



### **Class Objective**

- When you finish this class you will:
  - Be familiar with dsPIC DSP features
  - Be familiar with using dsPIC DSP library and tools



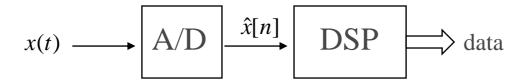
#### Agenda

- Why DSP
- dsPIC Support for DSP
  - dsPIC DSP architecture
  - dsPIC DSP Tools and Libraries





## **DSP Systems**



**Analysis (Receiver / Encoder)** 

data 
$$\longrightarrow$$
  $DSP$   $\xrightarrow{\hat{y}[n]}$   $D/A$   $\longrightarrow$   $y(t)$ 

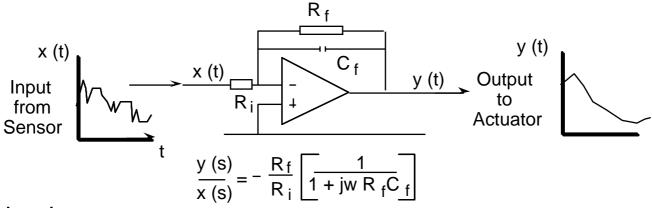
**Synthesis (Transmitter / Decoder)** 

$$x(t) \longrightarrow \boxed{A/D} \xrightarrow{\hat{x}[n]} \boxed{DSP} \xrightarrow{\hat{y}[n]} \boxed{D/A} \longrightarrow y(t)$$

**Signal Conditioning/Control** 



### **Analog Control Systems**

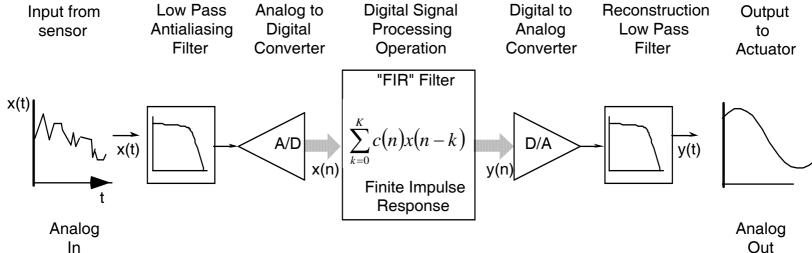


#### Drawbacks:

- Low noise immunity
- Little flexibility
- Requires adjustments
- Critical component specification, especially for high order filters
- Filter characteristics change with
  - Temperature
  - Component aging
  - Power supply variation



## **Digital Control Systems**



- Some key advantages of digital filtering:
  - Less affected by noise
  - Lower power consumption
  - Programmable systems
  - Minimal effect of drift in characteristics with age



#### FIR Filters: Definition

 The input-output relation of a FIR filter is given by

$$y[n] = \sum_{k=0}^{T-1} b_k x[n-k]$$

#### where:

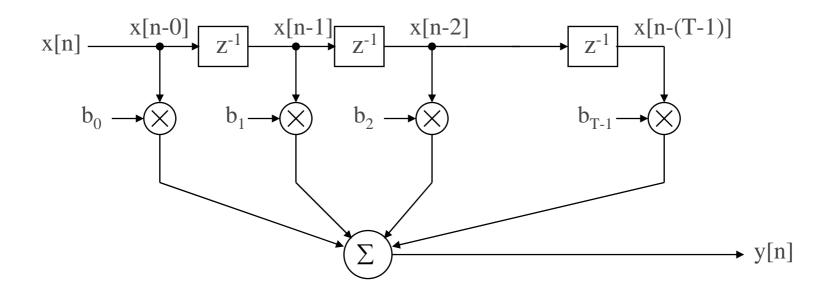
T = filter length (# of taps)

 $b_k$  = the  $k^{th}$  coefficient of the filter



#### FIR Filters: Structure

- FIR filter tapped delay line form
  - z<sup>-1</sup> refers to a unit sample delay







#### dsPIC support for Filters

- DSP Library Support
- Dual Harvard Architecture
- MAC instructions with data prefetch
- Modulo Addressing
- Loop control DO and REPEAT instructions



## C-callable fixed point FIR from MPLAB

**Description:** FIR applies an FIR filter to the sequence of source samples, places the

results in the sequence of destination samples, and updates the delay

values.

