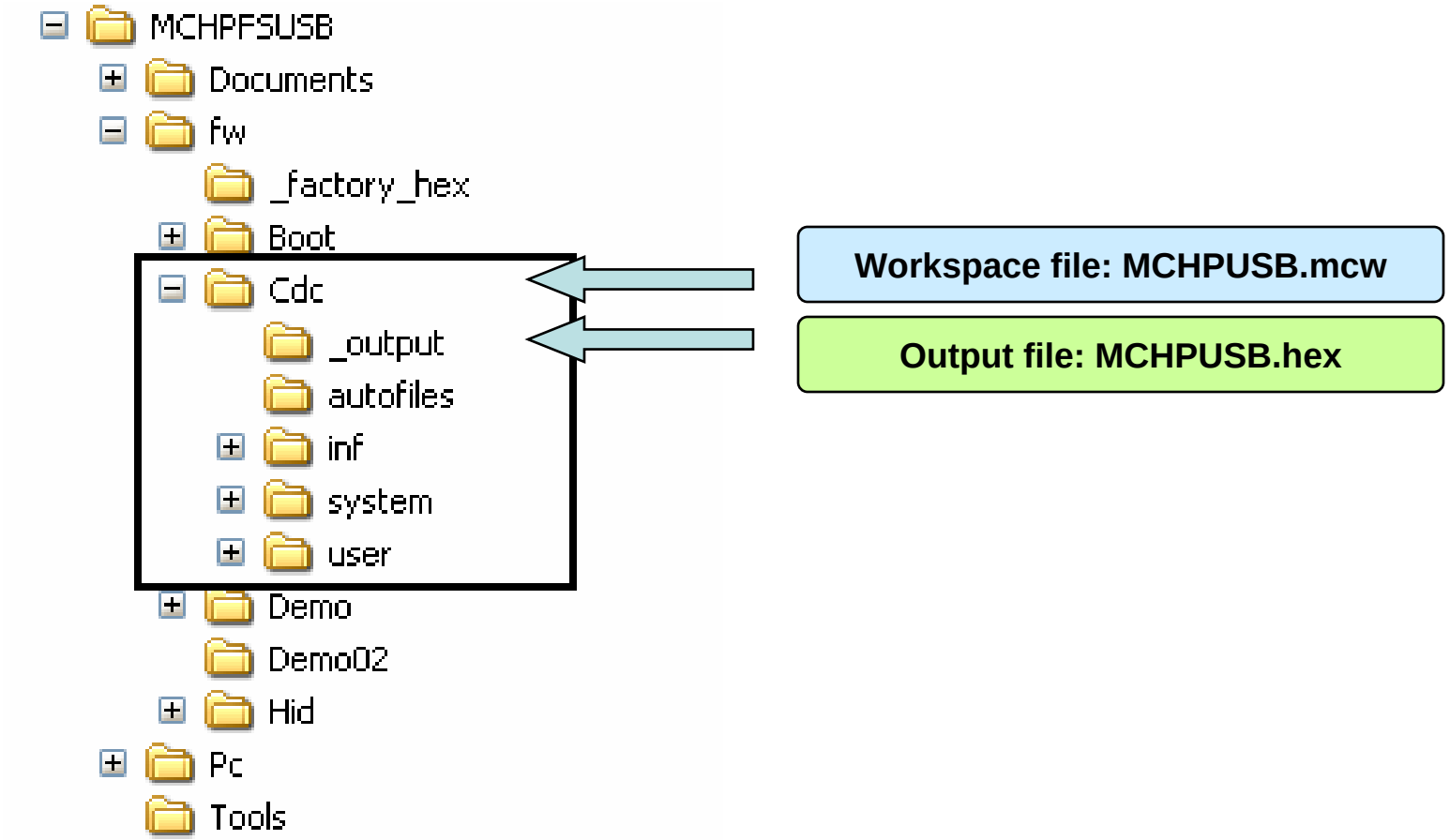
Just compiling, programming Flash memory, and playing with the default demonstration

Ex 1.1 General Purpose

Ex 1.2 Upload HID mouse example using the bootloader

Project Folder Structure

C:\MCHPFSUSB\



Ex 1.1 – General Purpose Driver Demo

- Launch MPLAB® IDE
- Import

- Select MPLAB ICD2 as a programmer
- Program the device
- Remove the 9 inch modular cable and follow instructions in Chapter 3 of the PICDEM™ FS USB User's Guide on how to run the demo

End of Ex 1.1

Ex 1.2 – Download HID Mouse Demo via a Bootloader

- Launch PDFSUSB.exe if you have not done so already
- Enter bootload mode by holding down push button S2 and hit S1 to reset
- Select Boot Mode Tab in PDFSUSB.exe
- Follow instructions in Chapter 3 of the User's Guide on how to download a hex file
- Download:

End of Ex 1.2

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Agenda

Checking your work station…

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Demonstration - Microchip USB Solutions

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Exercise Group 3: **Custom Class using Microchip General Purpose USB Windows Driver**