Include: dsp.h

Prototype: extern fractional\* FIR (

int numSamps,

fractional\* dstSamps,
fractional\* srcSamps,

FIRStruct\* filter

);

Arguments: numSamps number of input samples to filter (also N)

dstSamps pointer to destination samples (also y)

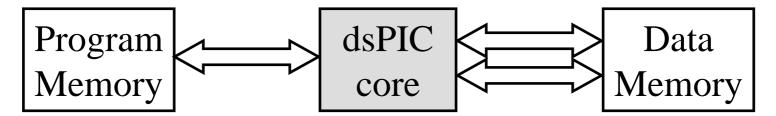
srcSamps pointer to source samples (also x)

filter pointer to FIRStruct filter structure

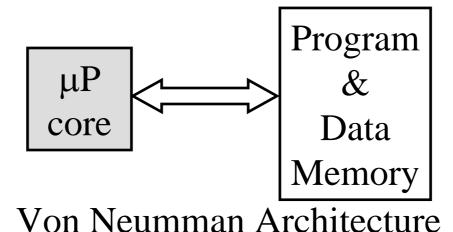
**Return Value:** Pointer to base address of destination samples.



## dsPIC vs. Microprocessor Architectures



**Dual Harvard Architecture** 





#### MAC and dual parallel reads

#### MAC

#### Multiply and Accumulate

Syntax: {label:} MAC Wm\*Wn, Acc {,[Wx], Wxd} {,[Wy], Wyd} {,AWB}

Operation:  $(Acc(A \text{ or } B)) + (Wm) * (Wn) \rightarrow Acc(A \text{ or } B)$ 

 $([Wx]) \rightarrow Wxd; (Wx) + kx \rightarrow Wx$   $([Wy]) \rightarrow Wyd; (Wy) + ky \rightarrow Wy$  $(Acc(B or A)) rounded \rightarrow AWB$ 

Description: Multiply the contents of two working registers, optionally prefetch

operands in preparation for another MAC type instruction and optionally store the unspecified accumulator results. The 32-bit result of the signed

multiply is sign-extended to 40 bits and added to the specified

accumulator.

Words:

Cycles: 1

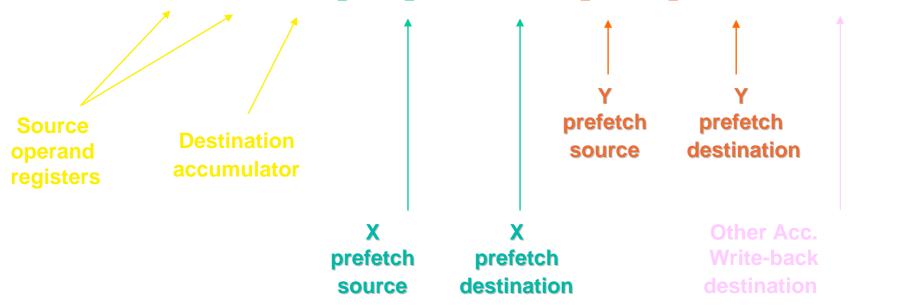
One clock cycle, One program word!

Example 1: MAC W4\*W5, A, [W8]+=6, W4, [W10]+=2, W5



### MAC and dual parallel reads

#### MAC W4\*W5, A, [W8]+=2, W4, [W10]-=6, W5, W13

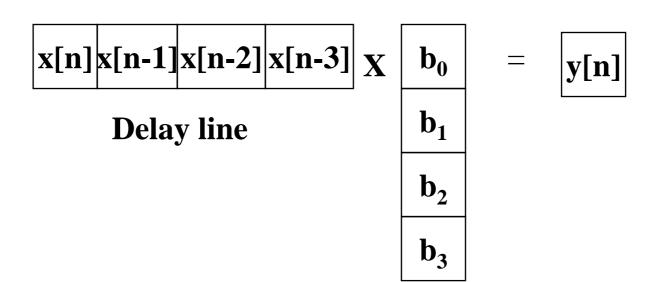




## Modulo or "Circular" Addressing

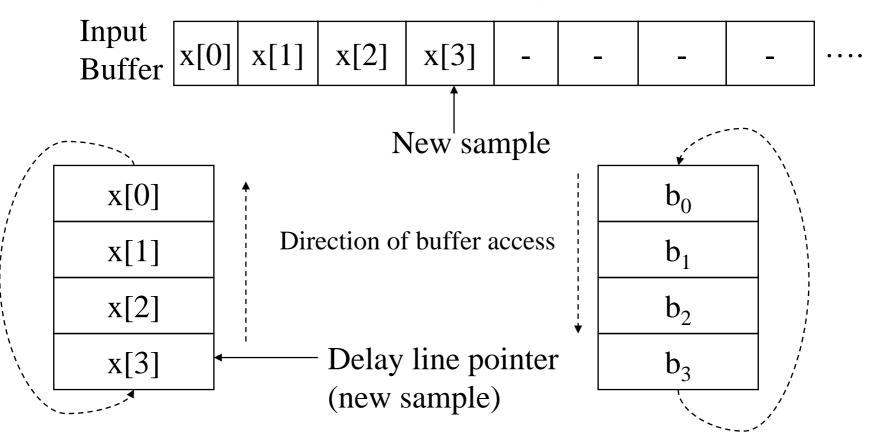
- Eliminates the software overhead associated with effective address (EA) correction
- Data address boundary checks are performed in hardware
- May be used with any instruction that utilizes indirect addressing

- Single Sample FIR Filter Operation (4 taps)
- Vector Dot Product of...
  - Input Delay Line
  - Coefficient Array





Buffer at n = 3 (before computation):



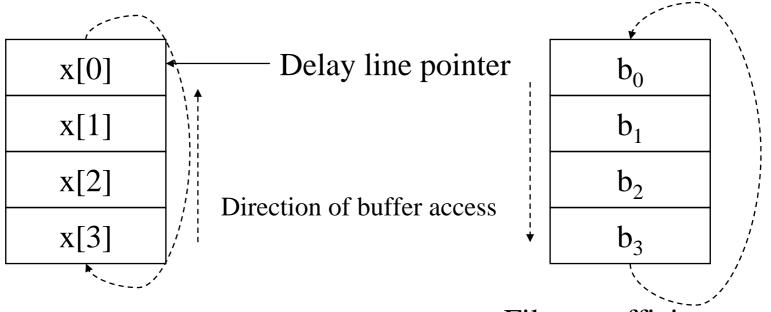
Delay line circular buffer

Filter coefficient array



FIR output for n = 3:

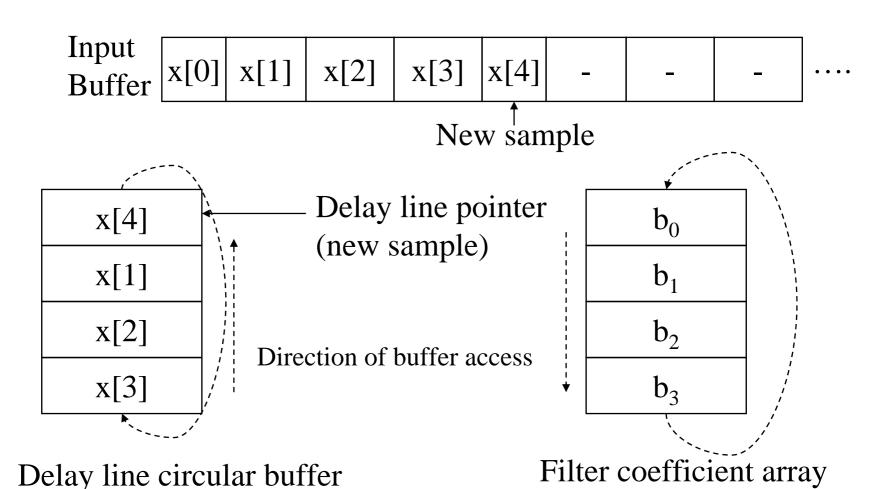
$$y[3] = x[3]*b_0+x[2]*b_1+x[1]*b_2+x[0]*b_3$$