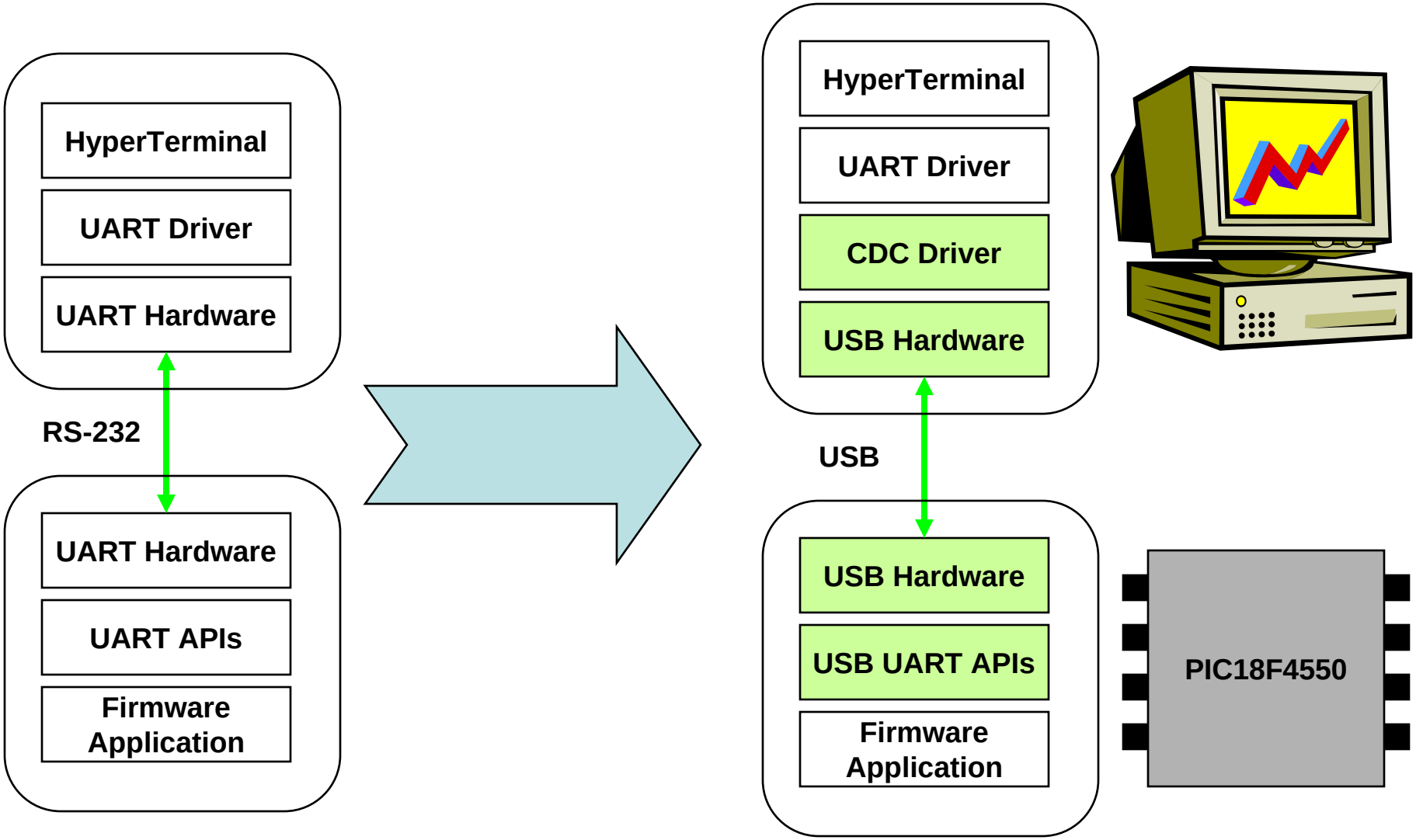
Wrapping up and Q&A

Exercise Group 2: Objectives

Learn how to use provided APIs to transfer data between a computer and the PIC18F4550

Be able to compile the project and download the hex file to program memory successfully

Migration Path



Opening CDC Project Workspace

If using an ICD 2...

Attach 9” Modular cable to the demo board

Attach USB cable to the demo board

Select “File/Open Workspace…”

Open project “C:\MCHPFSUSB\fw\CDC\MCHPUSB.mcw”

Do not do anything else just yet

Configuration Bits

FS USB Clock Source: Clock src from 96 MHz PLL/2

CPU Sys Clk Postscaler: [OSC1/OSC2 Src: /1][96MHz PLL Src: /2]

96MHz PLL Prescaler: Div by 5 {20 MHz input}

Oscillator: HS: HS+PLL, USB-HS

USB Voltage Regulator: Enabled

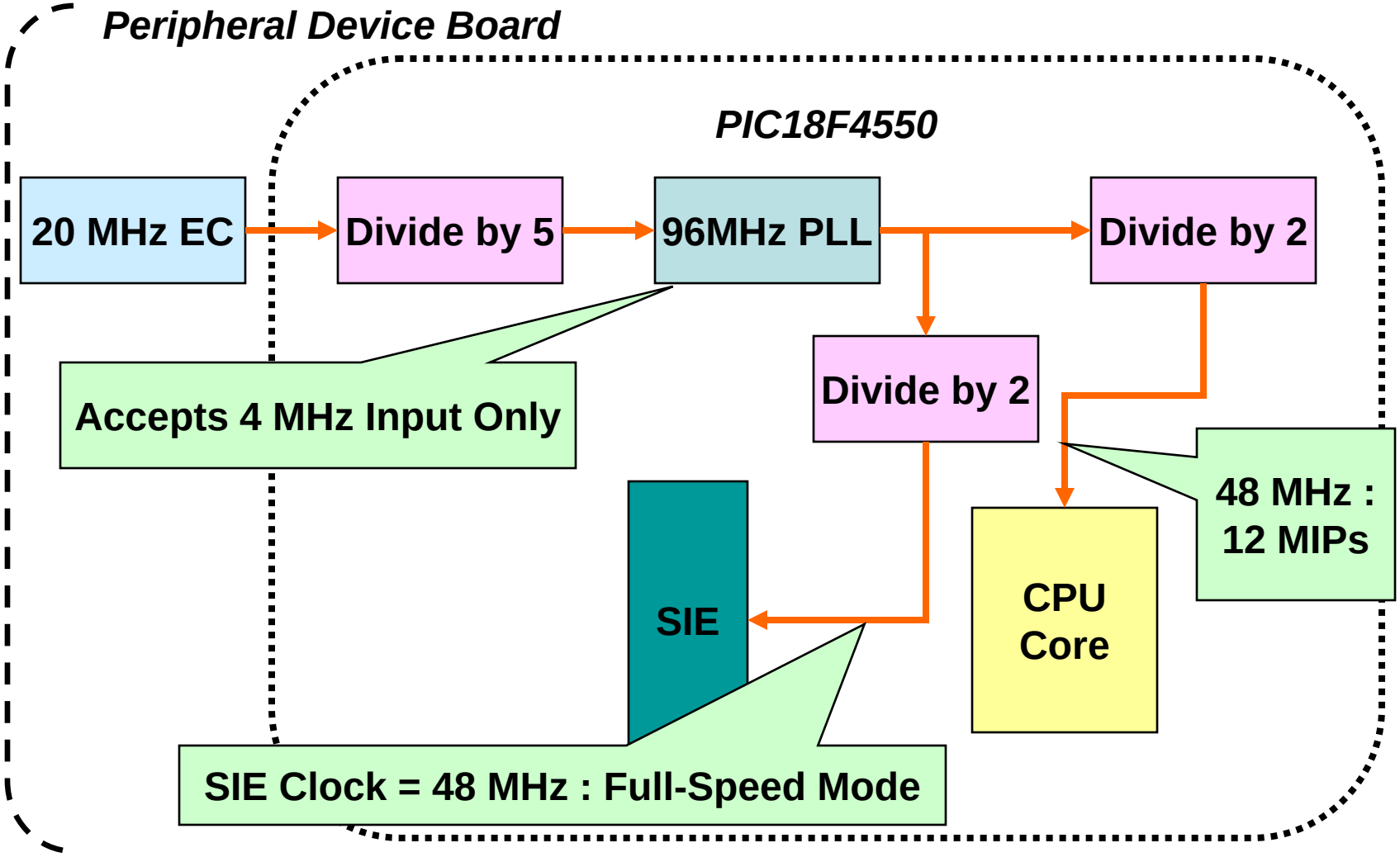
Watchdog Timer: Disabled

PortB A/D Enable: configured as digital I/O on RESET

Low Voltage Program: Disabled

The only file you will need to modify is user.c

Clock Configuration Example



Running the Default Code

- Press F10 to compile project
- Select “Programmer\Select Programmer” and make sure that MPLAB® ICD2 is selected
- Select “Programmer\Program” to download the code to the microcontroller
- Do not disconnect 9” Modular cable just yet