Delay line circular buffer

Filter coefficient array

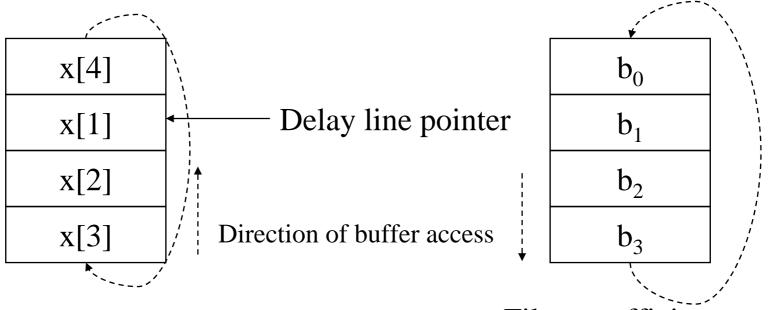






FIR output for n = 4: v[4] - v[4]\*b + v[3]\*b + v[2]\*b + v[1]

$$y[4] = x[4]*b_0+x[3]*b_1+x[2]*b_2+x[1]*b_3$$



Delay line circular buffer

Filter coefficient array



#### Zero Overhead Looping

- Two Instructions
  - REPEAT for single instruction loops
  - DO for multiple instruction loops
- Interruptable
- STATUS register indicates when looping is active



#### REPEAT Examples

REPEAT #200MOV [W0--], [W1]++

REPEAT W8CLR [W5]++

REPEAT #0x20ADD A, [W3++]



#### **Nested DO Example**

DO LOOP1, #0x100

MOV [W0], W1

**AND** #0x3FF, W1

DO LOOP2, #0x8

BTG W1, #0x9

LOOP2: IOR W1, [W2]++, [W3]++

LOOP1: MOV W1, [W0]++



# 4 Lines (dsPIC) vs. 31 Lines (16-bit MCU)

#### **16-bit MCU**

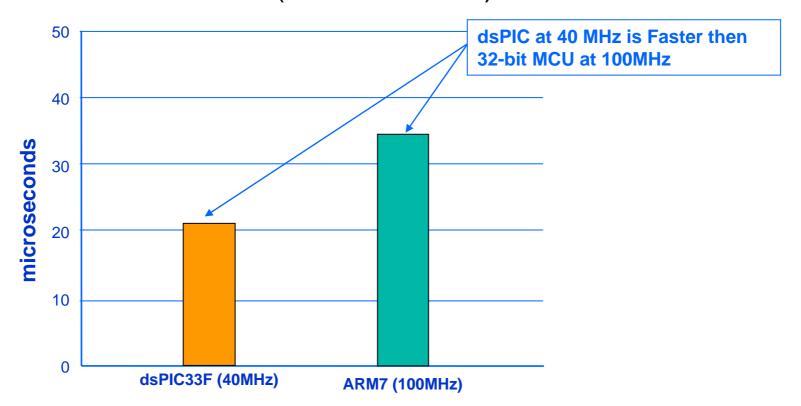
repeat w4
mac w5\*w6,a,[w8]+=2,w5,[w10]+=2,w6
mac w5\*w6,a,[w8]+=2,w5,[w10],w6
mac w5\*w6,a

```
do_again1:
       mov R6,[R5]
                       ;Get next x(n-l)
       mov R7,[R12+] ;Get next FIR filter coeff-a(i)
             R6,R7
                        ;Form product a(I)*x(n-I)
       mul
       impr cc NV,copyl
                                        ;Test for only 16 bit result
            R9,MDH ; Move high portion of MD
copy1:
       mov
             R6,MDL
                       :Move low portion of MD
             R11,R6
                       ;acc. Product terms in R10 and R11
       add
       addc R10.R9
             R5,#2
                       :Point to a next item in x(n-1)
       sub
             R5,R13
                       ;Chk if ptr falls out of circ buffer table
       cmp
             cc NN.leap1
                                        ;If still in table keep going otherwise
       ami
                                        ;adj. Ptr. To top of table
             R4,R2
       mov
              R4,#1
       shl
       add
              R5,R4
                       ;adj. Ptr to top of table
leap1:
             R1.#1h
                       ;Determine if all taps computed
       add
             R1,R2
       cmp
             cc NZ,do again1
       imp
             R4,#curr_ptr
       mov
       mov
             R5,[R4]
             R5,#2h
                        ;Inc. ptr. Into circ. Buffer
       add
             R3.R2
       mov
       shl
                       R3,#1
                       R3,#2
       sub
                       R6,R13
       mov
                       R6,R3
       add
       cmp
                       R5,R6
                                        :Does curr ptr exceed top of table?
       jmpr
                       cc_NZ,leap3
                       R5,R13
                                        ;Back to beginning of table
       mov
 leap3:
                       R10.#0h
       cmp
                       cc_Z,leap2
       jmpr
```



#### **DSP Benchmark**

- BDTI's Real Block FIR Filter Benchmark
  - Execution time (lower is better)





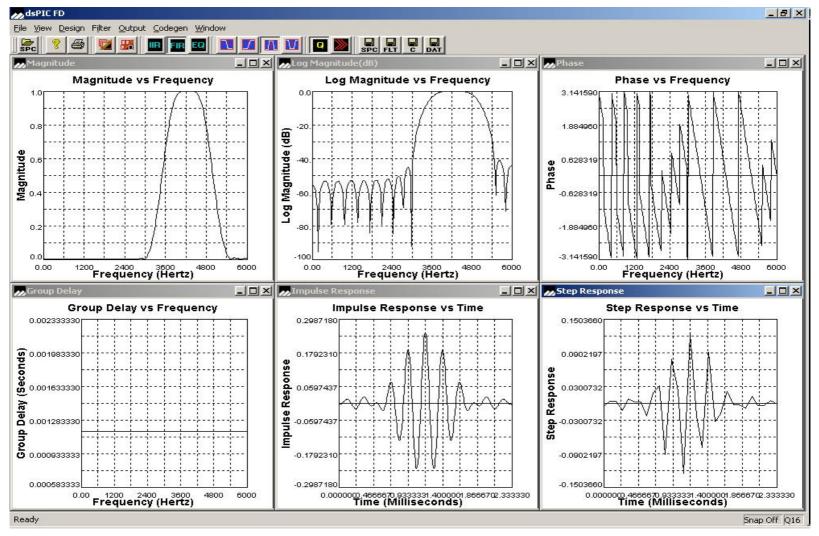


## dsPIC® Digital Filter Design

- Graphically design all types of digital filters
  - Low-pass, high-pass
  - Band-pass, band-stop
- Digital filter algorithm kernels are provided for:
  - FIR—Finite Impulse Response
  - IIR—Infinite Impulse Response
- Designing coefficients to control the filter response is the tricky part
  - You can do the math or use this tool!!
- Quickly observe filters response
- Generated code and coefficients fully compatible with MPLAB® C30 C Compiler language tools