Device Manager

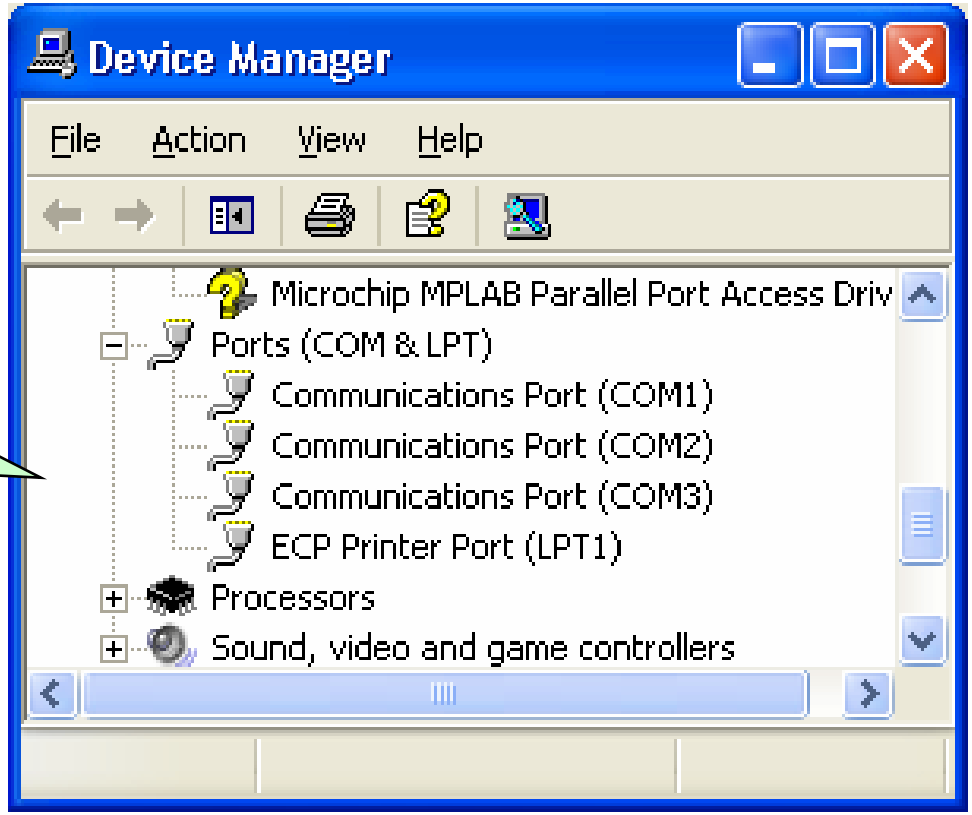
- Open “Device Manager” and take a look at the “Ports (COM & LPT)” category
- Observe how many COM ports are currently there on your computer

Device Manager

Now disconnect the 9” modular cable

The device should be detected by Windows

You should see an additional ‘virtual’ COM port. Remember the number of the COM port



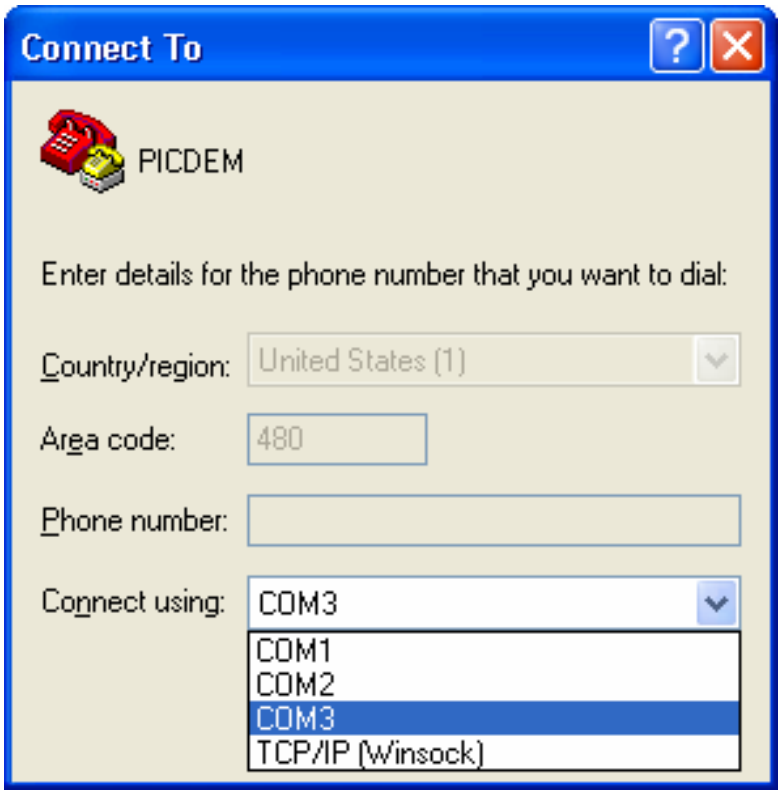
Using HyperTerminal

Launch HyperTerminal

Type in a name for a new connection, and hit “OK”