# dsPIC® Digital Filter Design



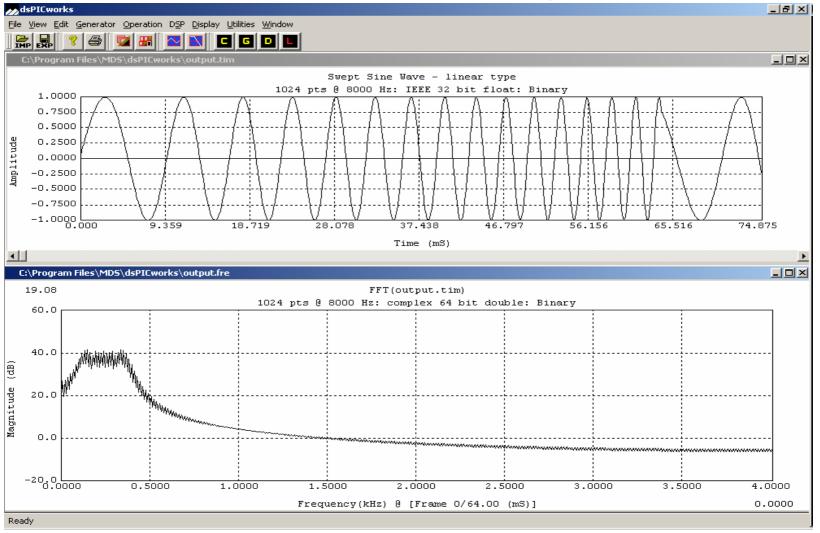


#### dsPICWorks<sup>™</sup> Data Analysis and DSP Software

- Graphical signal analysis and generation tool
  - Create waveforms and process them
  - Signal generation
    - SIN, square, swept SIN, triangular, etc...
  - Signal operations
    - Add, Flip and Shift, Multiply, etc...
  - DSP operations
    - Filtering, correlation, FFT, LPC analysis, etc...
- Designed especially for the dsPIC30F
  - Import/export data with MPLAB® compatible files
  - Processes filter files saved from dsPIC<sup>®</sup> Digital Filter Design



## dsPICWorks<sup>™</sup> Data Analysis







### Lab 1 – Using DSP

- Goals
  - Learn DSP tools and Libraries
- Lab
  - Implement signal filtering using FIR fitler





#### **Math Library**

- Supports all of <MATH.H> from ANSI "C"
  - Trigonometric Functions
  - Exponent and Log Functions
  - Power, Square Root, Floor(不大于的最大整数), Ceiling(不小于的最小整数), etc.
- IEEE-754 Compliant
- Optimized for code size, developed in Assembly
- Supports 2 data types
  - 32-bit floating point
  - 64-bit double
- Benefits any application which uses floats/doubles
- C and assembly callable



#### **DSP Library**

- Libraries for your DSP requirements
- Collection of 49 of the most common DSP functions
  - Vector and Matrix Functions
    - Add, Subtract, Multiply, Max, Min
    - Convolution, Correlation, Power, etc...
  - Filter Functions—block and single sample processing
    - FIR, IIR, Adaptive LMS(自适应LMS算法), Lattice(格型算法) and more
  - Transform Functions
    - FFT, Inverse FFT, Discrete Cosine Transform(离散余弦变换)
  - Window Functions
    - Bartlett, Blackman, Hamming, Hanning, Kaiser
- Most functions are hand coded in assembly language
  - Fast execution time, C and assembly callable



## **Embedded Modem Library**

## Software Modem (soft-modem) Support

Replacing external modem chip with software!

#### Benefits

- Single-chip integrated solution (up to 14.4 kbps)
- Quick dialup and connection times
  - Perfect for small transactions on analog phone line

## Application Examples

- Home automation, remote access, security systems
- POS applications, web-enabled devices
- Tele-metering, remote upgrades
- Library supplied with full DTMF Generation/Detection modules



# Soft-Modem Resource Summary

dsPIC30F implementation leaves room for other tasks...

ITU-T Specification	Bit Rate (bps)	RAM (Bytes)	Program Memory (Kbytes)	MIPS
V.32bis	14400	3600	36	15
V.32	9600	3200	31	12
V.22bis	2400	1700	22	7
V.23	600/1200	1000	15	4.5
V.21	300	1000	13	4.5
V.42 (Error Corr.)	na	2000	14	1.5



**Includes DTMF Library** 



## **Speech Coding Library**

- Performs speech compression / decompression
- Encoder 16:1 compression ratio
  - Speech input: 8 KHz, 16-bit mono
  - Encoded output: 8kbps data stream

#### Decoder

- Decoder input: 8 kbps data stream
- Speech output: 8 KHz, 16-bit mono

#### Based on Speex

- Open source technology
- Numerous PC plug-ins / apps readily available
- www.speex.org
- Includes PC Utility for making "playback" files



# Speech Coding Library How may it be used?

- By any application with voice communication
- Benefits
  - Reduces communication bandwidth
  - Reduces storage requirements
- Sample Applications
  - Digital radios / walkie-talkies
  - Answering machines / voice recorders
  - Playback-only systems
    - Security Systems (building evacuation)
    - Museum Guides
    - Application Voice Prompts



## Speech Coding Library Resource Requirements

Small Decoder footprint / Encoder is RAM intensive

	Encoder	Decoder	
MIPs	19	3	
RAM	5.4 KB	3.2 KB	
Flash	33 KB	15 KB	

- 2 analog interfaces supported
  - Silicon Labs Si-3000 Codec
  - Alternate interface for cost-sensitive applications
    - ADC for microphone input
    - Output compare for speaker output
    - Sample circuits provided in User's Guide



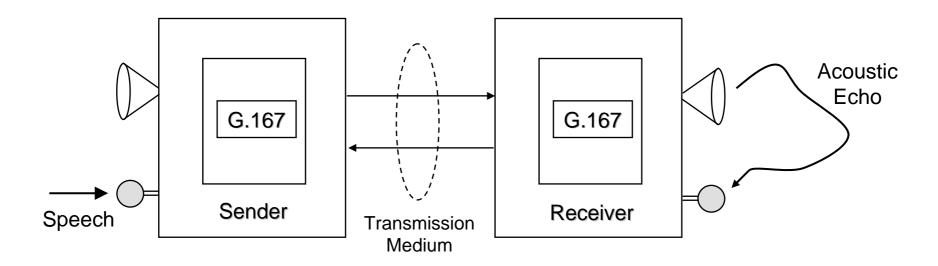
# Acoustic Echo Cancellation Library

#### Provides 'far-end' echo cancellation

 Speaker output is picked up by the local microphone and transmitted back to the sender

#### Features

- G.167-compliant algorithm (up to 64 msec)
- Supports full-duplex operation





# Acoustic Echo Cancellation Library

#### G.167 CPU Resources

Echo Delay	RAM (KB)	Program Memory (KB)	MIPS
16 msec	4.6*	6	7.5
32 msec	5.4*	6	10.5
64 msec	7.7*	6	16.5

<sup>\*</sup> Includes up to 2KB for CODEC and UART buffers and A/U-law compression

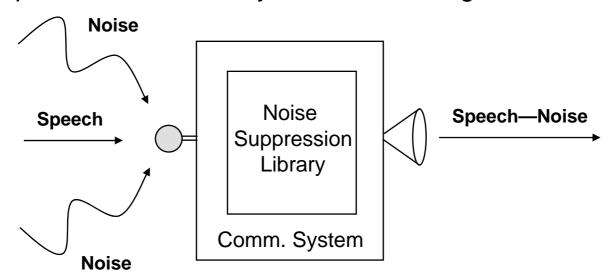
## Target Applications

- Speakerphone
- Hands-free car phone
- Intercom
- Emergency alarm units



## **Noise Suppression Library**

- Removes extraneous noise picked up by microphone
  - Voice activity detector differentiates noise and speech
  - Noise reduction filters adjust every 10 ms during periods of speech inactivity (uses FFT analysis)
  - Speech is continuously filtered, reducing noise