HyperTerminal: Connect To

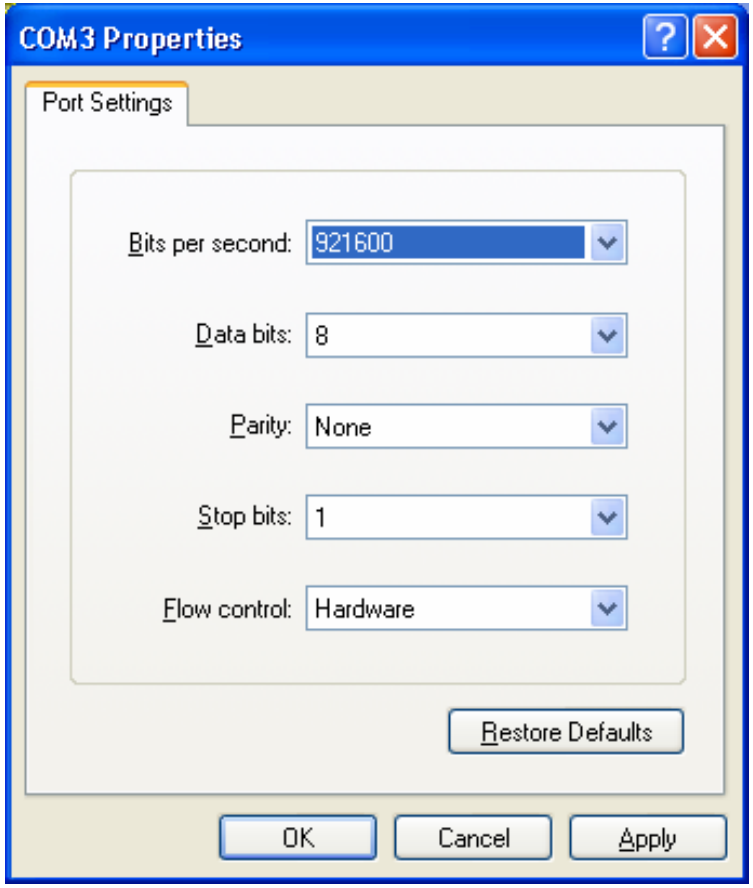
Select the new COM port that was added during USB CDC installation and hit "OK"



HyperTerminal: COM Properties

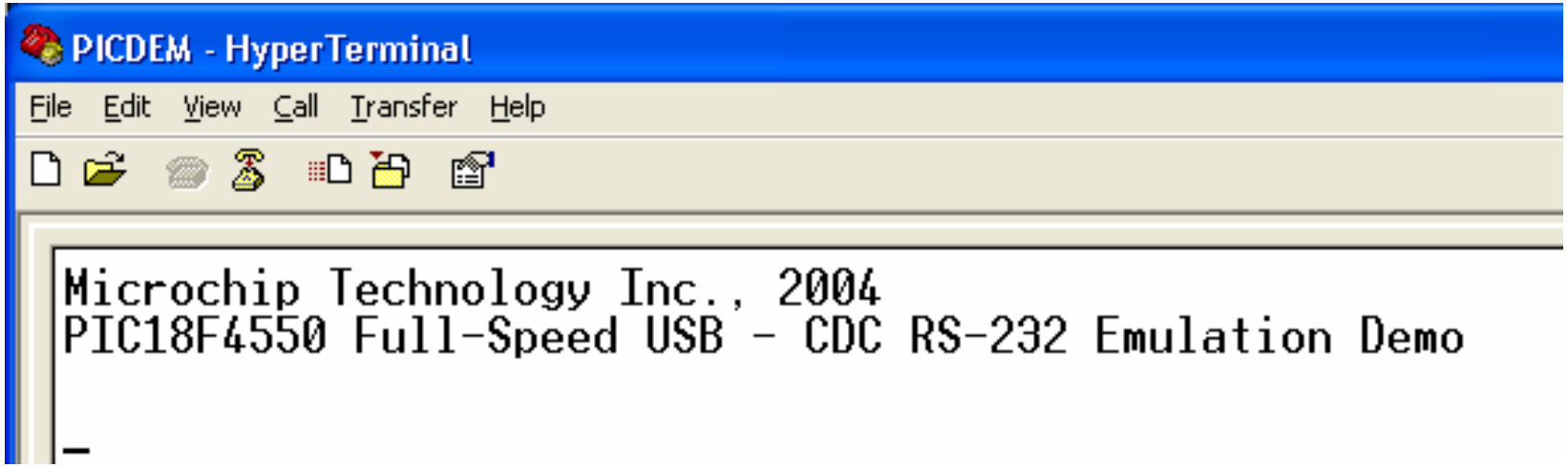
Hit “OK”

Terminal is now ready



HyperTerminal: First Use

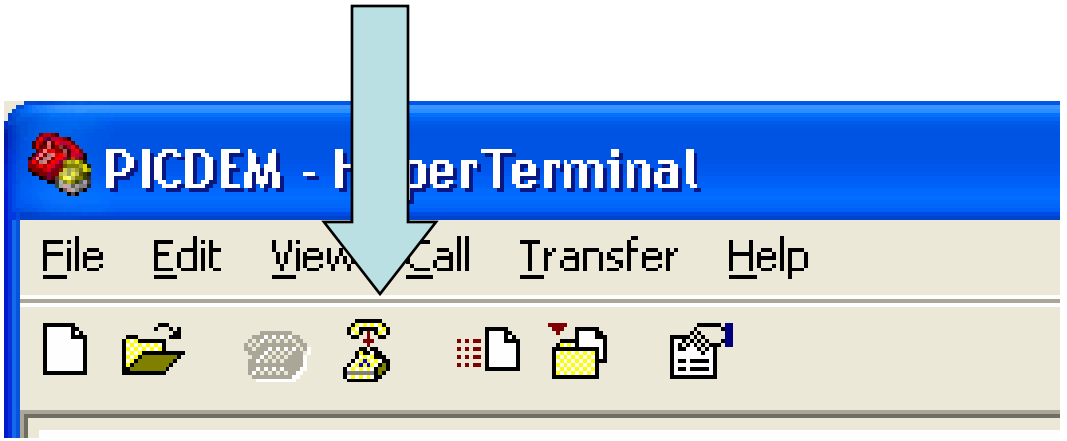
Now, hit switch 2 on the demo board, you should see the message below…



HyperTerminal: Important Note

Before physically disconnecting a USB device, you must hang up the connection first, otherwise, the program must be closed and opened again the next time a USB device is connected.

Let's take a look at the APIs



CDC APIs

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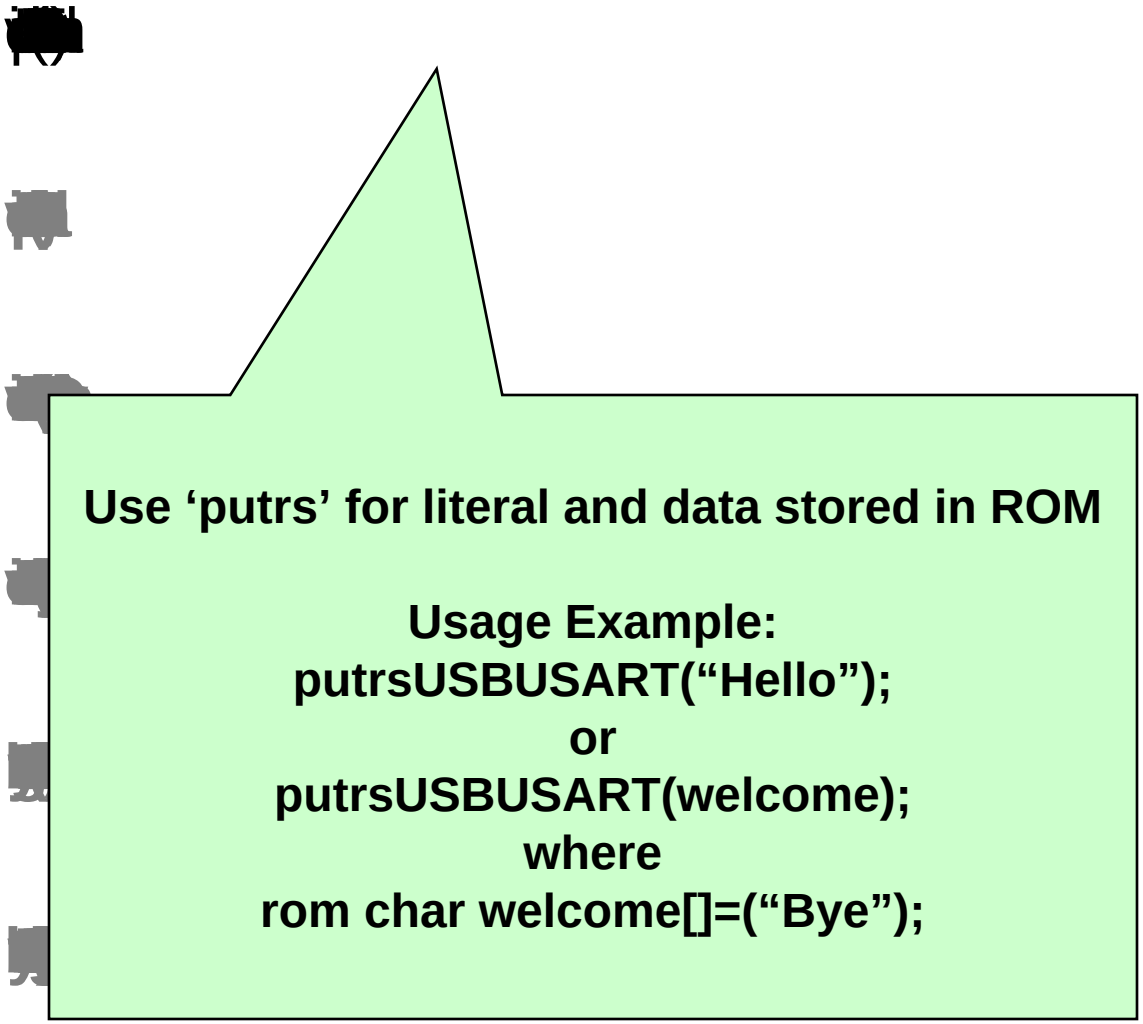
Determinants of API

Do you know the length of the data you want to send?

Is the data stored in ROM or RAM?

Is the string of data null-terminated (end in 0x00)?

API for Null-terminated Literal & ROM Data



Importance of Checking State

cdc_trf_state

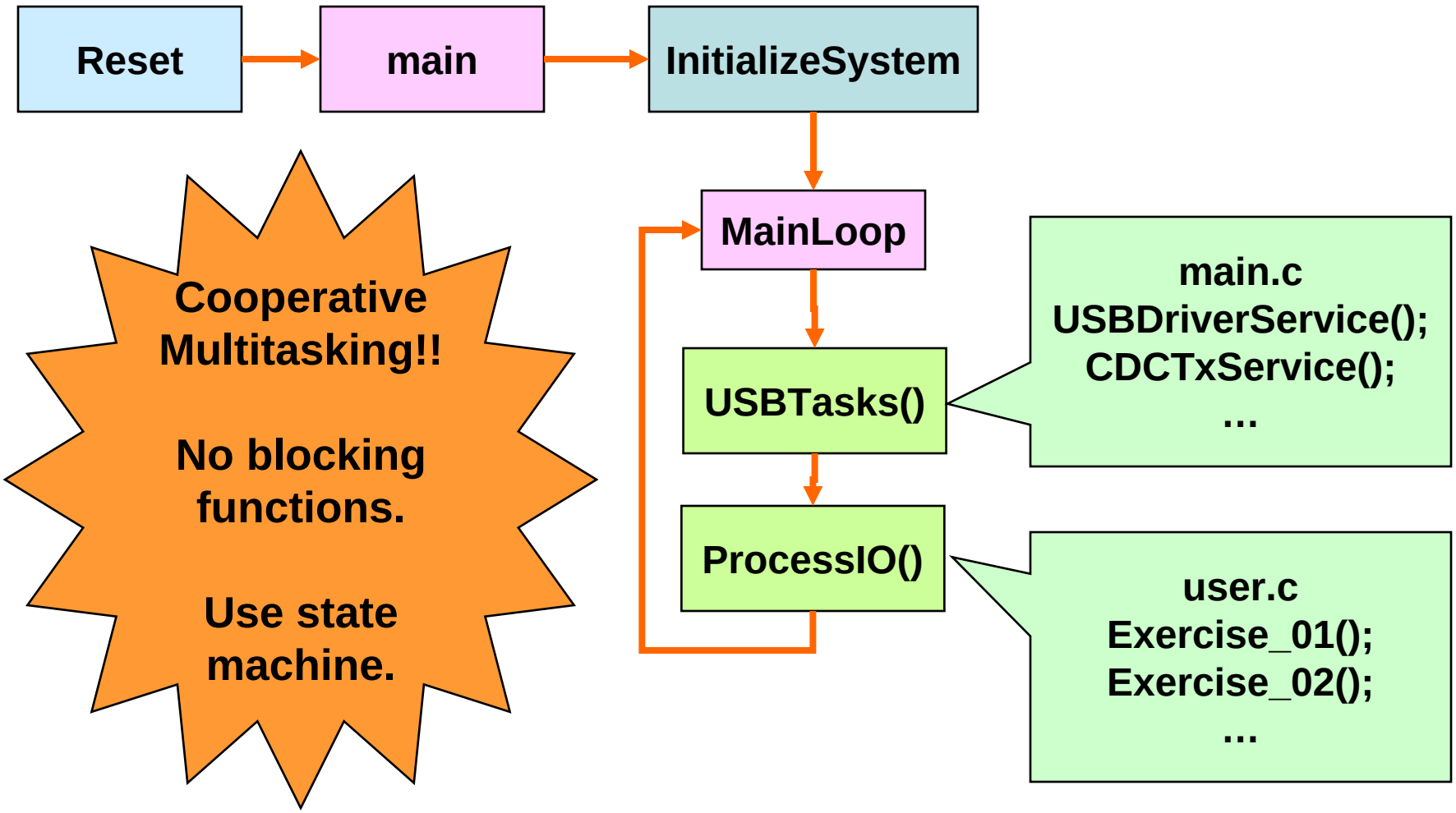
- **CDC_TX_READY**
- **CDC_TX_BUSY**
- **CDC_TX_BUSY_ZLP**
- **CDC_TX_COMPLETING**