# **Noise Suppression Library**

### Noise Suppression CPU Resources

- 3.3 MIPS
- 5 Kbytes Flash memory
- 2 Kbytes RAM
  - Includes up to 1 Kbyte for buffering Codec data

## Target Applications

- Front end for any voice based system
  - Headsets
  - Hands-free telephone
  - Intercom
  - Speech recognition
  - Speech coding



# **Embedded Encryption Libraries**

## dsPIC30F Symmetric Key Library

- Message Digests: SHA-1, MD5
- Symmetric Key Encryption: T-DES, AES
- Deterministic Random Bit Generator: ANSI X9.82

## dsPIC30F Asymmetric Key Library

- Signing and Verification: RSA, DSA
- Public Key Encryption: RSA
- Key Agreement Protocol: Diffie-Hellman
- Big Integer Arithmetic Package



# **Embedded Encryption Applications**

- Secure Web Transactions
  - Secure web access (SSL/TLS)
  - E-mail (S/MIME), secure XML transactions, and Virtual Private Networks (IPsec)
- Smart Card Readers
- PDAs and other mobile devices
- Secure communications between a dsPIC<sup>®</sup> DSC application and personal computers
  - Trusted Computing Group (TCG)
  - Microsoft® Next Generation Secure Computing Base (NGSCB)



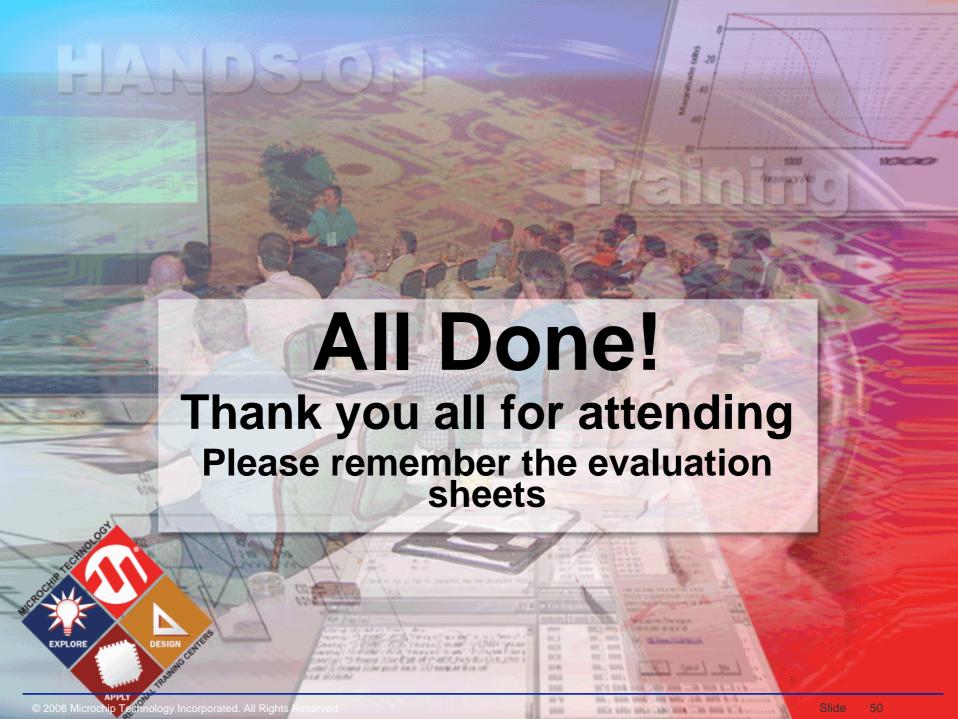
## Summary

- We learned advantages of dsPIC DSP architecture
- We learned DSP tools and libraries available for dsPIC



## References

- dsPIC30 & dsPIC33 Datasheet
- dsPICDEM1.1 User's Guide
- MPLAB® IDE
- C30 Compiler
- ICD2 In Circuit Debugger





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