When calling an API that sends data to the host, must check that:
cdc_trf_state == CDC_TX_READY

Or use macro:

-

Program Flow



Exercise 2.1: Sending Literal Data

Find function [redacted] in user.c

Write code in this function that sends a literal null-terminated string of text (“Hello World!\r\n”) to the PC when switch 2 is pressed

Take a look at examples in Exercise_Example();

Useful functions:

- [redacted]
  - **Returns 1 if switch 2 was pressed**
  - **Returns 0 if switch 2 was not pressed**
- [redacted]
- Use: [redacted].

End of Exercise 2.1

Exercise 2.2: Sending ROM Data

Find function [redacted] in user.c

Write code in this function that sends a null-terminated string of text stored in program memory pointed to by “ex02_string” to the PC when switch 3 is pressed

Useful functions:

- [redacted]
- [redacted]
- Use: [redacted].

End of Exercise 2.2

APIs for Receiving Data

len = expected number of input

buffer = pointer to user buffer of size equals to or larger than len

getsUSBUSART returns actual number of bytes copied to user buffer

Exercise 2.3: Receiving Data

Find function [illegible] in user.c

Write code in this function that reads data from USB bus and toggles LED D4 when the data read equals ASCII character ‘1’ (0x31)

Useful functions & variable:

- [illegible]
- [illegible]
- Use: [illegible].

End of Exercise 2.3

APIs for a String of Data with Known Length

Use mUSBUSARTTxRom for data stored in program memory

255-byte maximum

Use mUSBUSARTTxRam for data stored in data memory

Exercise 2.4: Sending Non Null-terminated Data

Before starting, comment out call to [illegible] first

Find function [illegible] in user.c

Write code in this function that sends the following 4 bytes of data:
0x30,0x31,0x32,0x33 when switch 2 is pressed

Useful function & variable:

- [illegible]
- [illegible]
- [illegible]
- Use: [illegible]

End of Exercise 2.4

API for Null-terminated RAM Data

Use ‘puts’ for data stored in RAM

Usage Example:
putsUSBUSART(output_buffer);
where
char output_buffer[]=(“Microchip”);

Exercise 2.5: Temperature Data

Find function in user.c

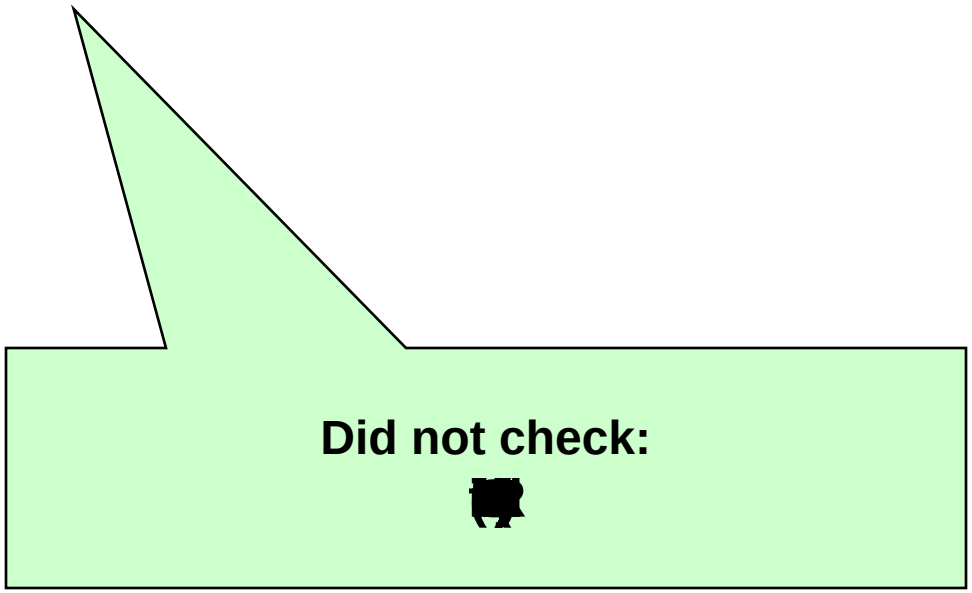
The program currently outputs temperature data on the physical UART port. Change the program to output data through the USB port.

Follow instructions in

End of Exercise 2.5

What is Wrong with This Code?

```
[redacted]
{
    [redacted]V
}
```



What is Wrong with This Code?

```
[redacted]
{
    [redacted]

    [redacted]V
}
```

Answer:
Blocking function!
Not good for cooperative multitasking.

CDCTxService() in USBTasks() will never get called, and cdc_trf_state will never be updated.

Program will just be stuck in a loop.

Remember, use a state machine!

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Post Exercise Analysis

Speed

- 640 Kbits/s = 80 Kbytes/s
- Faster than RS-232 (UART)
- This solution is not possible with a low-speed USB device because it does not have bulk endpoint

No hardware handshakes

Program Memory Usage: ~ 3 KB

Application Note

- AN956: Migrating Applications to USB from RS-232 UART with Minimal Impact on PC Software

10 minute Break

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Wrapping up and Q&A

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Exercise Group 3

Approximately 140 mins should have lapsed

Exercise Group 3 should take approximately 60 minutes

Please see handouts for instructions

Wrapping Up…

- Many choices of device classes
  - HID
  - CDC – RS-232 Emulation
  - General Purpose
  - MSD
  - Others…
- In the end, all you really wanted is to move data from one location to another

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Other Resources

Developers Discussion Forum

- **http://www.usb.org/phpbb/**
- **http://forum.microchip.com/tt.aspx?forumid=102**

Various application notes from:

- **www.microchip.com/usb**

USB Complete 3rd Edition
by Jan Axelson

Questions?

Thank you!

Addendum

Exercise 2.1: Solution

```
[redacted]
{
    [redacted]
    {
        [redacted]
        {
            [redacted]
        }
    }
}
```

Exercise 2.2: Solution

```
[redacted]
{
    [redacted]
    {
        [redacted]
        {
            [redacted]
        }
    }
}
```

Exercise 2.3: Solution

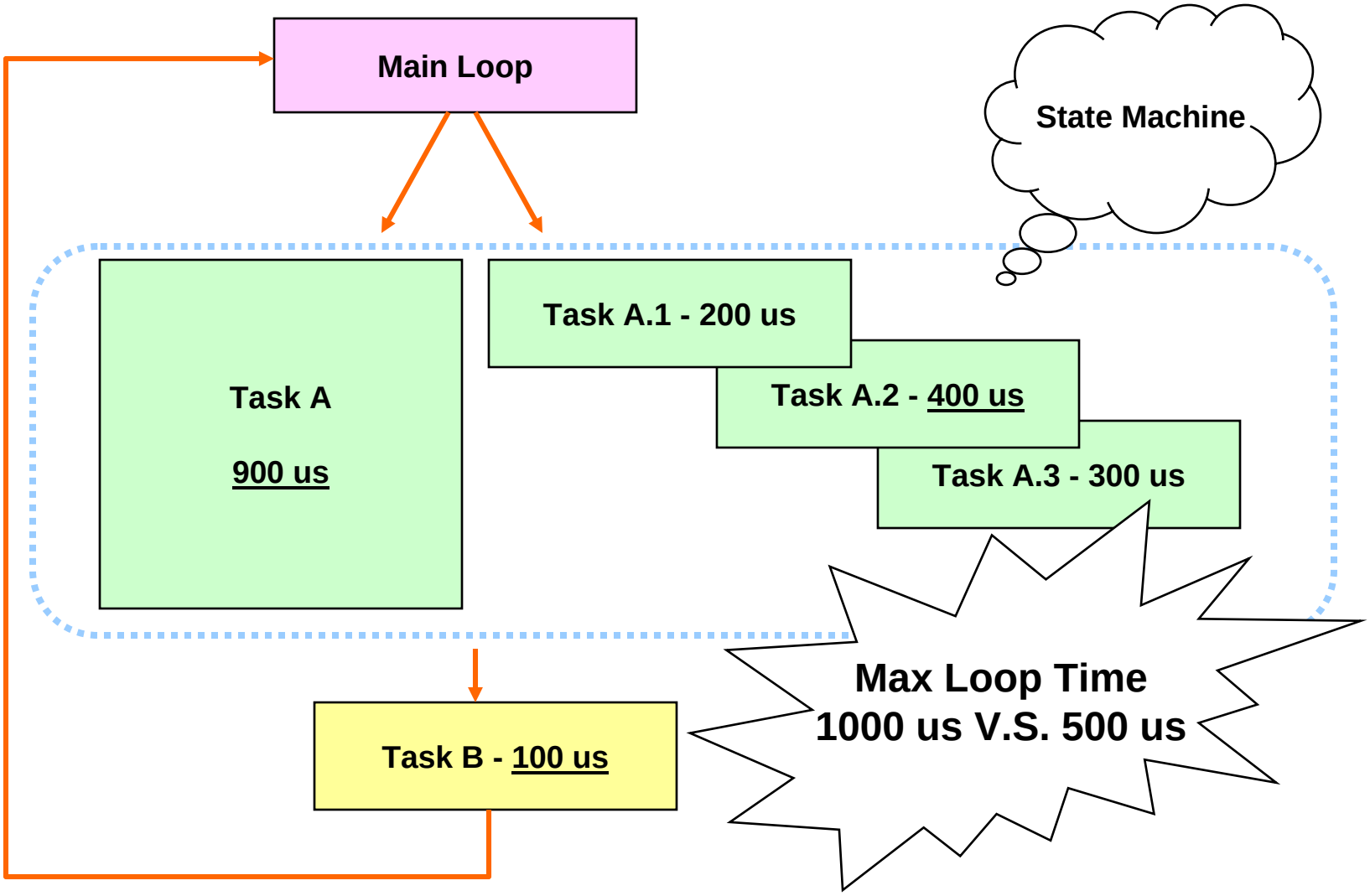
```
[redacted]
{
    [redacted]
    {
        [redacted]
                [redacted]
    }
}
```

Exercise 2.4: Solution

```
[redacted]
{
    [redacted]
    {
        [redacted]
        {
            [redacted]
            [redacted]
            [redacted]
            [redacted]
            [redacted]
        }
    }
}
```

Exercise 2.5: Solution

Cooperative Multitasking



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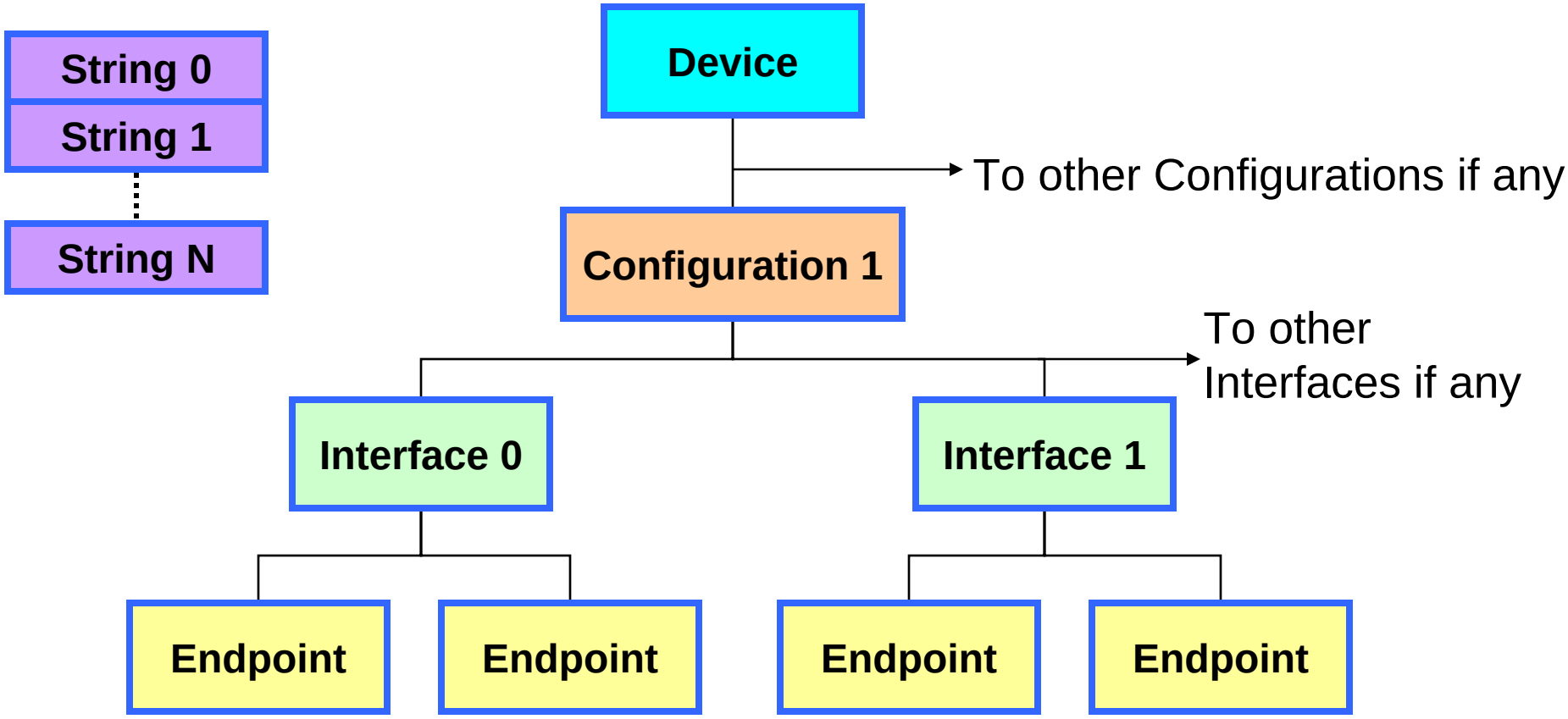
PIC18F4550 & PIC16C7X5 USB Features Summary

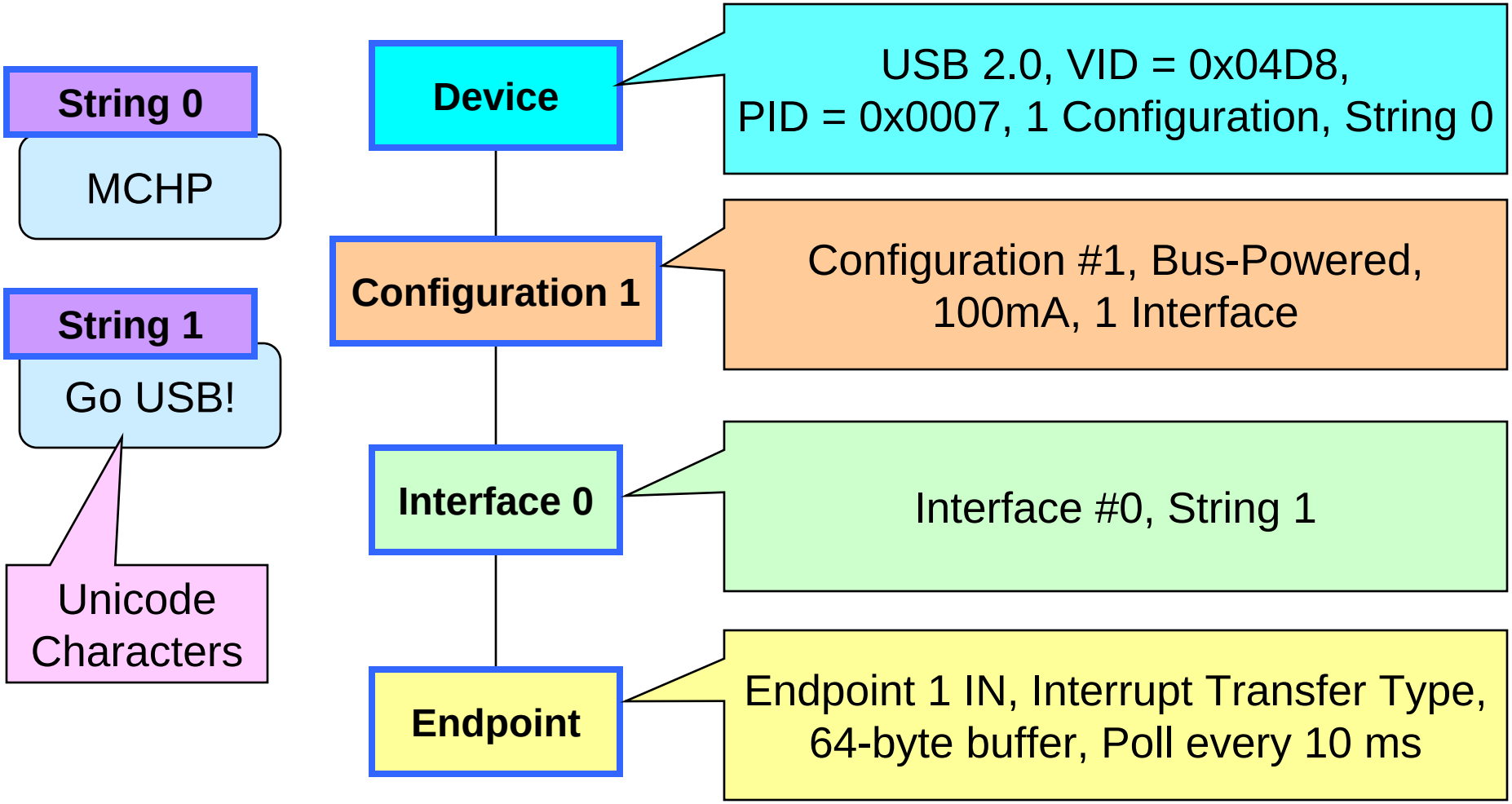
Features	*PIC18F4550*	*PIC16C7X5*
On-chip USB XCVR & Voltage Regulator	Yes	Yes
USB Dual-Port RAM	1-Kbyte	64-byte
USB Speed	Low & Full	Low
On-chip Pull-up Resistors	Yes	No
External XCVR Interface	Yes	No
Streaming Parallel Port	Yes	No
System Clock	Flexible	Fixed
Endpoints	32	6
Flash	Yes	No
USB Transfer Types	Control, Interrupt, Bulk, Isochronous	Control, Interrupt
Pins Compatible?	Yes	

Descriptors



Descriptors must be stored in a non-volatile memory.

Descriptors - Example



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